

UTC 1470 LINEAR INTEGRATED CIRCUIT

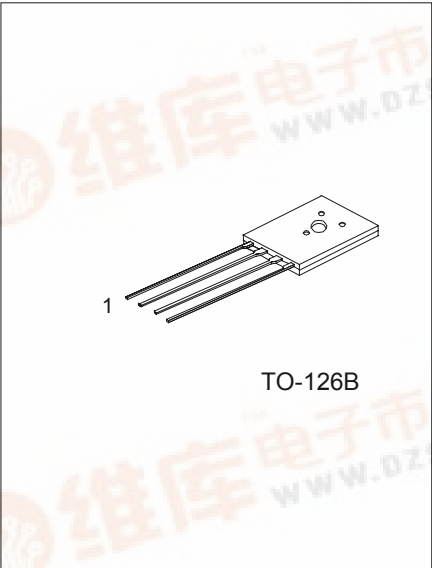
MOTOR SPEED REGULATORS

DESCRIPTION

The UTC 1470 is a monolithic integrated circuit intended as speed regulators for DC motors of record players, tape and cassette recorders etc .

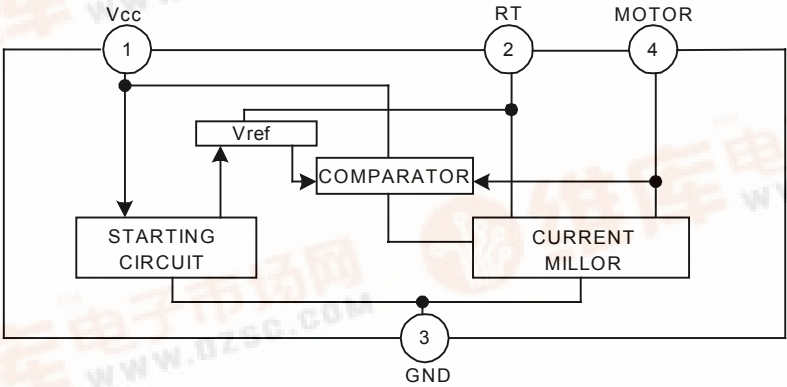
FEATURES

- *Excellent Versatility in use.
- *High Output current.
- *Low Quiescent current.
- *Low Reference voltage.
- *Excellent parameters stability versus temperature.
- *Excellent characteristic at low supply voltage.



1: Vcc 2: RT 3: GND 4: MOTOR

BLOCK DIAGRAM



ABSOLUTE MAXIMUM RATINGS (Ta=25°C)

PARAMETER	SYMBOL	RATING	UNIT
Supply Voltage	Vcc	18	V
Circuit Current	I ₄	2*	A
Package Dissipation	PD	1.2	W
Operating Temperature	Topt	-20 ~ +75	°C
Storage Temperature	TSTG	-40 ~ +150	°C
		*t≤5s	



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RECOMMENDED OPERATING CONDITION

PARAMETER	SYMBOL	PATING	UNIT
Supply Voltage Range	Vcc	3.5 ~ 16	V

ELECTRICAL CHARACTERISTICS (Ta=25°C, Vcc=12V)

CHARACTERISTIC	SYMBOL	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Reference Voltage	Vref	I ₄ =10mA (Fig.1)	1.10	1.27	1.40	V
Quiescent Current	I _d	R _M =180Ω (Fig.4)	0.5	0.8	1.2	mA
Reflection Coefficient	k	R _{M1} =44Ω, R _{M2} =33Ω (Fig.2)	18	20	22	
Saturation Voltage	V ₄ (sat)	V _{cc} =4.2V, R _M =4.4Ω (Fig.3)		1.5	2.0	V
	$\frac{\Delta k}{k} / \Delta V_{cc}$	I ₄ =100mA, V _{cc} =6.3~16V (Fig.2)		0.4		%/V
Line Regulation	$\frac{\Delta V_{ref}}{V_{ref}} / \Delta V_{cc}$	I ₄ =100mA, V _{cc} =6.3~16V (Fig.1)		0.06		%/V
	$\frac{\Delta k}{k} / \Delta I_M$	I ₄ =30~200mA (Fig.2)		-0.02		%/mA
Load Regulation	$\frac{\Delta V_{ref}}{V_{ref}} / \Delta I_M$	I ₄ =30~200mA (Fig.1)		-0.02		%/mA
	$\frac{\Delta k}{k} / \Delta T_a$	I ₄ =100mA, T _a =-20~+75°C (Fig.2)		0.01		%/°C
Temperature Coefficient	$\frac{\Delta V_{ref}}{V_{ref}} / \Delta T_a$	I ₄ =100mA, T _a =-20~+75°C (Fig.1)		0.01		%/°C

*Pulse Test::PW≤10ms,Duty cycle≤2%

TEST CIRCUIT

Fig.1

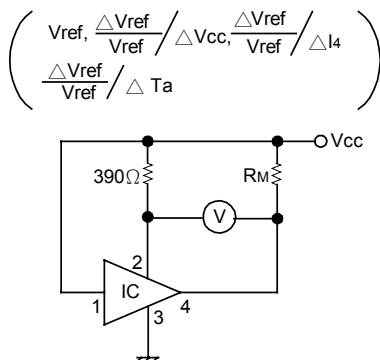
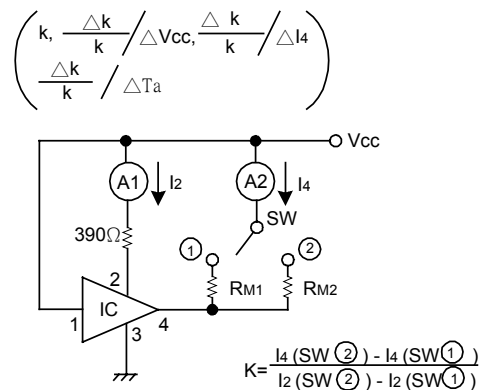


Fig.2



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Fig.3 (V_{4(sat)})

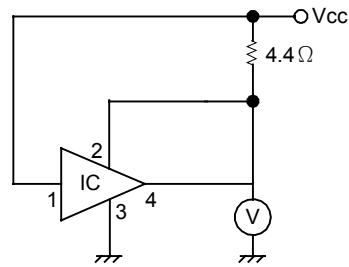
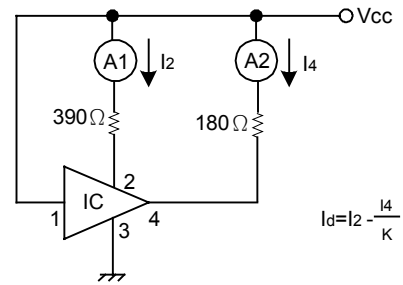
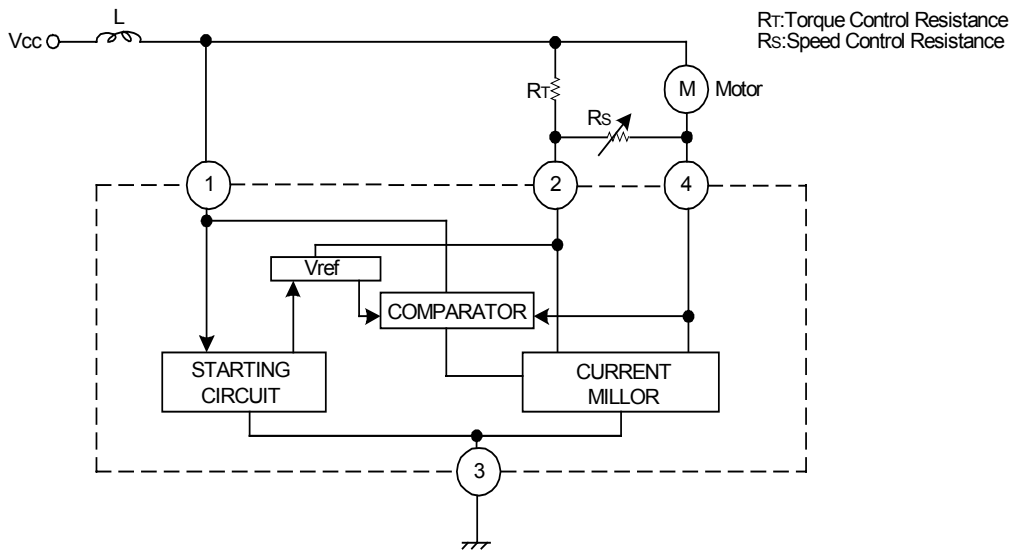


Fig.4 (I_d)



APPLICATION INFORMATION



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BASIC EQUATION FOR MOTOR

$$\begin{cases} E_t = V_{ref} + R_T (i_2 + \frac{V_{ref}}{R_s}) \\ i_2 = \frac{1}{K} i_4 + i_q \\ i_4 = i_m + \frac{V_{ref}}{R_s} \end{cases}$$

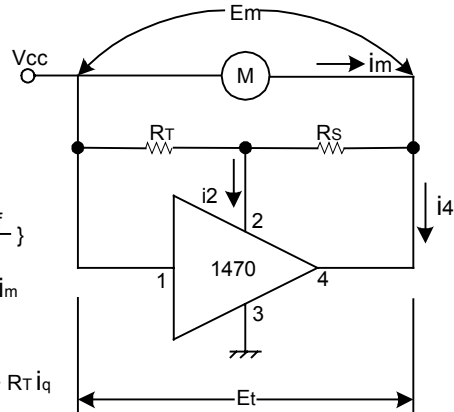
$$E_t = V_{ref} + R_T (\frac{1}{K} i_4 + i_q + \frac{V_{ref}}{R_s})$$

$$E_t = V_{ref} + R_T \{ \frac{1}{K} (i_m + \frac{V_{ref}}{R_s}) + i_q + \frac{V_{ref}}{R_s} \}$$

$$E_t = V_{ref} \{ 1 + \frac{R_T}{R_s} (1 + \frac{1}{K}) \} + R_T i_q + \frac{R_T}{K} i_m$$

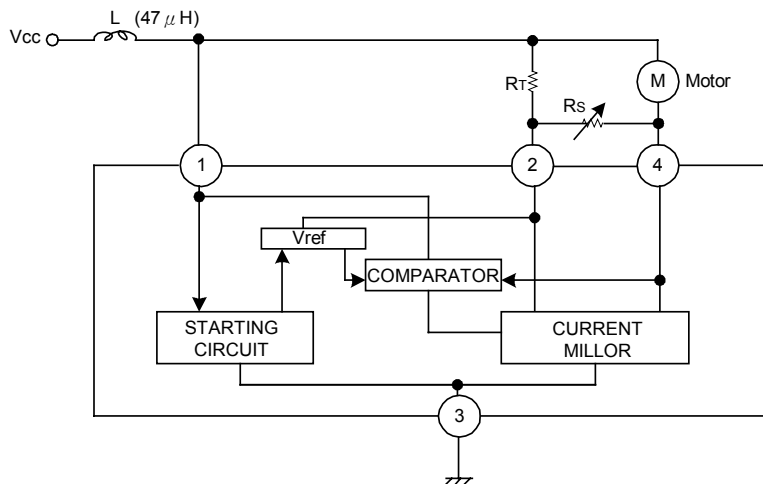
They also give : $E_m = E_o + R_m i_m$

$$\begin{cases} E_o = V_{ref} \{ 1 + \frac{R_T}{R_s} (1 + \frac{1}{K}) \} + R_T i_q \\ R_m = \frac{R_T}{K} \end{cases}$$



E_o : Back Electromotive Force
 R_m : internal Resistance(of the Motor)
 K : Reflection Coefficient = (i_4 / i_2)

APPLICATION CIRCUIT



$V_{cc} = 12V$
 $R_m = 19.5\Omega$
 $R_T = 330\Omega$
 $R_s = 1k\Omega$
 $E_o = 2.3V$
 $K = 20$

Note 1. The motor speed can be adjusted by the variable resistor R_s .

$$R_{smin} = \frac{V_{ref} \cdot R_T}{E_o - V_{ref} - i_q \cdot R_T}$$

Note 2. If $R_{Tmax} > K \cdot R_{min}$, instability of the motor may occur.

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