

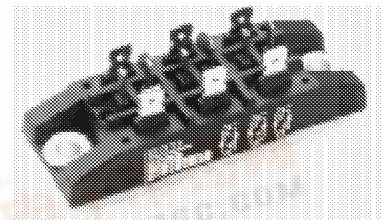
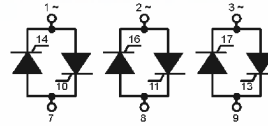
Three Phase AC Controller Modules

$$I_{RMS} = 3 \times 39 \text{ A}$$

$$V_{RRM} = 800 - 1600 \text{ V}$$

Preliminary data

V_{RSM}	V_{RRM}	Type
V_{DSM}	V_{DRM}	
V	V	
800	800	VWO 36-08io7
1200	1200	VWO 36-12io7
1400	1400	VWO 36-14io7
1600	1600	VWO 36-16io7



Symbol	Test Conditions	Maximum Ratings	Features
I_{RMS}	$T_K = 85^\circ\text{C}$, 50 - 400 Hz (per phase)	39 A	- Thyristor controller for AC (circuit W3C acc. to IEC) for mains frequency - Package with metal base plate - Isolation voltage 3000 V~ - Planar passivated chips - UL applied 1/4" fast-on power terminals
I_{TRMS}	$T_{VJ} = T_{VJM}$	28 A	
I_{TAVM}	$T_K = 85^\circ\text{C}$; (180° sine)	18 A	
I_{TSM}	$T_{VJ} = 45^\circ\text{C}$; $V_R = 0$	$t = 10 \text{ ms}$ (50 Hz), sine $t = 8.3 \text{ ms}$ (60 Hz), sine	
		320 A 350 A	
	$T_{VJ} = T_{VJM}$; $V_R = 0$	$t = 10 \text{ ms}$ (50 Hz), sine $t = 8.3 \text{ ms}$ (60 Hz), sine	
		280 A 310 A	
I^2t	$T_{VJ} = 45^\circ\text{C}$; $V_R = 0$	$t = 10 \text{ ms}$ (50 Hz), sine $t = 8.3 \text{ ms}$ (60 Hz), sine	Applications - Switching and control of three phase AC circuits - Softstart AC motor controller - Solid state switches - Light and temperature control
		500 A ² s 520 A ² s	
	$T_{VJ} = T_{VJM}$; $V_R = 0$	$t = 10 \text{ ms}$ (50 Hz), sine $t = 8.3 \text{ ms}$ (60 Hz), sine	
		390 A ² s 400 A ² s	
	$T_{VJ} = T_{VJM}$; $f = 50 \text{ Hz}$, $t_p = 200 \mu\text{s}$ $V_D = 2/3 V_{DRM}$ $I_G = 0.3 \text{ A}$ $di_G/dt = 0.3 \text{ A}/\mu\text{s}$	repetitive, $I_T = 20 \text{ A}$ non repetitive, $I_T = I_{TAVM}$	
		150 A/ μs 500 A/ μs	
$(dv/dt)_{cr}$	$T_{VJ} = T_{VJM}$; $R_{GK} = \infty$; method 1 (linear voltage rise)	$V_{DR} = 2/3 V_{DRM}$	Advantages - Easy to mount with two screws - Space and weight savings - Improved temperature and power cycling capability - High power density - Light weight and compact
		1000 V/ μs	
P_{GM}	$T_{VJ} = T_{VJM}$; $I_T = I_{TAVM}$	$t_p = 30 \mu\text{s}$ $t_p = 300 \mu\text{s}$	
		10 W 5 W	
P_{GAVM}		0.5 W	
V_{RGM}		10 V	
T_{VJ}		-40...+125 °C	
T_{VJM}		125 °C	
T_{stg}		-40...+125 °C	
V_{ISOL}	50/60 Hz, RMS	$t = 1 \text{ min}$	
	$I_{ISOL} \leq 1 \text{ mA}$	$t = 1 \text{ s}$	
		2500 V~ 3000 V~	
M_d	Mounting torque (M5)	$5 \pm 15 \%$	Nm
	(10-32 UNF)	$44 \pm 15 \%$	
		110 g	lb.in.
Weight	typ.		

Symbol	Test Conditions	Characteristic Values
I_D, I_R	$T_{VJ} = T_{VJM}; V_R = V_{RRM}; V_D = V_{DRM}$	≤ 5 mA
V_T	$I_T = 45$ A; $T_{VJ} = 25^\circ\text{C}$	≤ 1.45 V
V_{T0}	For power-loss calculations only ($T_{VJ} = 125^\circ\text{C}$)	0.85 V
r_T		13 m Ω
V_{GT}	$V_D = 6$ V; $T_{VJ} = 25^\circ\text{C}$	≤ 1.0 V
	$T_{VJ} = -40^\circ\text{C}$	≤ 1.2 V
I_{GT}	$V_D = 6$ V; $T_{VJ} = 25^\circ\text{C}$	≤ 65 mA
	$T_{VJ} = -40^\circ\text{C}$	≤ 80 mA
V_{GD}	$T_{VJ} = T_{VJM}; V_D = 2/3 V_{DRM}$	≤ 0.2 V
I_{GD}		≤ 5 mA
I_L	$T_{VJ} = 25^\circ\text{C}; t_p = 10$ μs $I_G = 0.3$ A; $di_G/dt = 0.3$ A/ μs	≤ 150 mA
I_H	$T_{VJ} = 25^\circ\text{C}; V_D = 6$ V; $R_{GK} = \infty$	≤ 100 mA
t_{gd}	$T_{VJ} = 25^\circ\text{C}; V_D = 1/2 V_{DRM}$ $I_G = 0.3$ A; $di_G/dt = 0.3$ A/ μs	≤ 2 μs
t_q	$T_{VJ} = T_{VJM}; I_T = 20$ A, $t_p = 200$ μs ; $di/dt = -10$ A/ μs $V_R = 100$ V; $dv/dt = 15$ V/ μs ; $V_D = 2/3 V_{DRM}$	typ. 150 μs
R_{thJC}	per thyristor; sine 180°el	1.3 K/W
	per module	0.216 K/W
R_{thJK}	per thyristor; sine 180°el	1.5 K/W
	per module	0.25 K/W
d_s	Creeping distance on surface	16.1 mm
d_A	Creepage distance in air	6.0 mm
a	Max. allowable acceleration	50 m/s ²

Dimensions in mm (1 mm = 0.0394")

