

Device Features

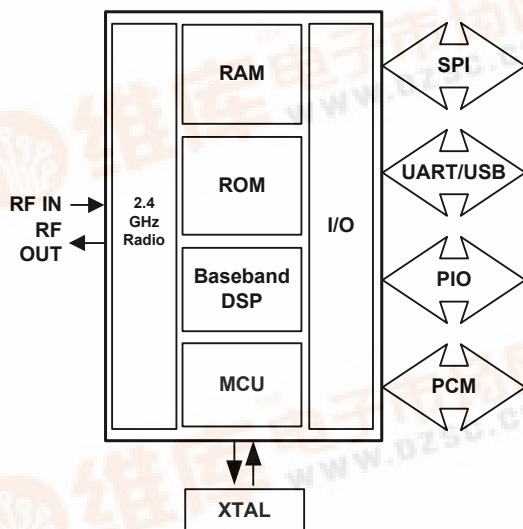
- Fully Qualified Bluetooth v2.0+EDR system
- Full Speed Bluetooth Operation with Full Piconet Support
- Scatternet Support
- Low Power 1.8V operation
- 10 x 10mm 96-ball LFBGA Package
- Minimum External Components
- Integrated 1.8V Regulator
- Dual UART Ports
- RF Plug-n-Go Package
- 50Ω Matched Connection to Antenna
- RoHS Compliant

General Description

The **BlueCore™4-ROM Plug-n-Go™** is a single chip radio and baseband IC for Bluetooth 2.4GHz systems. It is implemented in 0.18μm CMOS technology.

BC41B143A contains 4Mbit of internal ROM memory. When used with CSR Bluetooth stack, it provides a fully compliant Bluetooth system to v2.0 + EDR of the specification for data and voice.

BlueCore4-ROM Plug-n-Go has the same pinout and electrical characteristics as available in BlueCore4-Flash Plug-n-Go to enable development of custom code before committing to ROM. It also has the same pinout as BlueCore2-ROM Plug-n-Go and BlueCore2-Flash Plug-n-Go to keep compatibility.



System Architecture

BlueCore™4-ROM Plug-n-Go™

Single Chip Bluetooth® v2.0 + EDR System

Advance Information Data Sheet For
BC41B143A
July 2005

Applications

- Automotive
- Mice
- Keyboards

BlueCore4-ROM Plug-n-Go has been designed to reduce the number of external components required which ensures production costs are minimised. The 0.8mm pitch BlueCore4-ROM Plug-n-Go can be used on either two or four layer PCB construction.

The device incorporates auto-calibration and built in self test (BIST) routines to simplify development, type approval and production test. All hardware and device firmware is fully compliant with the Bluetooth v2.0 + EDR specification.

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1 Status Information

The status of this Data Sheet is **Advance Information**.

CSR Product Data Sheets progress according to the following format:

Advance Information

Information for designers concerning CSR product in development. All values specified are the target values of the design. Minimum and maximum values specified are only given as guidance to the final specification limits and must not be considered as the final values.

All detailed specifications including pinouts and electrical specifications may be changed by CSR without notice.

Pre-Production Information

Pinout and mechanical dimension specifications finalised. All values specified are the target values of the design. Minimum and maximum values specified are only given as guidance to the final specification limits and must not be considered as the final values.

All electrical specifications may be changed by CSR without notice.

Production Information

Final Data Sheet including the guaranteed minimum and maximum limits for the electrical specifications.

Production Data Sheets supersede all previous document versions.

Life Support Policy and Use in Safety-Critical Applications

CSR's products are not authorised for use in life-support or safety-critical applications. Use in such applications is done at the sole discretion of the customer. CSR will not warrant the use of its devices in such applications.

RoHS Compliance

BlueCore4-ROM Plug-n-Go devices meet the requirements of Directive 2002/95/EC of the European Parliament and of the Council on the Restriction of Hazardous Substance (RoHS).

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CSR reserves the right to make technical changes to its products as part of its development programme.

While every care has been taken to ensure the accuracy of the contents of this document, CSR cannot accept responsibility for any errors.

2 Key Features

Radio

- Direct 50Ω connection to a common TX/RX antenna
- Bluetooth v2.0+EDR specification compliant
- Extensive built-in self-test minimises production test time
- No external trimming is required in production
- Antenna matching and filtering within IC

Transmitter

- +6dBm RF transmit power with level control from on-chip 6-bit DAC over a dynamic range >30dB
- Class 2 and Class 3 support without the need for an external power amplifier or TX/RX switch

Receiver

- Integrated channel filters
- Digital demodulator for improved sensitivity and co-channel rejection
- Real time digitised RSSI available on HCI interface
- Fast AGC for enhanced dynamic range

Synthesiser

- Fully integrated synthesiser requires no external VCO varactor diode, resonator or loop filter
- Compatible with crystals between 8 and 32MHz (in multiples of 250kHz) or an external clock
- Accepts 7.68, 14.4, 15.36, 16.2, 16.8, 19.2, 19.44, 19.68, 19.8 and 38.4MHz TCXO frequencies for GSM and CDMA devices with sinusoidal or logic level signals

Auxiliary Features

- Crystal oscillator with built-in digital trimming
- Power management includes digital shutdown, and wake up commands with an integrated low power oscillator for ultra low Park/Sniff/Hold mode
- Clock request output to control external clock
- On-chip linear regulator, producing 1.8V output from 2.2V to 4.2V input
- Power on reset cell detects low supply voltage
- Arbitrary power supply sequencing permitted
- 8-bit ADC and DAC available to application

Baseband and Software

- Internal programmed 4Mbit ROM for complete system solution
- 48kbyte on-chip RAM allows full speed Bluetooth data transfer, mixed voice and data, plus full seven slave piconet operation
- Logic for forward error correction, header error control, access code correlation, demodulation, CRC, encryption bitstream generation, whitening and transmit pulse shaping
- Transcoders for A-law, μ -law and linear voice from host and A-law, μ -law and CVSD voice over air

Physical Interfaces

- Synchronous serial interface up to 4M baud for system debugging
- UART interface with programmable baud rate up to 3M baud with an optional bypass mode
- Full speed USB interface supports OHCI and UHCI host interfaces. Compliant with USB v2.0
- Synchronous bi-directional serial programmable audio interface
- Optional I²C™ compatible interface

Bluetooth Stack

CSR's Bluetooth Protocol Stack runs on-chip in a variety of configurations:

- Standard HCI (UART or USB)
- Fully embedded to RFCOMM
- Customer specific builds with embedded application code

Package Options

- 96-ball LFBGA 10 x 10 x 1.6mm 0.8mm pitch

3 Package Information

3.1 BC41B143A Pinout Diagram

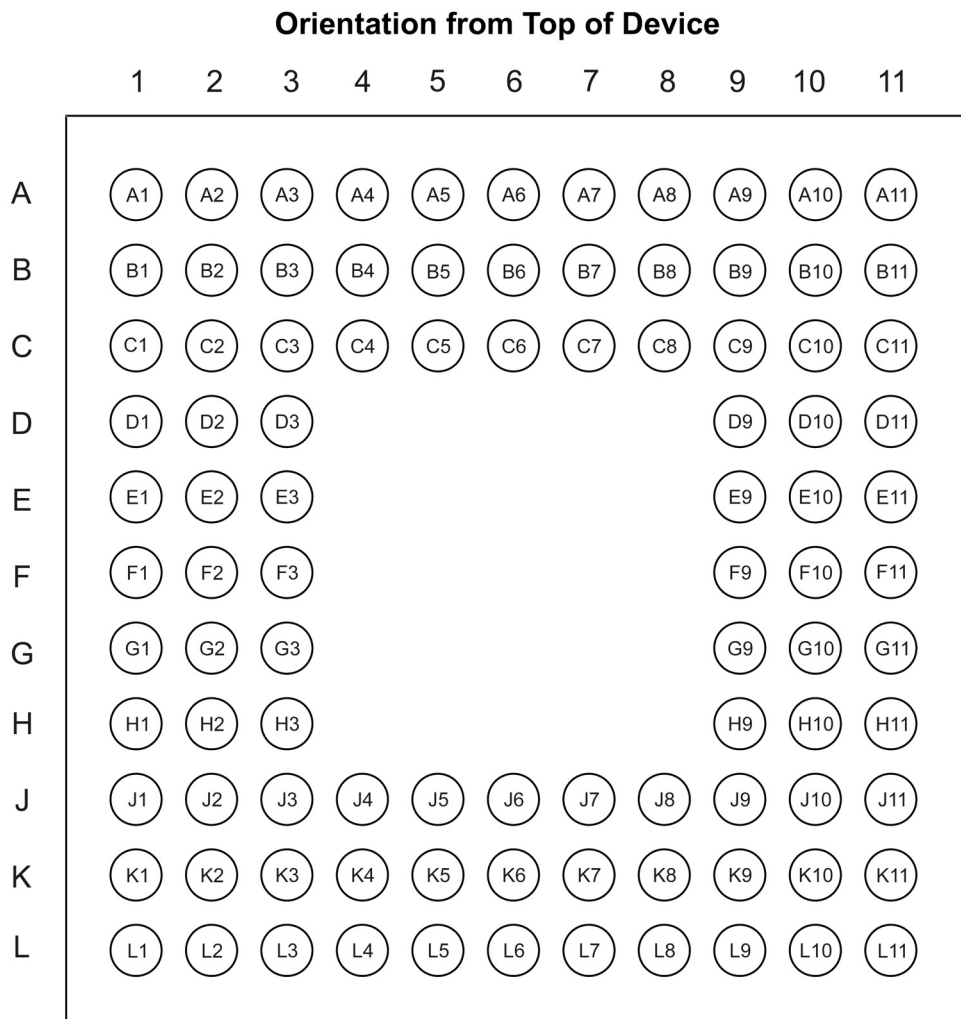


Figure 3.1: BlueCore4-ROM Plug-n-Go 10 x 10mm LFBGA Package

3.2 BC41B143A-ANN-E4 Device Terminal Functions

| Radio | Ball | Pad Type | Description |
|-------------|------|---|--------------------------------|
| RF_IN | D2 | Analogue | Single ended receiver input |
| PIO[0]/RXEN | D3 | Bi-directional with programmable strength internal pull-up/down | Programmable input/output line |
| PIO[1]/TXEN | C4 | Bi-directional with programmable strength internal pull-up/down | Programmable input/output line |
| BAL_MATCH | A1 | Analogue | Tie to VSS_RADIO |
| RF_CONNECT | B1 | Analogue | 50Ω RF matched I/O |
| AUX_DAC | C2 | Analogue | Voltage DAC output |

| Synthesiser and Oscillator | Ball | Pad Type | Description |
|----------------------------|------|----------|-------------------------------------|
| XTAL_IN | L3 | Analogue | For crystal or external clock input |
| XTAL_OUT | L4 | Analogue | Drive for crystal |

| PCM Interface | Ball | Pad Type | Description |
|---------------|------|---|-------------------------|
| PCM_OUT | G10 | CMOS output, tristatable with weak internal pull-down | Synchronous data output |
| PCM_IN | H11 | CMOS input, with weak internal pull-down | Synchronous data input |
| PCM_SYNC | G11 | Bi-directional with weak internal pull-down | Synchronous data sync |
| PCM_CLK | H10 | Bi-directional with weak internal pull-down | Synchronous data clock |

| USB and UART | Ball | Pad Type | Description |
|--------------|------|---|---|
| UART_TX | J10 | CMOS output, tri-state with weak internal pull-up | UART data output active low |
| UART_RX | J11 | CMOS input with weak internal pull-down | UART data input active low (idle status high) |
| UART_RTS | L11 | CMOS output, tristatable with weak internal pull-up | UART request to send active low |
| UART_CTS | K11 | CMOS input with weak internal pull-down | UART clear to send active low |
| USB_DP | L9 | Bi-directional | USB data plus with selectable internal 1.5kΩ pull-up resistor |
| USB_DN | L8 | Bi-directional | USB data minus |



| Test and Debug | Ball | Pad Type | Description |
|----------------|------|---|--|
| RESET | F9 | CMOS input with weak internal pull-down | Reset if high. Input debounced so must be high for >5ms to cause a reset |
| RESETB | G9 | CMOS input with weak internal pull-up | Reset if low. Input debounced so must be low for >5ms to cause a reset |
| SPI_CSB | C10 | CMOS input with weak internal pull-up | Chip select for Serial Peripheral Interface, active low |
| SPI_CLK | D10 | CMOS input with weak internal pull-down | Serial Peripheral Interface clock |
| SPI_MOSI | D11 | CMOS input with weak internal pull-down | Serial Peripheral Interface data input |
| SPI_MISO | C11 | CMOS output, tristatable with weak internal pull-down | Serial Peripheral Interface data output |
| TEST_EN | E9 | CMOS input with strong internal pull-down | For test purposes only (leave unconnected) |
| FLASH_EN | B10 | No connect | Not available for BlueCore4-ROM Plug-n-Go |

| PIO Port | Ball | Pad Type | Description |
|----------|------|---|--------------------------------|
| PIO[2] | C3 | Bi-directional with programmable strength internal pull-up/down | Programmable input/output line |
| PIO[3] | B2 | Bi-directional with programmable strength internal pull-up/down | Programmable input/output line |
| PIO[4] | H9 | Bi-directional with programmable strength internal pull-up/down | Programmable input/output line |
| PIO[5] | J8 | Bi-directional with programmable strength internal pull-up/down | Programmable input/output line |
| PIO[6] | K8 | Bi-directional with programmable strength internal pull-up/down | Programmable input/output line |
| PIO[7] | K9 | Bi-directional with programmable strength internal pull-up/down | Programmable input/output line |
| PIO[8] | B3 | Bi-directional with programmable strength internal pull-up/down | Programmable input/output line |
| PIO[9] | B4 | Bi-directional with programmable strength internal pull-up/down | Programmable input/output line |
| PIO[10] | A4 | Bi-directional with programmable strength internal pull-up/down | Programmable input/output line |
| PIO[11] | A5 | Bi-directional with programmable strength internal pull-up/down | Programmable input/output line |
| AIO[0] | K5 | Bi-directional | Programmable input/output line |
| AIO[1] | J6 | Bi-directional | Programmable input/output line |
| AIO[2] | K7 | Bi-directional | Programmable input/output line |

| Power Supplies and Control | Ball | Pad Type | Description |
|----------------------------|--------------|----------------------|---|
| VREG_IN | L7 | Regulator input | Linear regulator voltage input |
| VREG_EN | J2 | Digital input | Active high, regulator enable pin with internal pull-up |
| VDD_USB | L10 | VDD | Positive supply for UART/USB and AIO ports |
| VDD_PIO | A3 | VDD | Positive supply for PIO and AUX DAC ^(a) |
| VDD_PADS | E11 | VDD | Positive supply for all other digital input/output ports ^(b) |
| VDD_DIG | L6 | Regulator output | Positive 1.8V supply output for VDD_MEM and VDD_CORE |
| VDD_MEM | B11, K6 | VDD | Positive supply for internal memory |
| VDD_CORE | F11 | VDD | Positive supply for internal digital circuitry |
| VDD_RADIO | E3 | VDD | Positive supply for RF circuitry |
| VDD_ANA | L5 | VDD/Regulator output | Positive supply for analogue circuitry and 1.8V regulated output |
| VDD_BALUN | F1 | VDD | Positive supply for balun |
| VSS_PADS | A2, E10, K10 | VSS | Ground connection for input/output |
| VSS_MEM | D9, J9 | VSS | Ground connections for AIO and Extended PIO ports |
| VSS_CORE | F10 | VSS | Ground connection for internal digital circuitry |
| VSS_RADIO | E2, F3, G2 | VSS | Ground connections for RF circuitry |
| VSS_VCO | G3, H2, H3 | VSS | Ground connections for VCO and synthesiser |
| VSS_ANA | K4 | VSS | Ground connection for analogue circuitry |
| VSS_BALUN | G1, J1, K1 | VSS | Ground connection for balun |

(a) Positive supply for PIO[3:0] and PIO[11:8]

(b) Positive supply for SPI/PCM ports and PIO[7:4]

| Unconnected Terminals | Ball | Description |
|-----------------------|--|-------------------|
| N/C | A6, A7, A8, A9, A10, A11, B5, B6, B7, B8, B9, C1, C5, C6, C7, C8, C9, D1, E1, F2, H1, J3, J4, J5, J7, K2, K3, L1, L2 | Leave unconnected |

4 Electrical Characteristics

| Absolute Maximum Ratings | | |
|--|----------|----------|
| Rating | Min | Max |
| Storage Temperature | -40°C | +150°C |
| Supply Voltage: VDD_RADIO, VDD_ANA, VDD_BAL and VDD_CORE | -0.4V | 2.2V |
| Supply Voltage: VDD_MEM, VDD_PADS, VDD_PIO and VDD_USB | -0.4V | 3.7V |
| Supply Voltage: VREG_IN | -0.4V | 5.6V |
| Other Terminal Voltages | VSS-0.4V | VDD+0.4V |

| Recommended Operating Conditions | | |
|--|-------|---------------------|
| Operating Condition | Min | Max |
| Operating Temperature Range | -40°C | +85°C |
| Guaranteed RF performance range (a) | -25°C | +85°C |
| Supply Voltage: VDD_RADIO, VDD_ANA and VDD_CORE | 1.7V | 1.9V |
| Supply Voltage: VDD_MEM, VDD_PADS, VDD_PIO and VDD_USB | 1.7V | 3.6V |
| Supply Voltage: VREG_IN | 2.2V | 4.2V ^(b) |

(a) Typical figures are given for RF performance between -40°C and +85°C.

(b) The device will operate without damage with VREG_IN as high as 5.6V, however the RF performance is not guaranteed above 4.2V.

| Input/Output Terminal Characteristics (Supply) | | | | |
|---|------|------|--------------------|--------|
| Linear Regulator | Min | Typ | Max | Unit |
| Normal Operation | | | | |
| Output Voltage ^(a) ($I_{load} = 70 \text{ mA}$) | 1.70 | 1.78 | 1.85 | V |
| Temperature Coefficient | -250 | - | +250 | ppm/°C |
| Output Noise ^(b) (c) | - | - | 1 | mV rms |
| Load Regulation ($I_{load} < 100 \text{ mA}$) | - | - | 50 | mV/A |
| Settling Time ^(b) (d) | - | - | 50 | μs |
| Maximum Output Current | 140 | - | - | mA |
| Minimum Load Current | 5 | - | - | μA |
| Input Voltage | - | - | 4.2 ^(e) | V |
| Dropout Voltage ($I_{load} = 70 \text{ mA}$) | - | - | 350 | mV |
| Quiescent Current (excluding load, $I_{load} < 1 \text{ mA}$) | 25 | 35 | 50 | μA |
| Low Power Mode^(f) | | | | |
| Quiescent Current (excluding load, $I_{load} < 100 \mu\text{A}$) | 4 | 7 | 10 | μA |
| Disabled Mode^(g) | | | | |
| Quiescent Current | 1.5 | 2.5 | 3.5 | μA |

- (a) For optimum performance, the VDD_ANA ball adjacent to VREG_IN should be used for regulator output.
- (b) Regulator output connected to 47nF pure and 4.7μF 2.2Ω ESR capacitors.
- (c) Frequency range is 100Hz to 100kHz.
- (d) 1mA to 70mA pulsed load.
- (e) Operation up to 5.6V is permissible without damage and without the output voltage rising sufficiently to damage the rest of BlueCore4-ROM Plug-n-Go, but output regulation and other specifications are no longer guaranteed at input voltages in excess of 4.2V.
- (f) Low power mode is entered and exited automatically when the chip enters/leaves Deep Sleep mode.
- (g) Regulator is disabled when VREG_EN is pulled low. It is also disabled when VREG_IN is either open circuit or driven to the same voltage as VDD_ANA.

| Input/Output Terminal Characteristics (Digital) | | | | | |
|--|-------------------|---------|------|---------|------|
| Digital Terminals | | Min | Typ | Max | Unit |
| Input Voltage Levels | | | | | |
| V _{IL} input logic level low | 2.7V ≤ VDD ≤ 3.0V | -0.4 | - | +0.8 | V |
| | 1.7V ≤ VDD ≤ 1.9V | -0.4 | - | +0.4 | V |
| V _{IH} input logic level high | | 0.7VDD | - | VDD+0.4 | V |
| Output Voltage Levels | | | | | |
| V _{OL} output logic level low, (I _O = 4.0mA), 2.7V ≤ VDD ≤ 3.0V | | - | - | 0.2 | V |
| V _{OL} output logic level low, (I _O = 4.0mA), 1.7V ≤ VDD ≤ 1.9V | | - | - | 0.4 | V |
| V _{OH} output logic level high, (I _O = -4.0mA), 2.7V ≤ VDD ≤ 3.0V | | VDD-0.2 | - | - | V |
| V _{OH} output logic level high, (I _O = -4.0mA), 1.7V ≤ VDD ≤ 1.9V | | VDD-0.4 | - | - | V |
| Input and Tri-state Current with: | | | | | |
| Strong pull-up | | -100 | -40 | -10 | μA |
| Strong pull-down | | +10 | +40 | +100 | μA |
| Weak pull-up | | -5.0 | -1.0 | -0.2 | μA |
| Weak pull-down | | +0.2 | +1.0 | +5.0 | μA |
| I/O pad leakage current | | -1 | 0 | +1 | μA |
| C _I Input Capacitance | | 1.0 | - | 5.0 | pF |

| Input/Output Terminal Characteristics (USB) | | | | | |
|---|--|------------|-----|------------|------|
| USB Terminals | | Min | Typ | Max | Unit |
| VDD_USB for correct USB operation | | 3.1 | | 3.6 | V |
| Input Threshold | | | | | |
| V _{IL} input logic level low | | - | - | 0.3VDD_USB | V |
| V _{IH} input logic level high | | 0.7VDD_USB | - | - | V |
| Input Leakage Current | | | | | |
| VSS_PADS < VIN < VDD_USB ^(a) | | -1 | 1 | 5 | μA |
| C _I Input capacitance | | 2.5 | - | 10.0 | pF |
| Output Voltage Levels to Correctly Terminated USB Cable | | | | | |
| V _{OL} output logic level low | | 0.0 | - | 0.2 | V |
| V _{OH} output logic level high | | 2.8 | - | VDD_USB | V |

(a) Internal USB pull-up disabled

| Input/Output Terminal Characteristics (Reset) | | | | |
|---|------|------|------|------|
| Power-on Reset | Min | Typ | Max | Unit |
| VDD_CORE falling threshold | 1.40 | 1.50 | 1.60 | V |
| VDD_CORE rising threshold | 1.50 | 1.60 | 1.70 | V |
| Hysteresis | 0.05 | 0.10 | 0.15 | V |

| Input/Output Terminal Characteristics (Auxilliary ADC) | | | | | |
|--|-----|------|-----|---------|-----------|
| Auxiliary ADC | | Min | Typ | Max | Unit |
| Resolution | | - | - | 8 | Bits |
| Input voltage range (LSB size = VDD_ANA/255) | | 0 | - | VDD_ANA | V |
| Accuracy | INL | -1 | - | 1 | LSB |
| (Guaranteed monotonic) | DNL | 0 | - | 1 | LSB |
| Offset | | -1 | - | 1 | LSB |
| Gain Error | | -0.8 | - | 0.8 | % |
| Input Bandwidth | | - | 100 | - | kHz |
| Conversion time | | - | 2.5 | - | μs |
| Sample rate ^(a) | | - | - | 700 | Samples/s |

(a) ADC is accessed through the VM function. The sample rate given is achieved as part of this function.

| Input/Output Terminal Characteristics (Auxiliary DAC) | | | | |
|---|-------------|--------------------------|---------|------|
| Auxiliary DAC | Min | Typ | Max | Unit |
| Resolution | - | - | 8 | Bits |
| Average output step size ^(a) | 12.5 | 14.5 | 17.0 | mV |
| Output Voltage | | monotonic ^(a) | | |
| Voltage range (I _O =0mA) | VSS_PADS | - | VDD_PIO | V |
| Current range | -10.0 | - | +0.1 | mA |
| Minimum output voltage (I _O =100μA) | 0.0 | - | 0.2 | V |
| Maximum output voltage (I _O =10mA) | VDD_PIO-0.3 | - | VDD_PIO | V |
| High Impedance leakage current | -1 | - | +1 | μA |
| Offset | -220 | - | +120 | mV |
| Integral non-linearity ^(a) | -2 | - | +2 | LSB |
| Settling time (50pF load) | - | - | 10 | μs |

(a) Specified for an output voltage between 0.2V and VDD_PIO -0.2V. Output is high impedance when chip is in Deep Sleep mode.

| Input/Output Terminal Characteristics (Clocks) | | | | |
|--|-----|------|---------|------------|
| Crystal Oscillator | Min | Typ | Max | Unit |
| Crystal frequency ^(a) | 8.0 | - | 32.0 | MHz |
| Digital trim range ^(b) | 5.0 | 6.2 | 8.0 | pF |
| Trim step size ^(b) | - | 0.1 | - | pF |
| Transconductance | 2.0 | - | - | mS |
| Negative resistance ^(c) | 870 | 1500 | 2400 | Ω |
| External Clock | | | | |
| Input frequency ^(d) | 7.5 | - | 40.0 | MHz |
| Clock input level ^(e) | 0.2 | - | VDD_ANA | V pk-pk |
| Allowable Jitter | - | - | 15 | ps rms |
| XTAL_IN input impedance | - | - | - | k Ω |
| XTAL_IN input capacitance | - | 7 | - | pF |

- (a) Integer multiple of 250kHz
- (b) The difference between the internal capacitance at minimum and maximum settings of the internal digital trim.
- (c) XTAL frequency = 16MHz; XTAL C0 = 0.75pF; XTAL load capacitance = 8.5pF.
- (d) Clock input can be any frequency between 8MHz and 40MHz in steps of 250kHz plus CDMA/3G TCXO frequencies of 7.68, 14.44, 15.36, 16.2, 16.8, 19.2, 19.44, 19.68, 19.8 and 38.4MHz.
- (e) Clock input can be either sinusoidal or square wave. If the peaks of the signal are below VSS_ANA or above VDD_ANA. A DC blocking capacitor is required between the signal and XTAL_IN.

4.1 Power Consumption

| Typical Average Current Consumption | | |
|--|---------------------|----------------------|
| VDD=1.8V | Temperature = +20°C | Output Power = +4dBm |
| Mode | Average | Unit |
| SCO connection HV3 (30ms interval Sniff Mode) (Slave) | 21 | mA |
| SCO connection HV3 (30ms interval Sniff Mode) (Master) | 21 | mA |
| SCO connection HV3 (No Sniff Mode) (Slave) | 28 | mA |
| SCO connection HV1 (Slave) | 42 | mA |
| SCO connection HV1 (Master) | 42 | mA |
| ACL data transfer 115.2kbps UART no traffic (Master) | 5 | mA |
| ACL data transfer 115.2kbps UART no traffic (Slave) | 22 | mA |
| ACL data transfer 720kbps UART (Master or Slave) | 45 | mA |
| ACL data transfer 720kbps USB (Master or Slave) | 45 | mA |
| ACL connection, Sniff Mode 40ms interval, 38.4kbps UART | 3.2 | mA |
| ACL connection, Sniff Mode 1.28s interval, 38.4kbps UART | 0.45 | mA |
| Parked Slave, 1.28s beacon interval, 38.4kbps UART | 0.55 | mA |
| Standby Mode (Connected to host, no RF activity) | 47.0 | μA |
| Reset (RESET high or RESETB low) | 15.0 | μA |

| Typical Peak Current at +20°C | |
|---|--------------|
| Device Activity/State | Current (mA) |
| Peak Current during cold boot (100ms sampling interval) | - |
| Peak TX Current Average across burst) | - |
| Peak RX Current | - |
| Average RX Current across burst | - |

| Conditions | |
|----------------------------|---|
| VREG_IN, VDD_PIO, VDD_PADS | - |
| Host Interface | - |
| Baud Rate | - |
| Clock Source | - |
| Output Power | - |
| Receive Sensitivity | - |
| Device Mode | - |
| Packet Type | - |

5 Radio Characteristics - Basic Data Rate

5.1 Temperature +20°C

5.1.1 Transmitter

| Radio Characteristics | VDD = 1.8V | | Temperature = +20°C | | |
|---|------------|------|---------------------|-------------------------------|----------------|
| | Min | Typ | Max | Bluetooth Specification | Unit |
| Maximum RF transmit power ^{(a) (b)} | TBD | 2.5 | - | -6 to +4 ^(c) | dBm |
| RF power variation over temperature range with compensation enabled (\pm) ^(d) | - | 1.5 | TBD | - | dB |
| RF power variation over temperature range with compensation disabled (\pm) ^(d) | - | 2.5 | TBD | - | dB |
| RF power control range | 25 | 35 | - | ≥ 16 | dB |
| RF power range control resolution ^(e) | - | 0.5 | 1.2 | - | dB |
| 20dB bandwidth for modulated carrier | - | 780 | 1000 | ≤ 1000 | kHz |
| Adjacent channel transmit power $F = F_0 \pm 2\text{MHz}^{(f) (g)}$ | - | -40 | -20 | ≤ -20 | dBm |
| Adjacent channel transmit power $F = F_0 \pm 3\text{MHz}^{(f) (g)}$ | - | -45 | -40 | ≤ -40 | dBm |
| Adjacent channel transmit power $F = F_0 \pm > 3\text{MHz}^{(f) (g)}$ | - | -50 | -40 | ≤ -40 | dBm |
| $\Delta f_{1\text{avg}}$ Maximum Modulation | 140 | 165 | 175 | $140 < f_{1\text{avg}} < 175$ | kHz |
| $\Delta f_{2\text{max}}$ Minimum Modulation | 115 | 150 | - | 115 | kHz |
| $\Delta f_{1\text{avg}}/\Delta f_{2\text{avg}}$ | 0.8 | 0.97 | - | ≥ 0.80 | - |
| Initial carrier frequency tolerance | - | 6 | ± 75 | ± 75 | kHz |
| Drift Rate | - | 8 | 20 | ≤ 20 | kHz/50 μ s |
| Drift (single slot packet) | - | 7 | 25 | ≤ 25 | kHz |
| Drift (five slot packet) | - | 9 | 40 | ≤ 40 | kHz |
| 2 nd Harmonic Content | - | TBD | -30 | ≤ 30 | dBm |
| 3 rd Harmonic Content | - | TBD | -40 | ≤ 30 | dBm |

- (a) The BlueCore4-ROM Plug-n-Go firmware maintains the transmit power to be within the Bluetooth specification v2.0+EDR limits.
- (b) Measurement made using a PSKEY_LC_MAX_TX_POWER setting corresponds to a PSKEY_LC_POWER_TABLE power table entry of 63
- (c) Class 2 RF transmit power range, Bluetooth specification v2.0+EDR
- (d) To some extent these parameters are dependent on the matching circuit used, and its behaviour over temperature. Therefore these parameters may be beyond CSR's direct control.
- (e) Resolution guaranteed over the range -5dB to -25dB relative to maximum power for Tx Level > 20
- (f) Measured at $F_0 = 2441\text{MHz}$
- (g) Up to three exceptions are allowed in v2.0+EDR of the Bluetooth specification. BlueCore4-ROM Plug-n-Go is guaranteed to meet the ACP performance as specified by the Bluetooth specification v2.0+EDR

| Radio Characteristics | | VDD = 1.8V | | Temperature = +20°C | | | |
|--|------------------------------|------------|-----|---------------------|---------------------|----------|--|
| | Frequency (GHz) | Min | Typ | Max | Cellular Band | Unit | |
| Emitted power in cellular bands measured at RF_CONNECT. Output power ≤4dBm | 0.869 - 0.894 ^(a) | - | TBD | TBD | GSM 850 | dBm / Hz | |
| | 0.869 - 0.894 ^(b) | - | TBD | TBD | CDMA 850 | | |
| | 0.925 - 0.960 ^(a) | - | TBD | TBD | GSM 900 | | |
| | 1.570 - 1.580 ^(c) | - | TBD | TBD | GPS | | |
| | 1.805 - 1.880 ^(a) | - | TBD | TBD | GSM 1800 / DCS 1800 | | |
| | 1.930 - 1.990 ^(d) | - | TBD | TBD | PCS 1900 | | |
| | 1.930 - 1.990 ^(b) | - | TBD | TBD | GSM 1900 | | |
| | 1.930 - 1.990 ^(a) | - | TBD | TBD | CDMA 1900 | | |
| | 2.110 - 2.170 ^(b) | - | TBD | TBD | W-CDMA 2000 | | |
| | 2.110 - 2.170 ^(e) | - | TBD | TBD | W-CDMA 2000 | | |

(a) Integrated in 200kHz bandwidth and then normalised to 1Hz bandwidth

(b) Integrated in 1.2MHz bandwidth and then normalised to 1Hz bandwidth

(c) Integrated in 1MHz bandwidth and then normalised to 1Hz bandwidth

(d) Integrated in 30kHz bandwidth and then normalised to 1Hz bandwidth

(e) Integrated in 5MHz bandwidth and then normalised to 1Hz bandwidth

5.1.2 Receiver

| Radio Characteristics | | VDD = 1.8V | | | Temperature = +20°C | |
|--|-----------------|------------|-----|-----|-------------------------|--------|
| | Frequency (GHz) | Min | Typ | Max | Bluetooth Specification | Unit |
| Sensitivity at 0.1% BER for all packet types | 2.402 | - | -84 | TBD | ≤-70 | dBm |
| | 2.441 | - | -84 | TBD | | |
| | 2.480 | - | -86 | TBD | | |
| Maximum received signal at 0.1% BER | | -20 | TBD | - | ≥-20 | dBm |
| | Frequency (MHz) | Min | Typ | Max | Bluetooth Specification | Unit |
| Continuous power required to block Bluetooth reception (for input power of -67dBm with 0.1% BER) measured at the unbalanced port of the balun. | 30-2000 | -10 | TBD | - | -10 | dBm |
| | 2000-2400 | -27 | TBD | - | -27 | |
| | 2500-3000 | -27 | TBD | - | -27 | |
| | 3000-3300 | -10 | TBD | - | -10 | |
| C/I co-channel | | - | 6 | 11 | ≤11 | dB |
| Adjacent channel selectivity C/I $F = F_0 + 1\text{MHz}^{(a) (b)}$ | | - | -5 | 0 | ≤0 | dB |
| Adjacent channel selectivity C/I $F = F_0 - 1\text{MHz}^{(a) (b)}$ | | - | -4 | 0 | ≤0 | dB |
| Adjacent channel selectivity C/I $F = F_0 + 2\text{MHz}^{(a) (b)}$ | | - | -38 | -30 | ≤-30 | dB |
| Adjacent channel selectivity C/I $F = F_0 - 2\text{MHz}^{(a) (b)}$ | | - | -23 | -20 | ≤-20 | dB |
| Adjacent channel selectivity C/I $F \geq F_0 + 3\text{MHz}^{(a) (b)}$ | | - | -45 | -40 | ≤-40 | dB |
| Adjacent channel selectivity C/I $F \leq F_0 - 5\text{MHz}^{(a) (b)}$ | | - | -44 | -40 | ≤-40 | dB |
| Adjacent channel selectivity C/I $F = F_{\text{Image}}^{(a) (b)}$ | | - | -22 | -9 | ≤-9 | dB |
| Maximum level of intermodulation interferers ^(c) | | -39 | TBD | - | ≥-39 | dBm |
| Spurious output level ^(d) | | - | TBD | - | - | dBm/Hz |

(a) Up to five exceptions are allowed in v2.0+EDR of the Bluetooth specification. BlueCore4-ROM Plug-n-Go is guaranteed to meet the C/I performance as specified by the Bluetooth specification v2.0+EDR.

(b) Measured at $F = 2441\text{MHz}$

(c) Measured at $f_1 - f_2 = 5\text{MHz}$. Measurement is performed in accordance with Bluetooth RF test RCV/CA/05/c., i.e., wanted signal at -64dBm.

(d) Measured at RF_CONNECT. Integrated in 100kHz bandwidth and normalised to 1Hz. Figure is typically below TBDdBm/Hz except for peaks of TBDdBm at 1.6GHz, TBDdBm inband at 2.4GHz and TBDdBm at 3.2GHz.

| Radio Characteristics | | VDD = 1.8V | | Temperature = +20°C | | |
|--|-----------------|------------|--------------------|---------------------|---------------------|------|
| | Frequency (GHz) | Min | Typ | Max | Cellular Band | Unit |
| Continuous power in cellular bands required to block Bluetooth reception (for input power of -67dBm with 0.1% BER) measured at RF_CONNECT. | 0.824 - 0.849 | - | TBD ^(a) | - | GSM 850 | dBm |
| | 0.824 - 0.849 | - | TBD | - | CDMA 850 | |
| | 0.880 - 0.915 | - | TBD | - | GSM 900 | |
| | 1.710 - 1.785 | - | TBD | - | GSM 1800 / DCS 1800 | |
| | 1.850 - 1.910 | - | TBD | - | GSM 1900 / PCS 1900 | |
| | 1.850 - 1.910 | - | TBD | - | CDMA 1900 | |
| | 1.920 - 1.980 | - | TBD | - | W-CDMA 2000 | |
| Continuous power in cellular bands required to block Bluetooth reception (for input power of -72dBm with 0.1% BER) measured at RF_CONNECT. TBD | 0.824 - 0.849 | - | TBD | - | GSM 850 | dBm |
| | 0.824 - 0.849 | - | TBD | - | CDMA 850 | |
| | 0.880 - 0.915 | - | TBD | - | GSM 900 | |
| | 1.710 - 1.785 | - | TBD | - | GSM 1800 / DCS 1800 | |
| | 1.850 - 1.910 | - | TBD | - | GSM 1900 / PCS 1900 | |
| | 1.850 - 1.910 | - | TBD | - | CDMA 1900 | |
| | 1.920 - 1.980 | - | TBD | - | W-CDMA 2000 | |

(a) TBD dBm if $f_{\text{BLOCKING}} < 0.831\text{GHz}$

5.2 Temperature -40°C

5.2.1 Transmitter

| Radio Characteristics | VDD = 1.8V | | | Temperature = -40°C | |
|---|------------|------|------|-------------------------|----------|
| | Min | Typ | Max | Bluetooth Specification | Unit |
| Maximum RF transmit power ^(a) | TBD | 3.5 | - | -6 to +4 ^(b) | dBm |
| RF power control range | 25 | 35 | - | ≥16 | dB |
| RF power range control resolution | - | 0.5 | - | - | dB |
| 20dB bandwidth for modulated carrier | - | 780 | 1000 | ≤1000 | kHz |
| Adjacent channel transmit power F = F ₀ ± 2MHz ^(c) (d) | - | -40 | -20 | ≤-20 | dBm |
| Adjacent channel transmit power F = F ₀ ± 3MHz ^(c) (d) | - | -45 | -40 | ≤-40 | dBm |
| Δf1avg Maximum Modulation | 140 | 165 | 175 | 140<Δf1avg<175 | kHz |
| Δf2max Minimum Modulation | 115 | 151 | - | 115 | kHz |
| Δf2avg/Δf1avg | 0.8 | 0.97 | - | ≥0.80 | - |
| Initial carrier frequency tolerance | - | 10 | ±75 | ±75 | kHz |
| Drift Rate | - | 7 | 20 | ≤20 | kHz/50μs |
| Drift (single slot packet) | - | 8 | 25 | ≤25 | kHz |
| Drift (five slot packet) | - | 12 | 40 | ≤40 | kHz |

- (a) BlueCore4-ROM Plug-n-Go firmware maintains the transmit power to be within the Bluetooth specification v2.0+EDR limits.
(b) Class 2 RF transmit power range, Bluetooth specification v2.0+EDR
(c) Measured at F₀ = 2441MHz
(d) Up to three exceptions are allowed in v2.0+EDR of the Bluetooth specification.

5.2.2 Receiver

| Radio Characteristics | VDD = 1.8V | | | Temperature = -40°C | |
|--|-----------------|-----|-----|---------------------|-------------------------|
| | Frequency (GHz) | Min | Typ | Max | Bluetooth Specification |
| Sensitivity at 0.1% BER for all packet types | 2.402 | - | -86 | TBD | ≤-70 |
| | 2.441 | - | -86 | TBD | |
| | 2.480 | - | -88 | TBD | |
| Maximum received signal at 0.1% BER | | -20 | TBD | - | ≥-20 |

5.3 Temperature -25°C

5.3.1 Transmitter

| Radio Characteristics | VDD = 1.8V | | | Temperature = -25°C | |
|---|------------|------|------|-------------------------|----------|
| | Min | Typ | Max | Bluetooth Specification | Unit |
| Maximum RF transmit power ^(a) | TBD | 3.0 | - | -6 to +4 ^(b) | dBm |
| RF power control range | 25 | 35 | - | ≥16 | dB |
| RF power range control resolution | - | 0.5 | - | - | dB |
| 20dB bandwidth for modulated carrier | - | 780 | 1000 | ≤1000 | kHz |
| Adjacent channel transmit power F = F ₀ ± 2MHz ^(c) (d) | - | -40 | -20 | ≤-20 | dBm |
| Adjacent channel transmit power F = F ₀ ± 3MHz ^(c) (d) | - | -45 | -40 | ≤-40 | dBm |
| Δf1avg Maximum Modulation | 140 | 165 | 175 | 140<Δf1avg<175 | kHz |
| Δf2max Minimum Modulation | 115 | 151 | - | 115 | kHz |
| Δf2avg/Δf1avg | 0.8 | 0.97 | - | ≥0.80 | - |
| Initial carrier frequency tolerance | - | 8 | ±75 | ±75 | kHz |
| Drift Rate | - | 7 | 20 | ≤20 | kHz/50μs |
| Drift (single slot packet) | - | 8 | 25 | ≤25 | kHz |
| Drift (five slot packet) | - | 12 | 25 | ≤40 | kHz |

- (a) BlueCore4-ROM Plug-n-Go firmware maintains the transmit power to be within the Bluetooth specification v2.0+EDR limits.
- (b) Class 2 RF transmit power range, Bluetooth specification v2.0+EDR
- (c) Measured at F₀ = 2441MHz
- (d) Up to three exceptions are allowed in v2.0+EDR of the Bluetooth specification.

5.3.2 Receiver

| Radio Characteristics | | VDD = 1.8V | | Temperature = -25°C | | |
|--|-----------------|------------|-----|---------------------|-------------------------|------|
| | Frequency (GHz) | Min | Typ | Max | Bluetooth Specification | Unit |
| Sensitivity at 0.1% BER for all packet types | 2.402 | - | -86 | TBD | ≤-70 | dBm |
| | 2.441 | - | -86 | TBD | | |
| | 2.480 | - | -87 | TBD | | |
| Maximum received signal at 0.1% BER | | -20 | TBD | - | ≥-20 | dBm |

5.4 Temperature +85°C

5.4.1 Transmitter

| Radio Characteristics | VDD = 1.8V | | | Temperature = +85°C | |
|---|------------|------|------|-------------------------|----------|
| | Min | Typ | Max | Bluetooth Specification | Unit |
| Maximum RF transmit power ^(a) | TBD | 0 | - | -6 to +4 ^(b) | dBm |
| RF power control range | 25 | 35 | - | ≥16 | dB |
| RF power range control resolution | - | 0.5 | - | - | dB |
| 20dB bandwidth for modulated carrier | - | 780 | 1000 | ≤1000 | kHz |
| Adjacent channel transmit power F = F ₀ ± 2MHz ^(c) (d) | - | -40 | -20 | ≤-20 | dBm |
| Adjacent channel transmit power F = F ₀ ± 3MHz ^(c) (d) | - | -45 | -40 | ≤-40 | dBm |
| Δf1avg Maximum Modulation | 140 | 165 | 175 | 140<Δf1avg<175 | kHz |
| Δf2max Minimum Modulation | 115 | 148 | - | 115 | kHz |
| Δf2avg/Δf1avg | 0.8 | 0.97 | - | ≥0.80 | - |
| Initial carrier frequency tolerance | - | 7 | ±75 | ±75 | kHz |
| Drift Rate | - | 7 | 20 | ≤20 | kHz/50μs |
| Drift (single slot packet) | - | 8 | 25 | ≤25 | kHz |
| Drift (five slot packet) | - | 9 | 40 | ≤40 | kHz |

(a) BlueCore4-ROM Plug-n-Go firmware maintains the transmit power to be within the Bluetooth specification v2.0+EDR limits

(b) Class 2 RF transmit power range, Bluetooth specification v2.0+EDR

(c) Measured at F₀ = 2441MHz

(d) Up to three exceptions are allowed in v2.0+EDR of the Bluetooth specification

5.4.2 Receiver

| Radio Characteristics | | VDD = 1.8V | | Temperature = +85°C | | |
|--|-----------------|------------|-----|---------------------|-------------------------|------|
| | Frequency (GHz) | Min | Typ | Max | Bluetooth Specification | Unit |
| Sensitivity at 0.1% BER for all packet types | 2.402 | - | -81 | TBD | ≤-70 | dBm |
| | 2.441 | - | -81 | TBD | | |
| | 2.480 | - | -82 | TBD | | |
| Maximum received signal at 0.1% BER | | -20 | TBD | - | ≥-20 | dBm |

6 Radio Characteristics - Enhanced Data Rate

6.1 Temperature +20°C

6.1.1 Transmitter

| Radio Characteristics | | VDD = 1.8V | | Temperature = +20°C | | |
|--|-----------|------------|-----|---------------------|-------------------------|------|
| | | Min | Typ | Max | Bluetooth Specification | Unit |
| Maximum RF transmit power ^(a) | | - | 6 | - | -6 to +4 ^(b) | dBm |
| Relative transmit power ^(c) | | - | -1 | - | -4 to +1 | dB |
| Carrier frequency stability ^(c) | | - | 3 | - | ≤10 | kHz |
| Modulation Accuracy ^{(c) (d)} | RMS DEVM | - | 10 | - | ≤13 ^(e) | % |
| | 99% DEVM | - | 15 | - | ≤20 ^(e) | % |
| | Peak DEVM | - | 20 | - | ≤25 ^(e) | % |

(a) BlueCore4-ROM Plug-n-Go firmware keeps RF transmit power within the Bluetooth v2.0+EDR specification limits

(b) Class 2 RF transmit power range, Bluetooth v2.0+EDR specification

(c) Measurement methods are in accordance with the Bluetooth v2.0+EDR RF Test Specification

(d) Modulation accuracy utilises differential error vector magnitude (DEVM) with tracking of the carrier frequency drift.

(e) The Bluetooth specification values are for 8DPSK modulation (values for the $\pi/4$ DQPSK modulation are less stringent)

Notes:

Results shown are referenced to the unbalanced port of the balun.

6.1.2 Receiver

| Radio Characteristics | | VDD = 1.8V | | Temperature = +20°C | | |
|---|---------------|------------|-----|---------------------|-------------------------|------|
| | Modulation | Min | Typ | Max | Bluetooth Specification | Unit |
| Sensitivity at 0.01% BER ^(a) | $\pi/4$ DQPSK | - | -86 | - | ≤ -70 | dBm |
| | 8DPSK | - | -79 | - | ≤ -70 | dBm |
| Maximum received signal at 0.1% BER ^(a) | $\pi/4$ DQPSK | - | -6 | - | ≥ -20 | dBm |
| | 8DPSK | - | -7 | - | ≥ -20 | dBm |
| C/I co-channel at 0.1% BER ^(a) | $\pi/4$ DQPSK | - | +11 | - | $\leq +13$ | dB |
| | 8DPSK | - | +19 | - | $\leq +21$ | dB |
| Adjacent channel selectivity | $\pi/4$ DQPSK | - | -8 | - | ≤ 0 | dB |
| C/I $F = F_0 + 1\text{MHz}$ ^{(a) (b) (c)} | 8DPSK | - | -2 | - | $\leq +5$ | dB |
| Adjacent channel selectivity | $\pi/4$ DQPSK | - | -8 | - | ≤ 0 | dB |
| C/I $F = F_0 - 1\text{MHz}$ ^{(a) (b) (c)} | 8DPSK | - | -2 | - | $\leq +5$ | dB |
| Adjacent channel selectivity | $\pi/4$ DQPSK | - | -35 | - | ≤ -30 | dB |
| C/I $F = F_0 + 2\text{MHz}$ ^{(a) (b) (c)} | 8DPSK | - | -35 | - | ≤ -25 | dB |
| Adjacent channel selectivity | $\pi/4$ DQPSK | - | -23 | - | ≤ -20 | dB |
| C/I $F = F_0 - 2\text{MHz}$ ^{(a) (b) (c)} | 8DPSK | - | -19 | - | ≤ -13 | dB |
| Adjacent channel selectivity | $\pi/4$ DQPSK | - | -43 | - | ≤ -40 | dB |
| C/I $F \geq F_0 + 3\text{MHz}$ ^{(a) (b) (c)} | 8DPSK | - | -40 | - | ≤ -33 | dB |
| Adjacent channel selectivity | $\pi/4$ DQPSK | - | -43 | - | ≤ -40 | dB |
| C/I $F \leq F_0 - 5\text{MHz}$ ^{(a) (b) (c)} | 8DPSK | - | -38 | - | ≤ -33 | dB |
| Adjacent channel selectivity | $\pi/4$ DQPSK | - | -17 | - | ≤ -7 | dB |
| C/I $F = F_{\text{Image}}$ ^{(a) (b) (c)} | 8DPSK | - | -10 | - | ≤ 0 | dB |

- (a) Measurements methods are in accordance with the Bluetooth v2.0+EDR RF Test Specification
(b) Up to five exceptions are allowed in the Bluetooth v2.0 +EDR RF Test Specification. BlueCore4-ROM Plug-n-Go is guaranteed to meet the C/I performance as specified by the Bluetooth v2.0 +EDR RF Test Specification
(c) Measured at $F_0 = 2405\text{MHz}, 2441\text{MHz}, 2477\text{MHz}$

Notes:

Results shown are referenced to the unbalanced port of the balun.

6.2 Temperature -40°C

6.2.1 Transmitter

| Radio Characteristics | | VDD = 1.8V | | Temperature = -40°C | | |
|--|-----------|------------|-----|---------------------|-------------------------|------|
| | | Min | Typ | Max | Bluetooth Specification | Unit |
| Maximum RF transmit power ^(a) | | - | 8 | - | -6 to +4 ^(b) | dBm |
| Relative transmit power ^(c) | | - | -1 | - | -4 to +1 | dB |
| Carrier frequency stability ^(c) | | - | 3 | - | ≤10 | kHz |
| Modulation Accuracy ^{(c) (d)} | RMS DEVM | - | 10 | - | ≤13 ^(e) | % |
| | 99% DEVM | - | 15 | - | ≤20 ^(e) | % |
| | Peak DEVM | - | 20 | - | ≤25 ^(e) | % |

- (a) BlueCore4-ROM Plug-n-Go firmware keeps RF transmit power within the Bluetooth v2.0+EDR specification limits
(b) Class 2 RF transmit power range, Bluetooth v2.0+EDR specification
(c) Measurements methods are in accordance with the Bluetooth v2.0+EDR RF Test specification
(d) Modulation accuracy utilises differential error vector magnitude (DEVM) with tracking of the carrier frequency drift.
(e) The Bluetooth specification values are for 8DPSK modulation (values for the $\pi/4$ DQPSK modulation are less stringent)

Notes:

Results shown are referenced to the unbalanced port of the balun.

6.2.2 Receiver

| Radio Characteristics | | VDD = 1.8V | | Temperature = -40°C | | |
|--|---------------|------------|-----|---------------------|-------------------------|------|
| | Modulation | Min | Typ | Max | Bluetooth Specification | Unit |
| Sensitivity at 0.01% BER ^(a) | $\pi/4$ DQPSK | - | -89 | - | ≤-70 | dBm |
| | 8DPSK | - | -82 | - | ≤-70 | dBm |
| Maximum received signal at 0.1% BER ^(a) | $\pi/4$ DQPSK | - | -10 | - | ≥-20 | dBm |
| | 8DPSK | - | -10 | - | ≥-20 | dBm |

- (a) Measurements methods are in accordance with the Bluetooth v2.0 + EDR RF Test Specification

Notes:

Results shown are referenced to the unbalanced port of the balun.

6.3 Temperature -25°C

6.3.1 Transmitter

| Radio Characteristics | | VDD = 1.8V | | Temperature = -25°C | | |
|--|-----------|------------|-----|---------------------|-------------------------|------|
| | | Min | Typ | Max | Bluetooth Specification | Unit |
| Maximum RF transmit power ^(a) | | - | 7 | - | -6 to +4 ^(b) | dBm |
| Relative transmit power ^(c) | | - | -1 | - | -4 to +1 | dB |
| Carrier frequency stability ^(c) | | - | 3 | - | ≤10 | kHz |
| Modulation Accuracy ^(c) (d) | RMS DEVM | - | 10 | - | ≤13 ^(e) | % |
| | 99% DEVM | - | 15 | - | ≤20 ^(e) | % |
| | Peak DEVM | - | 20 | - | ≤25 ^(e) | % |

(a) BlueCore4-ROM Plug-n-Go firmware keeps RF transmit power within the Bluetooth v2.0+EDR specification limits

(b) Class 2 RF transmit power range, Bluetooth v2.0+EDR specification

(c) Measurement methods are in accordance with the Bluetooth v2.0+EDR RF Test Specification

(d) Modulation accuracy utilises differential error vector magnitude (DEVM) with tracking of the carrier frequency drift.

(e) The Bluetooth specification values are for 8DPSK modulation (values for the $\pi/4$ DQPSK modulation are less stringent)

Notes:

Results shown are referenced to the unbalanced port of the balun.

6.3.2 Receiver

| Radio Characteristics | | VDD = 1.8V | | Temperature = -25°C | | |
|--|---------------|------------|-----|---------------------|-------------------------|------|
| | Modulation | Min | Typ | Max | Bluetooth Specification | Unit |
| Sensitivity at 0.01% BER ^(a) | $\pi/4$ DQPSK | - | -87 | - | ≤-70 | dBm |
| | 8DPSK | - | -80 | - | ≤-70 | dBm |
| Maximum received signal at 0.1% BER ^(a) | $\pi/4$ DQPSK | - | -10 | - | ≥-20 | dBm |
| | 8DPSK | - | -10 | - | ≥20 | dBm |

(a) Measurements methods are in accordance with the Bluetooth v2.0 +EDR RF Test Specification

Notes:

Results shown are referenced to the unbalanced port of the balun.

6.4 Temperature +85°C

6.4.1 Transmitter

| Radio Characteristics | | VDD = 1.8V | | Temperature = +85°C | | |
|--------------------------------|-----------|------------|-----|---------------------|-------------------------|------|
| | | Min | Typ | Max | Bluetooth Specification | Unit |
| Maximum RF transmit power (a) | | - | 1 | - | -6 to +4(b) | dBm |
| Relative transmit power(c) | | - | -1 | - | -4 to +1 | dB |
| Carrier frequency stability(c) | | - | 3 | - | ≤10 | kHz |
| Modulation Accuracy(c) (d) | RMS DEVM | - | 10 | - | ≤13(e) | % |
| | 99% DEVM | - | 15 | - | ≤20(e) | % |
| | Peak DEVM | - | 20 | - | ≤25(e) | % |

(a) BlueCore4-ROM Plug-n-Go firmware keeps RF transmit power within the Bluetooth v2.0+EDR specification limits

(b) Class 2 RF transmit power range, Bluetooth v2.0+EDR specification

(c) Measurement methods are in accordance with the Bluetooth v2.0 + EDR RF Test Specification

(d) Modulation accuracy utilises differential error vector magnitude (DEVM) with tracking of the carrier frequency drift.

(e) The Bluetooth specification values are for 8DPSK modulation (values for the $\pi/4$ DQPSK modulation are less stringent)

Notes:

Results shown are referenced to the unbalanced port of the balun.

6.4.2 Receiver

| Radio Characteristics | | VDD = 1.8V | | Temperature = +85°C | | |
|--|---------------|------------|-----|---------------------|-------------------------|------|
| | Modulation | Min | Typ | Max | Bluetooth Specification | Unit |
| Sensitivity at 0.01% BER(a) | $\pi/4$ DQPSK | - | -84 | - | ≤-70 | dBm |
| | 8DPSK | - | -77 | - | ≤-70 | dBm |
| Maximum received signal at 0.1% BER(a) | $\pi/4$ DQPSK | - | 0 | - | ≥-20 | dBm |
| | 8DPSK | - | -3 | - | ≥-20 | dBm |

(a) Measurements methods are in accordance with the Bluetooth v2.0 + EDR RF Test Specification

Notes:

Results shown are referenced to the unbalanced port of the balun.

7 Device Diagram

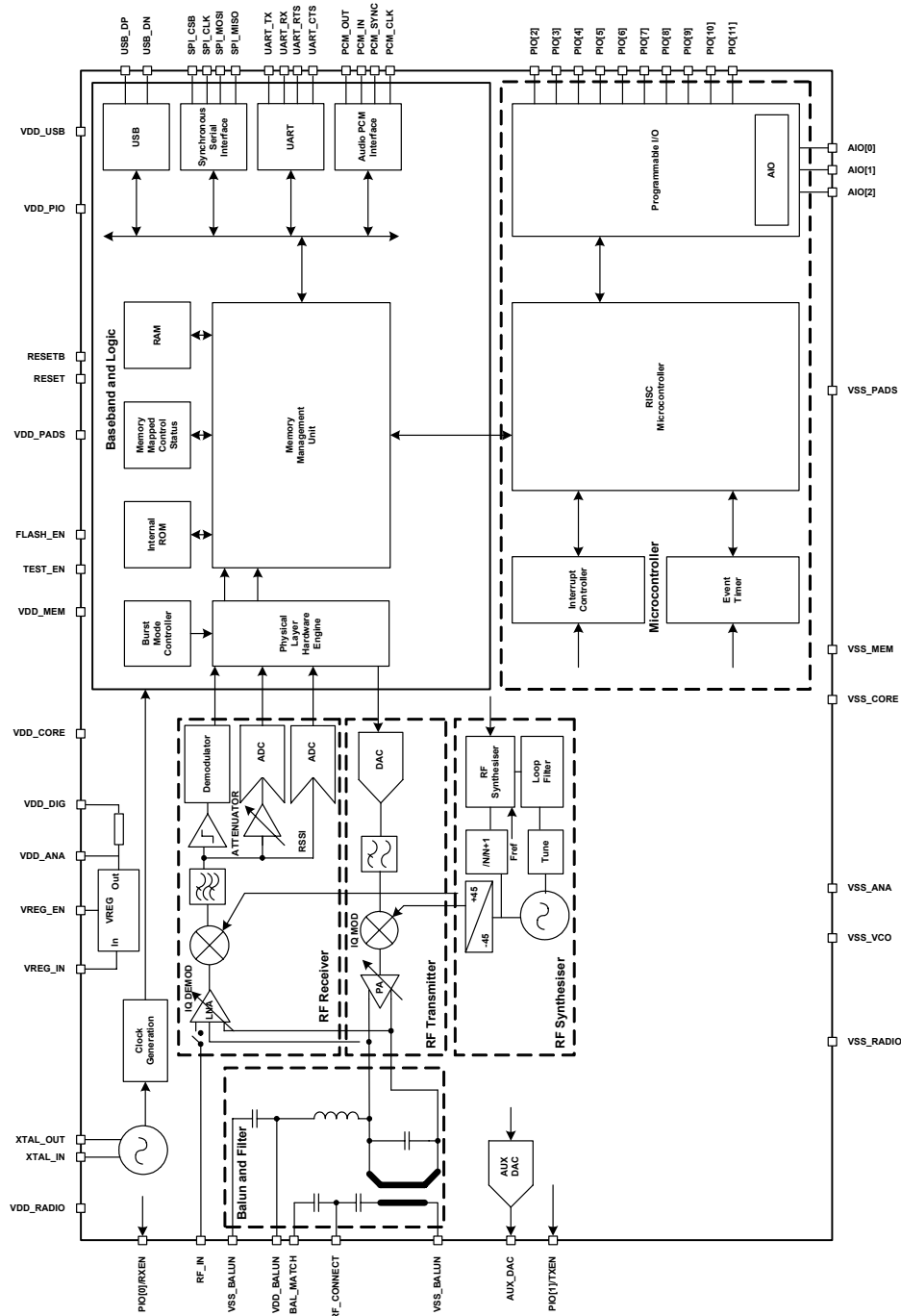


Figure 7.1: BlueCore4-ROM Plug-n-Go Device Diagram

8 Description of Functional Blocks

8.1 RF Receiver

The receiver features a near-zero Intermediate Frequency (IF) architecture that allows the channel filters to be integrated onto the die. Sufficient out-of-band blocking specification at the Low Noise Amplifier (LNA) input allows the radio to be used in close proximity to Global System for Mobile Communications (GSM) and Wideband Code Division Multiple Access (W-CDMA) cellular phone transmitters without being desensitised. The use of a digital Frequency Shift Keying (FSK) discriminator means that no discriminator tank is needed and its excellent performance in the presence of noise allows BlueCore4-ROM Plug-n-Go to exceed the Bluetooth requirements for co-channel and adjacent channel rejection.

For EDR, an ADC is used to digitise the IF received signal.

8.1.1 Low Noise Amplifier

The LNA can be configured to operate in single-ended or differential mode. Single-ended mode is used for Class 1⁽¹⁾ Bluetooth operation; differential mode is used for Class 2 operation.

8.1.2 Analogue to Digital Converter

The Analogue to Digital Converter (ADC) is used to implement fast Automatic Gain Control (AGC). The ADC samples the Received Signal Strength Indicator (RSSI) voltage on a slot-by-slot basis. The front-end LNA gain is changed according to the measured RSSI value, keeping the first mixer input signal within a limited range. This improves the dynamic range of the receiver, improving performance in interference limited environments.

8.2 RF Transmitter

8.2.1 IQ Modulator

The transmitter features a direct IQ modulator to minimise the frequency drift during a transmit timeslot, which results in a controlled modulation index. Digital baseband transmit circuitry provides the required spectral shaping.

8.2.2 Power Amplifier

The internal Power Amplifier (PA) has a maximum output power of +6dBm. This allows BlueCore4-ROM Plug-n-Go to be used in Class 2 and Class 3 radios without an external RF PA.

8.2.3 Auxiliary DAC

An 8-bit voltage Auxiliary DAC is provided for power control of an external PA for Class 1 operation or any other customer specific application.

8.3 Balun and Filter

The Plug-n-Go device incorporates a balun and filter to provide a 50Ω unbalanced antenna port.

8.4 RF Synthesiser

The radio synthesiser is fully integrated onto the die with no requirement for an external Voltage Controlled Oscillator (VCO) screening can, varactor tuning diodes, LC resonators or loop filter. The synthesiser is guaranteed to lock in sufficient time across the guaranteed temperature range to meet the Bluetooth v2.0 + EDR specification.

8.5 Clock Input and Generation

The reference clock for the system is generated from a TCXO or crystal input between 8MHz and 40MHz. All internal reference clocks are generated using a phase locked loop, which is locked to the external reference frequency.

⁽¹⁾ Class 1 operation is not recommended for Plug-n-Go devices and therefore is not recommended for BlueCore4-ROM Plug-n-Go.

8.6 Baseband and Logic

8.6.1 Memory Management Unit

The Memory Management Unit (MMU) provides a number of dynamically allocated ring buffers that hold the data that is in transit between the host and the air. The dynamic allocation of memory ensures efficient use of the available Random Access Memory (RAM) and is performed by a hardware MMU to minimise the overheads on the processor during data/voice transfers.

8.6.2 Burst Mode Controller

During radio transmission the Burst Mode Controller (BMC) constructs a packet from header information previously loaded into memory-mapped registers by the software and payload data/voice taken from the appropriate ring buffer in the RAM. During radio reception, the BMC stores the packet header in memory-mapped registers and the payload data in the appropriate ring buffer in RAM. This architecture minimises the intervention required by the processor during transmission and reception.

8.6.3 Physical Layer Hardware Engine DSP

Dedicated logic is used to perform the following:

- Forward error correction
- Header error control
- Cyclic redundancy check
- Encryption
- Data whitening
- Access code correlation
- Audio transcoding

The following voice data translations and operations are performed by firmware:

- A-law/ μ -law/linear voice data (from host)
- A-law/ μ -law/Continuously Variable Slope Delta (CVSD) (over the air)
- Voice interpolation for lost packets
- Rate mismatches

The hardware supports all optional and mandatory features of Bluetooth v2.0 + EDR including AFH and eSCO.

8.6.4 RAM (48Kbytes)

48Kbytes of on-chip RAM is provided to support the RISC MCU and is shared between the ring buffers used to hold voice/data for each active connection and the general purpose memory required by the Bluetooth stack.

8.6.5 ROM

4Mbits of metal programmable ROM is provided for system firmware implementation.

8.6.6 USB

This is a full speed Universal Serial Bus (USB) interface for communicating with other compatible digital devices. BlueCore4-ROM Plug-n-Go acts as a USB peripheral, responding to requests from a master host controller such as a PC.

8.6.7 Synchronous Serial Interface

This is a synchronous serial port interface (SPI) for interfacing with other digital devices. The SPI port can be used for system debugging. It can also be used for programming the Flash memory.

8.6.8 UART

This is a standard Universal Asynchronous Receiver Transmitter (UART) interface for communicating with other serial devices.

8.7 Microcontroller

The microcontroller (MCU), interrupt controller and event timer run the Bluetooth software stack and control the radio and host interfaces. A 16-bit reduced instruction set computer (RISC) microcontroller is used for low power consumption and efficient use of memory.

8.7.1 Programmable I/O

8.7.2 802.11 Co-Existence Interface

Dedicated hardware is provided to implement a variety of co-existence schemes. Channel skipping AFH, priority signalling, channel signalling and host passing of channel instructions are all supported. The features are configured in firmware. The details of some methods are proprietary (e.g., Intel WCS). Contact CSR for details.

9 CSR Bluetooth Software Stacks

BlueCore4-ROM Plug-n-Go is supplied with Bluetooth v2.0 + EDR compliant stack firmware, which runs on the internal RISC microcontroller.

The BlueCore4-ROM Plug-n-Go software architecture allows Bluetooth processing and the application program to be shared in different ways between the internal RISC microcontroller and an external host processor (if any). The upper layers of the Bluetooth stack (above HCI) can be run either on-chip or on the host processor.

9.1 BlueCore HCI Stack

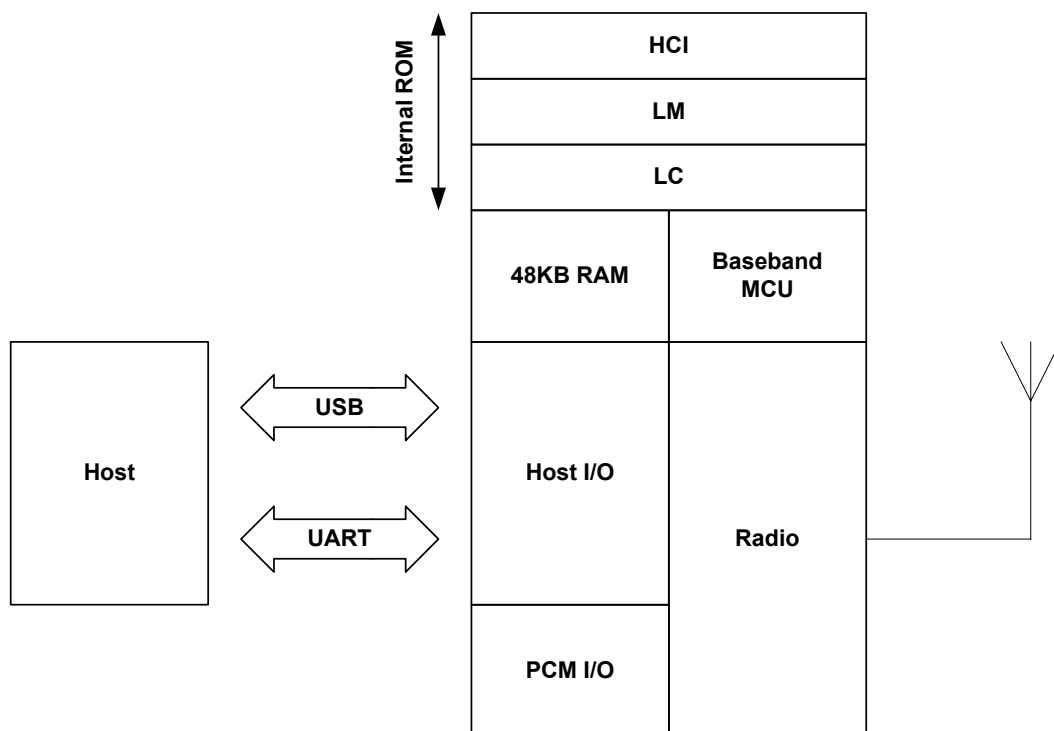


Figure 9.1: BlueCore HCI Stack

In the implementation shown in Figure 9.1 the internal processor runs the Bluetooth stack up to the Host Controller Interface (HCI). The Host processor must provide all upper layers including the application.

9.1.1 Key Features of the HCI Stack: Standard Bluetooth Functionality

Bluetooth v2.0 + EDR mandatory functionality:

- Adaptive frequency hopping (AFH), including classifier
- Faster connection - enhanced inquiry scan (immediate FHS response)
- LMP improvements
- Parameter ranges

Optional Bluetooth v2.0 + EDR functionality supported:

- Adaptive Frequency Hopping (AFH) as Master and Automatic Channel Classification
- Fast Connect - Interlaced Inquiry and Page Scan plus RSSI during Inquiry
- Extended SCO (eSCO), eV3 +CRC, eV4, eV5
- SCO handle
- Synchronisation

The firmware was written against the Bluetooth v2.0 + EDR specification.

- Bluetooth components:
 - Baseband (including LC)
 - LM
 - HCI
- Standard USB v1.1 and UART HCI Transport Layers
- All standard radio packet types
- Full Bluetooth data rate, enhanced data rates of 2 and 3Mbps⁽¹⁾
- Operation with up to seven active slaves⁽¹⁾
- Scatternet v2.5 operation
- Maximum number of simultaneous active ACL connections: 7⁽²⁾
- Maximum number of simultaneous active SCO connections: 3⁽²⁾
- Operation with up to three SCO links, routed to one or more slaves
- All standard SCO voice coding, plus transparent SCO
- Standard operating modes: Page, Inquiry, Page-Scan and Inquiry-Scan
- All standard pairing, authentication, link key and encryption operations
- Standard Bluetooth power saving mechanisms: Hold, Sniff and Park modes, including Forced Hold
- Dynamic control of peers' transmit power via LMP
- Master/Slave switch
- Broadcast
- Channel quality driven data rate
- All standard Bluetooth test modes

The firmware's supported Bluetooth features are detailed in the standard Protocol Implementation Conformance Statement (PICS) documents, available from www.csr.com.

⁽¹⁾ This is the maximum allowed by Bluetooth v2.0 + EDR specification.

⁽²⁾ BlueCore4-ROM Plug-n-Go supports all combinations of active ACL and SCO channels for both master and slave operation, as specified by the Bluetooth v2.0 + EDR specification.

9.1.2 Key Features of the HCI Stack: Extra Functionality

The firmware extends the standard Bluetooth functionality with the following features:

- Supports BlueCore Serial Protocol (BCSP), a proprietary, reliable alternative to the standard Bluetooth UART Host Transport
- Provides a set of approximately 50 manufacturer-specific HCI extension commands. This command set, called BlueCore Command (BCCMD), provides:
 - Access to the chip's general-purpose PIO port
 - The negotiated effective encryption key length on established Bluetooth links
 - Access to the firmware's random number generator
 - Controls to set the default and maximum transmit powers; these can help minimise interference between overlapping, fixed-location piconets
 - Dynamic UART configuration
 - Radio transmitter enable/disable. A simple command connects to a dedicated hardware switch that determines whether the radio can transmit.
- The firmware can read the voltage on a pair of the chip's external pins. This is normally used to build a battery monitor, using either VM or host code
- A block of BCCMD commands provides access to the chip's Persistent Store configuration database (PS). The database sets the device's Bluetooth address, Class of Device, radio (transmit class) configuration, SCO routing, LM, USB and DFU constants, etc.
- A UART break condition can be used in three ways:
 1. Presenting a UART break condition to the chip can force the chip to perform a hardware reboot
 2. Presenting a break condition at boot time can hold the chip in a low power state, preventing normal initialisation while the condition exists
 3. With BCSP, the firmware can be configured to send a break to the host before sending data. (This is normally used to wake the host from a Deep Sleep state.)
- The DFU standard has been extended with public/private key authentication, allowing manufacturers to control the firmware that can be loaded onto their Bluetooth modules
- A modified version of the DFU protocol allows firmware upgrade via the chip's UART
- A block of radio test or BIST commands allows direct control of the chip's radio. This aids the development of modules' radio designs, and can be used to support Bluetooth qualification.
- Virtual Machine (VM). The firmware provides the VM environment in which to run application-specific code. Although the VM is mainly used with BlueLab and RFCOMM builds (alternative firmware builds providing L2CAP, SDP and RFCOMM), the VM can be used with this build to perform simple tasks such as flashing LEDs via the chip's PIO port.
- Hardware low power modes: Shallow Sleep and Deep Sleep. The chip drops into modes that significantly reduce power consumption when the software goes idle.
- SCO channels are normally routed via HCI (over BCSP). However, up to three SCO channels can be routed over the chip's single PCM port (at the same time as routing any remaining SCO channels over HCI).

Note:

Always refer to the Firmware Release Note for the specific functionality of a particular build.

9.2 BlueCore RFCOMM Stack

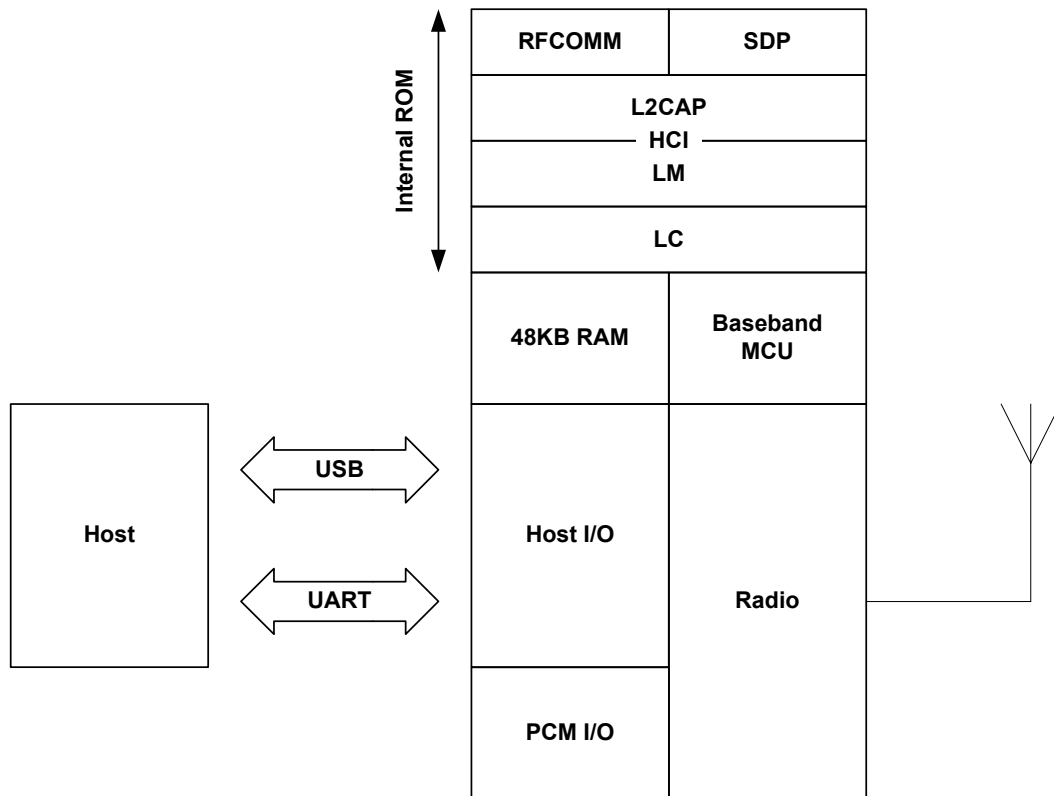


Figure 9.2: BlueCore RFCOMM Stack

In the version of the firmware, shown in Figure 9.2 the upper layers of the Bluetooth stack up to RFCOMM are run on-chip. This reduces host-side software and hardware requirements at the expense of some of the power and flexibility of the HCI only stack.

9.2.1 Key Features of the BlueCore4-ROM Plug-n-Go RFCOMM Stack

Interfaces to Host:

- RFCOMM, an RS-232 serial cable emulation protocol
- SDP, a service database look-up protocol

Connectivity:

- Maximum number of active slaves: three
- Maximum number of simultaneous active ACL connections: three
- Maximum number of simultaneous active SCO connections: three
- Data Rate: up to 350kbps⁽¹⁾

Security:

- Full support for all Bluetooth security features up to and including strong (128-bit) encryption.

Power Saving:

- Full support for all Bluetooth power saving modes (Park, Sniff and Hold).

Data Integrity:

- CQDDR increases the effective data rate in noisy environments.
- RSSI used to minimise interference to other radio devices using the ISM band.

⁽¹⁾ The data rate is with respect to BlueCore4-ROM Plug-n-Go with basic data rate packets.

9.3 BlueCore Virtual Machine Stack

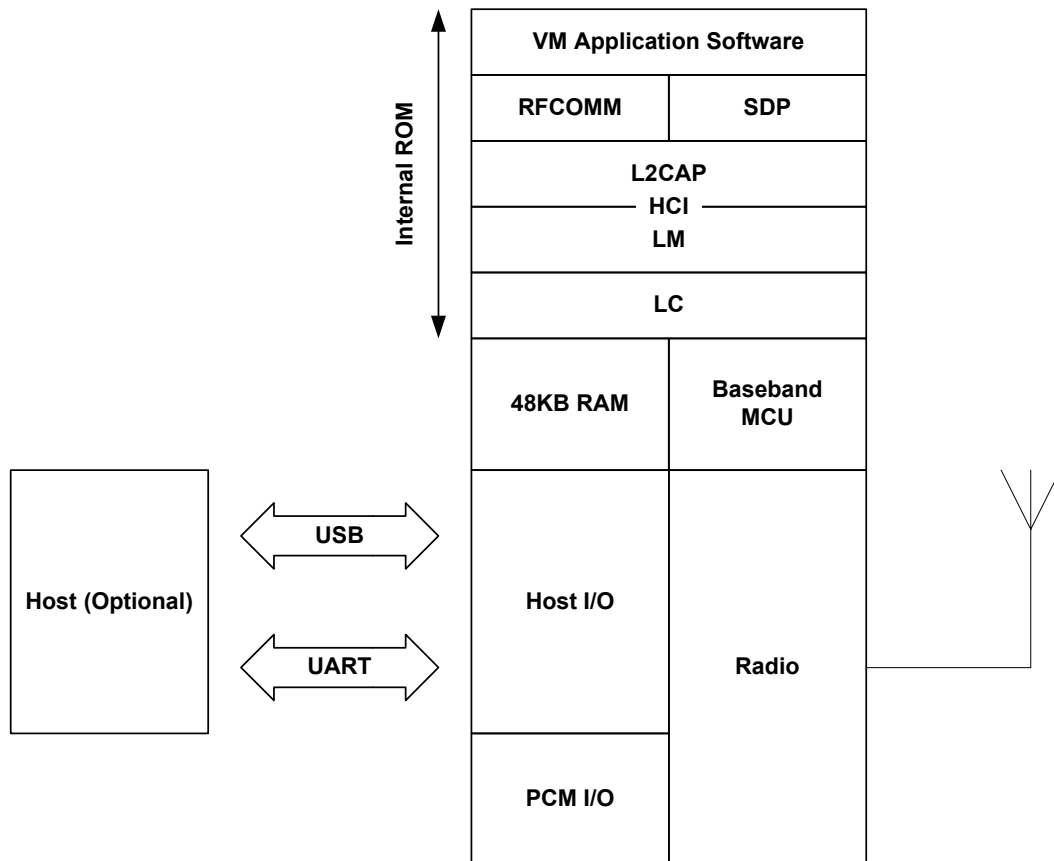


Figure 9.3: Virtual Machine

In Figure 9.3, this version of the stack firmware shown requires no host processor (but it can use a host processor for debugging, etc.). All software layers, including application software, run on the internal RISC processor in a protected user software execution environment known as a Virtual Machine (VM).

The user may write custom application code to run on the BlueCore VM using BlueLab SDK supplied with the BlueLab Multimedia and Casira development kits, available separately from CSR. This code will then execute alongside the main BlueCore firmware. The user is able to make calls to the BlueCore firmware for various operations.

The execution environment is structured so the user application does not adversely affect the main software routines, thus ensuring that the Bluetooth stack software component does not need re-qualification when the application is changed.

Using the VM and the BlueLab SDK the user is able to develop applications such as a cordless handsfree kit or other profiles without the requirement of a host controller. BlueLab is supplied with example code including a full implementation of the handsfree profile.

Note:

Sample applications to control PIO lines can also be written with BlueLab SDK and the VM for the HCI stack.

9.4 BlueCore HID Stack

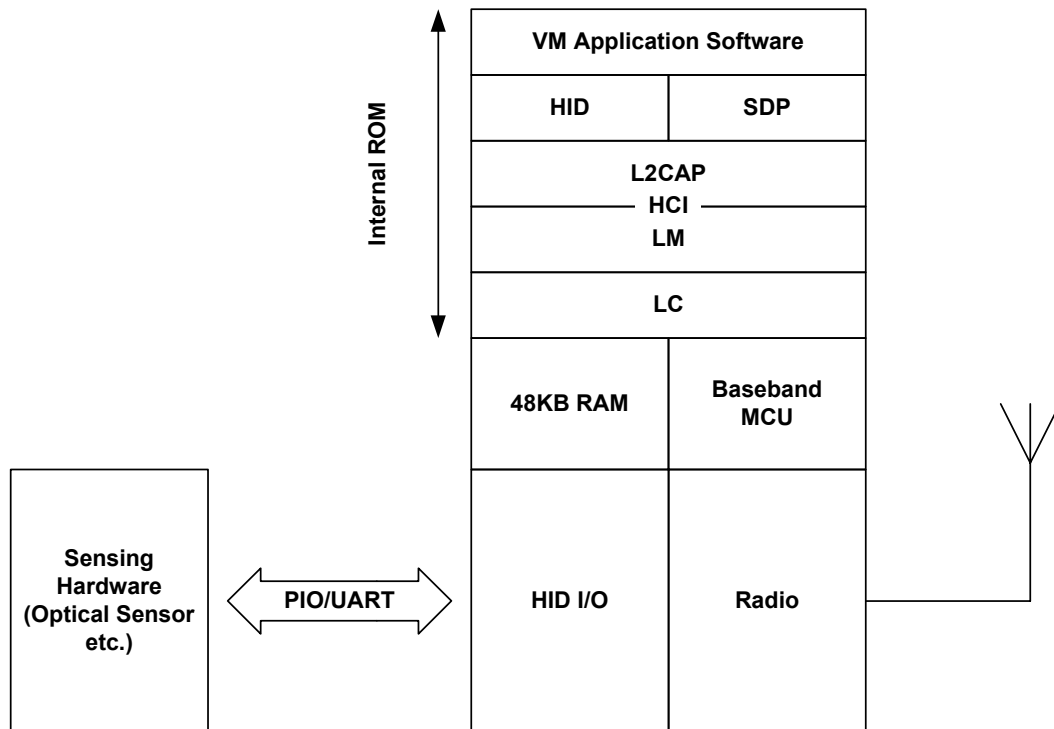


Figure 9.4: HID Stack

This version of the stack firmware requires no host processor. All software layers, including application software, run on the internal RISC microcontroller in a protected user software execution environment known as a virtual machine (VM).

The user may write custom application code to run on the BlueCore VM using BlueLab Professional SDK supplied with the BlueLab Professional and Casira development kits, available separately from CSR. This code will then execute alongside the main BlueCore firmware. The user is able to make calls to the BlueCore firmware for various operations.

The execution environment is structured so the user application does not adversely affect the main software routines, thus ensuring that the Bluetooth stack software component does not need re-qualification when the application is changed.

Using the VM and the BlueLab Professional SDK the user is able to develop Bluetooth HID devices such as an optical mouse or keyboard. The user is able to customise features such as power management and connect/reconnect behaviour.

The HID I/O component in the HID stack controls low latency data acquisition from external sensor hardware. With this component running in native code, it does not incur the overhead of the VM code interpreter. Supported external sensors include five mouse buttons, the Agilent ADNS-2030 optical sensor, quadrature scroll wheel, direct coupling to a keyboard matrix and a UART interface to custom hardware.

A reference schematic for implementing a three button, optical mouse with scroll wheel is available from CSR.

9.5 Host-Side Software

BlueCore4-ROM Plug-n-Go can be ordered with companion host-side software:

- BlueCore3-PC includes software for a full Windows 98/ME, Windows 2000 or Windows XP Bluetooth host-side stack together with IC hardware described in this document.
- BlueCore3-Mobile includes software for a full host-side stack designed for modern ARM chip-based mobile handsets together with IC hardware described in this document.

9.6 Device Firmware Upgrade

BlueCore4-ROM Plug-n-Go is supplied with boot loader software, which implements a Device Firmware Upgrade (DFU) capability. This allows new firmware to be uploaded to the Flash memory through BlueCore4-ROM Plug-n-Go UART or USB ports.

9.7 BCHS Software

BlueCore Embedded Host Software is designed to enable CSR customers to implement Bluetooth functionality into embedded products quickly, cheaply and with low risk.

BCHS is developed to work with CSR's family of BlueCore ICs. BCHS is intended for embedded products that have a host processor for running BCHS and the Bluetooth application, e.g., a mobile phone or a PDA. BCHS together with the BlueCore IC with embedded Bluetooth core stack (L2CAP, RFCOMM and SDP) is a complete Bluetooth system solution from RF to profiles.

BCHS includes most of the Bluetooth intelligence and gives the user a simple API. This makes it possible to develop a Bluetooth product without in-depth Bluetooth knowledge.

The BlueCore Embedded Host Software contains three elements:

- Example Drivers (BCSP and proxies)
- Bluetooth Profile Managers
- Example Applications

The profiles are qualified which makes the qualification of the final product very easy. BCHS is delivered with source code (ANSI C). BCHS also comes with example applications in ANSI C, which makes the process of writing the application easier.

9.8 Additional Software for Other Embedded Applications

When the upper layers of the Bluetooth protocol stack are run as firmware on BlueCore4-ROM Plug-n-Go, a UART software driver is supplied that presents the L2CAP, RFCOMM and Service Discovery Protocol (SDP) APIs to higher Bluetooth stack layers running on the host. The code is provided as C source or object code.

9.9 CSR Development Systems

CSR's BlueLab Multimedia and Casira development kits are available to allow the evaluation of the BlueCore4-ROM Plug-n-Go hardware and software, and as toolkits for developing on-chip and host software.

10 Device Terminal Descriptions

10.1 RF Ports

The BlueCore4-ROM Plug-n-Go RF_IN terminal can be configured as either a single-ended or differential input. The operational mode is determined by setting the PS Key PSKEY_TXRX_PIO_CONTROL (0x20).

10.1.1 RF Plug-n-Go

The 10 x 10mm 96-ball LFBGA package used on the BlueCore4-ROM Plug-n-Go device is an RF Plug-n-Go package, where the terminal RF_CONNECT forms an unbalanced output with a nominal 50Ω impedance. This terminal can be directly connected to an antenna requiring no impedance matching network as Figure 10.1 indicates.

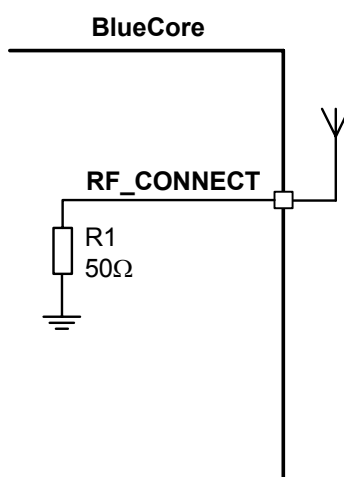


Figure 10.1: Circuit for RF_CONNECT

10.1.2 Single-Ended Input (RF_IN)

This is the single-ended RF input from the antenna. The input presents a complex impedance that requires a matching network between the terminal and the antenna. Starting from the substrate (chip) side, the input can be modelled as a lossy capacitor with the bond wire to the ball grid represented as a series inductance.

The terminal is DC blocked. The DC level must not exceed (VSS_RADIO - 0.3V to VDD_RADIO + 0.3V).

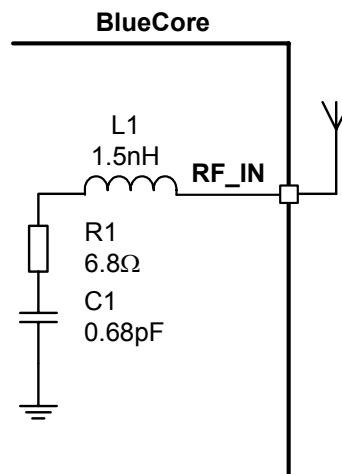


Figure 10.2: Circuit RF_IN

Note:

Both terminals must be externally DC biased to VDD_RADIO

10.2 External Reference Clock Input (XTAL_IN)

The BlueCore4-ROM Plug-n-Go RF local oscillator and internal digital clocks are derived from the reference clock at the BlueCore4-ROM Plug-n-Go XTAL_IN input. This reference may be either an external clock or from a crystal connected between XTAL_IN and XTAL_OUT. The crystal mode is described in section 10.3.

10.2.1 External Mode

BlueCore4-ROM Plug-n-Go can be configured to accept an external reference clock from another device (such as TCXO) at XTAL_IN by connecting XTAL_OUT to ground. The external clock can be either a digital level square wave or sinusoidal, and this may be directly coupled to XTAL_IN without the need for additional components. If the peaks of the reference clock are below VSS_ANA or above VDD_ANA, it must be driven through a DC blocking capacitor (approximately 33pF) connected to XTAL_IN. A digital level reference clock gives superior noise immunity, as the high slew rate clock edges have lower voltage to phase conversion.

The external clock signal should meet the specifications in Table 10.1:

| | Min | Typ | Max |
|--------------------------------|-------------|-------|----------------------------|
| Frequency ^(a) | 7.5MHz | 16MHz | 40MHz |
| Duty cycle | 20:80 | 50:50 | 80:20 |
| Edge Jitter (At Zero Crossing) | - | - | 15ps rms |
| Signal Level | 400mV pk-pk | - | VDD_ANA ^{(b) (c)} |

Table 10.1: External Clock Specifications

- (a) The frequency should be an integer multiple of 250kHz except for the CDMA/3G frequencies
- (b) VDD_ANA is 1.8V nominal
- (c) If the external clock is driven through a DC blocking capacitor, then maximum allowable amplitude is reduced from VDD_ANA to 800mV pk-pk.

10.2.2 XTAL_IN Impedance in External Mode

The impedance of the XTAL_IN will not change significantly between operating modes, typically 10fF. When transitioning from Deep Sleep to an active state a spike of up to 1pC may be measured. For this reason it is recommended that a buffered clock input be used.

10.2.3 Clock Timing Accuracy

As Figure 10.3 indicates, the 250ppm timing accuracy on the external clock is required 7ms after the assertion of the system clock request line. This is to guarantee that the firmware can maintain timing accuracy in accordance with the Bluetooth v2.0 + EDR specification. Radio activity may occur after 11ms, therefore, at this point the timing accuracy of the external clock source must be within 20ppm.

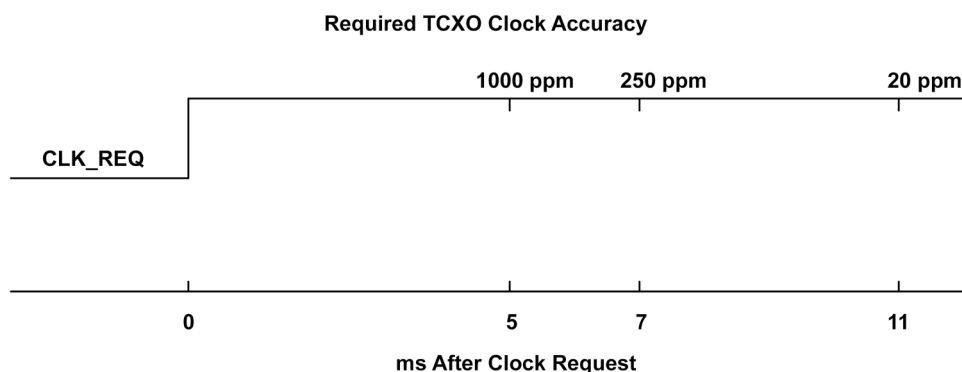


Figure 10.3: TCXO Clock Accuracy

10.2.4 Clock Start-Up Delay

BlueCore4-ROM Plug-n-Go hardware incorporates an automatic 5ms delay after the assertion of the system clock request signal before running firmware. This is suitable for most applications using an external clock source. However, there may be scenarios where the clock cannot be guaranteed to either exist or be stable after this period. Under these conditions, BlueCore4-ROM Plug-n-Go firmware provides a software function which will extend the system clock request signal by a period stored in PSKEY_CLOCK_STARTUP_DELAY. This value is set in milliseconds from 5-31ms.

This PS Key allows the designer to optimise a system where clock latencies may be longer than 5ms while still keeping the current consumption of BlueCore4-ROM Plug-n-Go as low as possible. BlueCore4-ROM Plug-n-Go will consume about 2mA of current for the duration of PSKEY_CLOCK_STARTUP_DELAY before activating the firmware.

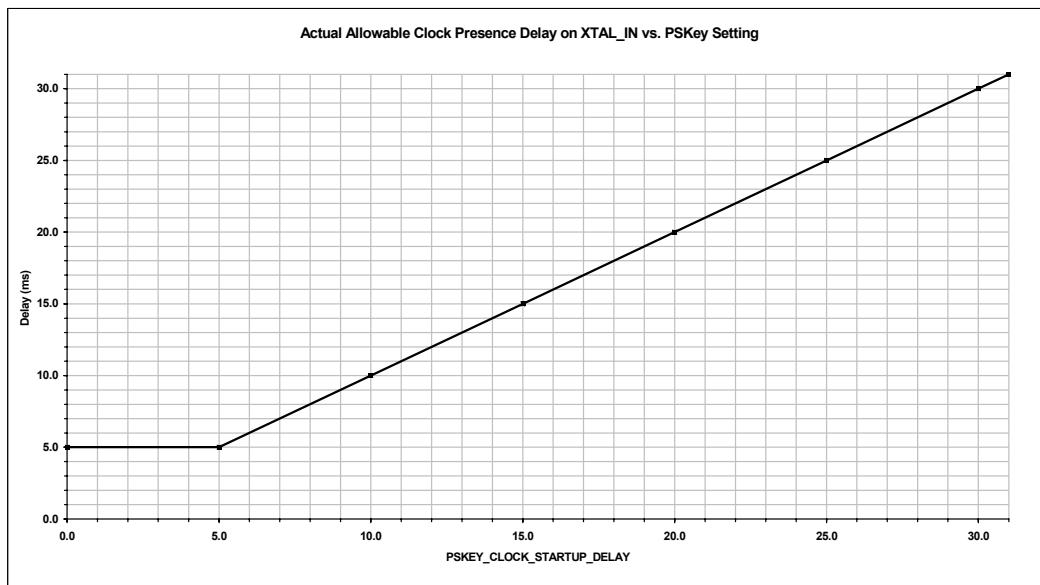


Figure 10.4: Actual Allowable Clock Presence Delay on XTAL_IN vs. PS Key Setting

10.2.5 Input Frequencies and PS Key Settings

BlueCore4-ROM Plug-n-Go should be configured to operate with the chosen reference frequency. This is accomplished by setting the PS Key PSKEY_ANA_FREQ (0x1fe) for all frequencies with an integer multiple of 250kHz. The input frequency default setting in BlueCore4-ROM Plug-n-Go is 26MHz.

The following CDMA/3G TCXO frequencies are also catered for: 7.68, 14.4, 15.36, 16.2, 16.8, 19.2, 19.44, 19.68, 19.8 and 38.4MHz.

| Reference Crystal Frequency (MHz) | PSKEY_ANA_FREQ (0x1fe) (Units of 1kHz) |
|-----------------------------------|---|
| 7.68 | 7680 |
| 14.40 | 14400 |
| 15.36 | 15360 |
| 16.20 | 16200 |
| 16.80 | 16800 |
| 19.20 | 19200 |
| 19.44 | 19440 |
| 19.68 | 19680 |
| 19.80 | 19800 |
| 38.40 | 38400 |
| n x 250kHz | - |
| +26.00 Default | 26000 |

Table 10.2: PS Key Values for CDMA/3G Phone TCXO Frequencies

10.3 Crystal Oscillator (XTAL_IN, XTAL_OUT)

This section describes the crystal mode. See section 10.2 for the description of the external reference clock mode.

10.3.1 XTAL Mode

BlueCore4-ROM Plug-n-Go contains a crystal driver circuit. This operates with an external crystal and capacitors to form a Pierce oscillator.

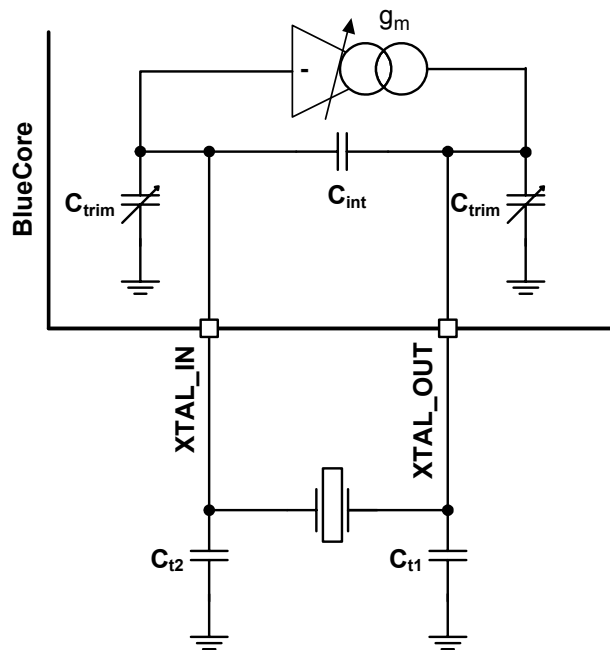


Figure 10.5: Crystal Driver Circuit

Figure 10.6 shows an electrical equivalent circuit for a crystal. The crystal appears inductive near its resonant frequency. It forms a resonant circuit with its load capacitors.

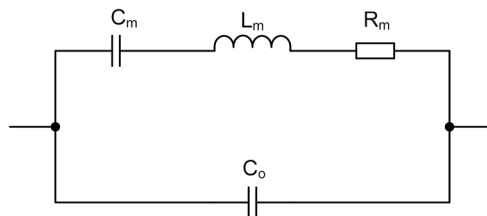


Figure 10.6: Crystal Equivalent Circuit

The resonant frequency may be trimmed with the crystal load capacitance. BlueCore4-ROM Plug-n-Go contains variable internal capacitors to provide a fine trim.

| | Min | Typ | Max |
|-------------------|------|-----------|-------|
| Frequency | 8MHz | 16MHz | 32MHz |
| Initial Tolerance | - | ±25ppm | - |
| Pullability | - | ±20ppm/pF | - |

Table 10.3: Crystal Specification

The BlueCore4-ROM Plug-n-Go driver circuit is a transconductance amplifier. A voltage at XTAL_IN generates a current at XTAL_OUT. The value of transconductance is variable and may be set for optimum performance.

10.3.2 Load Capacitance

For resonance at the correct frequency the crystal should be loaded with its specified load capacitance, which is defined for the crystal. This is the total capacitance across the crystal viewed from its terminals. BlueCore4-ROM Plug-n-Go provides some of this load with the capacitors C_{trim} and C_{int} . The remainder should be from the external capacitors labelled C_{t1} and C_{t2} . C_{t1} should be three times the value of C_{t2} for best noise performance. This maximises the signal swing, hence, slew rate at XTAL_IN (to which all on-chip clocks are referred). Crystal load capacitance, C_l is calculated with Equation 10.1:

$$C_l = C_{int} + \frac{C_{trim}}{2} + \frac{C_{t1} \cdot C_{t2}}{C_{t1} + C_{t2}}$$

Equation 10.1: Load Capacitance
Where:

C_{trim} = 3.4pF nominal (mid-range setting)

C_{int} = 1.5pF

Note:

C_{int} does not include the crystal internal self capacitance; it is the driver self capacitance.

10.3.3 Frequency Trim

BlueCore4-ROM Plug-n-Go enables frequency adjustments to be made. This feature is typically used to remove initial tolerance frequency errors associated with the crystal. Frequency trim is achieved by adjusting the crystal load capacitance with on-chip trim capacitors, C_{trim} . The value of C_{trim} is set by a 6-bit word in the PS Key PSKEY_ANA_FTRIM (0x1f6). Its value is calculated thus:

$$C_{trim} = 110fF \times PSKEY_ANA_FTRIM$$

Equation 10.2: Trim Capacitance

There are two C_{trim} capacitors, which are both connected to ground. When viewed from the crystal terminals, they appear in series so each least significant bit (LSB) increment of frequency trim presents a load across the crystal of 55fF.

The frequency trim is described by Equation 10.3.

$$\frac{\Delta(F_X)}{F_X} = \text{pullability} \times 55 \times 10^{-3} (\text{ppm/LSB})$$

Equation 10.3: Frequency Trim

Where F_X is the crystal frequency and pullability is a crystal parameter with units of ppm/pF. Total trim range is 63 times the value above.

If not specified, the pullability of a crystal may be calculated from its motional capacitance with Equation 10.4.

$$\frac{\partial(F_X)}{\partial(C_X)} = F_X \cdot \frac{C_m}{4(C_1 + C_0)^2}$$

Equation 10.4: Pullability

Where:

C_0 = Crystal self capacitance (shunt capacitance)

C_m = Crystal motional capacitance (series branch capacitance in crystal model). See Figure 10.6.

Note:

It is a Bluetooth requirement that the frequency is always within $\pm 20\text{ppm}$. The trim range should be sufficient to pull the crystal within $\pm 5\text{ppm}$ of the exact frequency. This leaves a margin of $\pm 15\text{ppm}$ for frequency drift with ageing and temperature. A crystal with an ageing and temperature drift specification of better than $\pm 15\text{ppm}$ is required.

10.3.4 Transconductance Driver Model

The crystal and its load capacitors should be viewed as a transimpedance element, whereby a current applied to one terminal generates a voltage at the other. The transconductance amplifier in BlueCore4-ROM Plug-n-Go uses the voltage at its input, XTAL_IN, to generate a current at its output, XTAL_OUT. Therefore, the circuit will oscillate if the transconductance, transimpedance product is greater than unity. For sufficient oscillation amplitude, the product should be greater than three. The transconductance required for oscillation is defined by the relationship shown in Equation 10.5:

$$g_m > \frac{3(C_{t1} + C_{trim})(C_{t2} + C_{trim})}{(2\pi F_X)^2 R_m ((C_0 + C_{int})(C_{t1} + C_{t2} + 2C_{trim}) + (C_{t1} + C_{trim})(C_{t2} + C_{trim}))^2}$$

Equation 10.5: Transconductance Required for Oscillation

BlueCore4-ROM Plug-n-Go guarantees a transconductance value of at least 2mA/V at maximum drive level.

Notes:

More drive strength is required for higher frequency crystals, higher loss crystals (larger R_m) or higher capacitance loading.

Optimum drive level is attained when the level at XTAL_IN is approximately 1V pk-pk. The drive level is determined by the crystal driver transconductance, by setting the PS Key PSKEY_XTAL_LVL (0x241).

10.3.5 Negative Resistance Model

An alternative representation of the crystal and its load capacitors is a frequency dependent resistive element. The driver amplifier may be considered as a circuit that provides negative resistance. For oscillation, the value of the negative resistance must be greater than that of the crystal circuit equivalent resistance. Although the BlueCore4-ROM Plug-n-Go crystal driver circuit is based on a transimpedance amplifier, an equivalent negative resistance may be calculated for it with the following formula in Equation 10.6:

$$R_{neg} > \frac{3(C_{t1} + C_{trim})(C_{t2} + C_{trim})}{g_m (2\pi F_X)^2 (C_0 + C_{int})(C_{t1} + C_{t2} + 2C_{trim}) + (C_{t1} + C_{trim})(C_{t2} + C_{trim})^2}$$

Equation 10.6: Equivalent Negative Resistance

This formula shows the negative resistance of the BlueCore4-ROM Plug-n-Go driver as a function of its drive strength.

The value of the driver negative resistance may be easily measured by placing an additional resistance in series with the crystal. The maximum value of this resistor (oscillation occurs) is the equivalent negative resistance of the oscillator.

10.3.6 Crystal PS Key Settings

See tables in section 10.2.5.

10.3.7 Crystal Oscillator Characteristics

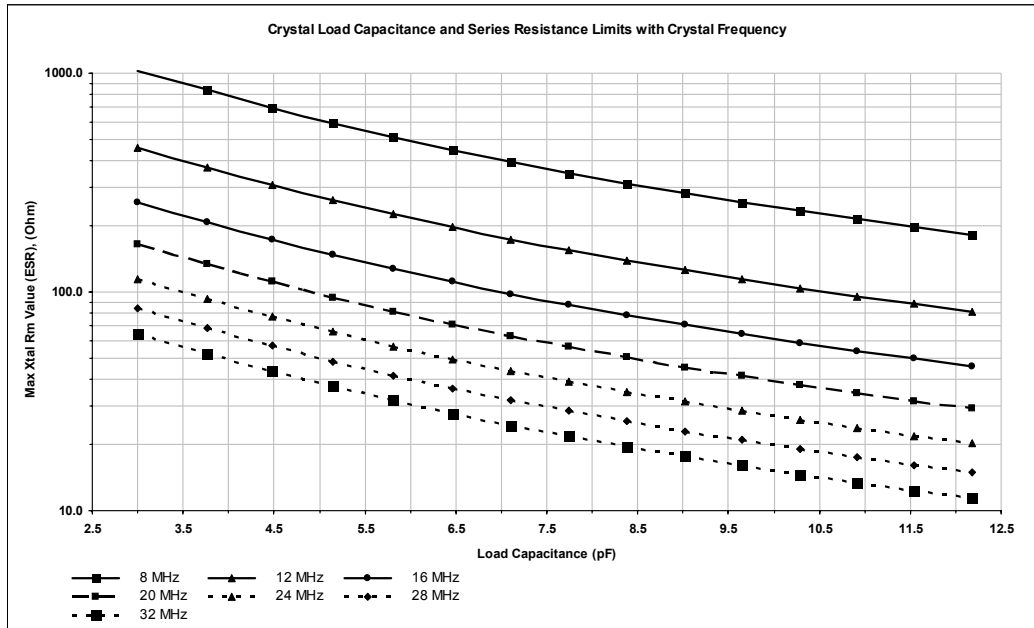


Figure 10.7: Crystal Load Capacitance and Series Resistance Limits with Crystal Frequency

Note:

Graph shows results for BlueCore4-ROM Plug-n-Go crystal driver at maximum drive level.

Conditions:

$C_{trim} = 3.4\text{pF}$ centre value

Crystal $C_0 = 2\text{pF}$

Transconductance setting = 2mA/V

Loop gain = 3

$C_{t1}/C_{t2} = 3$

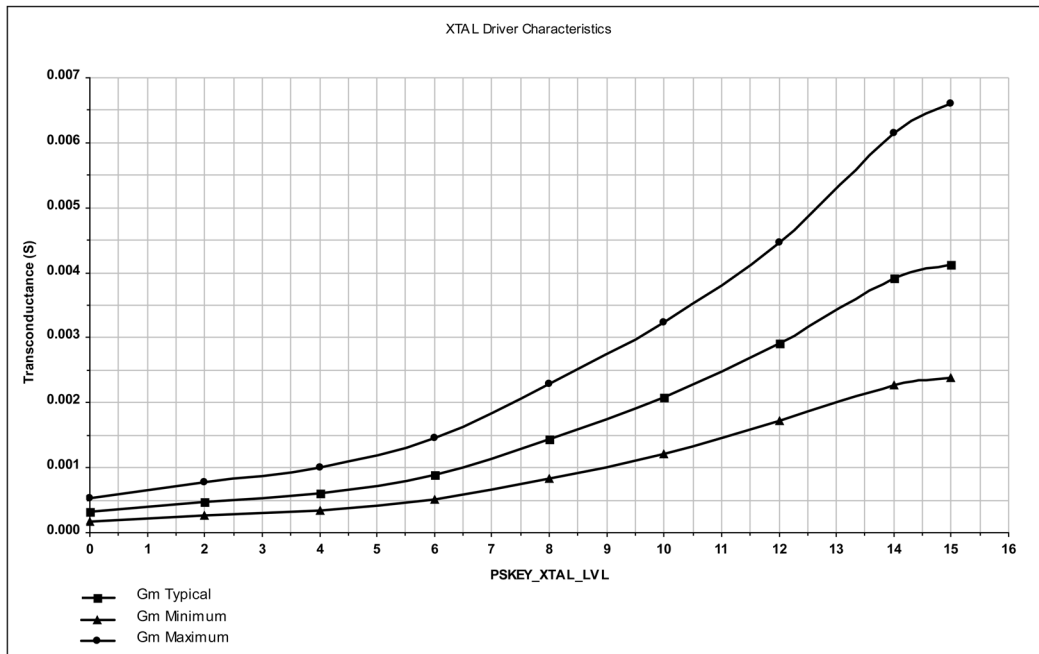


Figure 10.8: Crystal Driver Transconductance vs. Driver Level Register Setting

Note:

Drive level is set by PS Key PSKEY_XTAL_LVL (0x241).

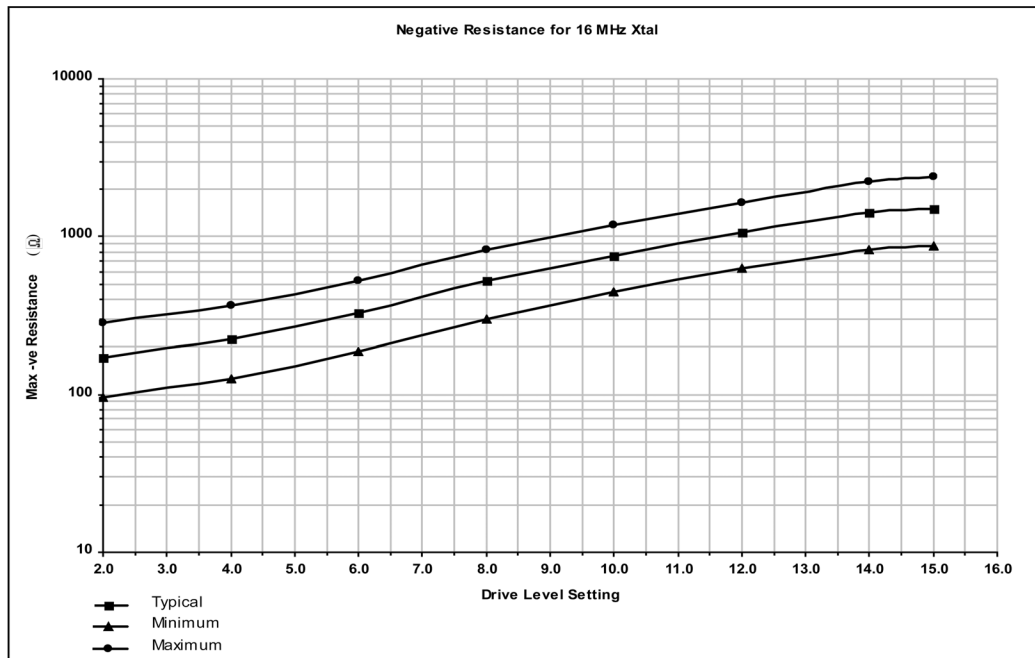


Figure 10.9: Crystal Driver Negative Resistance as a Function of Drive Level Setting

Crystal parameters:

Crystal frequency 16MHz (refer to your software build release note for supported frequencies).

Crystal $C_0 = 0.75\text{pF}$

Circuit parameters:

$C_{\text{trim}} = 8\text{pF}$, maximum value

$C_{t1}, C_{t2} = 5\text{pF}$ (3.9pF plus 1.1 pF stray)

(Crystal total load capacitance 8.5pF)

Note:

This is for a specific crystal and load capacitance.

10.4 UART Interface

BlueCore4-ROM Plug-n-Go UART interface provides a simple mechanism for communicating with other serial devices using the RS232 protocol.⁽¹⁾

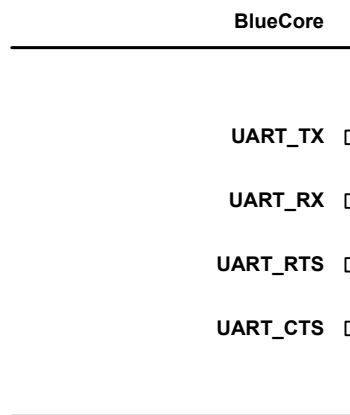


Figure 10.10: Universal Asynchronous Receiver

Four signals are used to implement the UART function, as shown in Figure 10.10. When BlueCore4-ROM Plug-n-Go is connected to another digital device, UART_RX and UART_TX transfer data between the two devices. The remaining two signals, UART_CTS and UART_RTS, can be used to implement RS232 hardware flow control where both are active low indicators. All UART connections are implemented using CMOS technology and have signalling levels of 0V and VDD_USB.

UART configuration parameters, such as baud rate and packet format, are set using BlueCore4-ROM Plug-n-Go software.

Note:

In order to communicate with the UART at its maximum data rate using a standard PC, an accelerated serial port adapter card is required for the PC.

| Parameter | | Possible Values |
|---------------------|---------|-------------------------------|
| Baud Rate | Minimum | 1200 baud ($\leq 2\%$ Error) |
| | Maximum | 9600 baud ($\leq 1\%$ Error) |
| Flow Control | | RTS/CTS or None |
| Parity | | None, Odd or Even |
| Number of Stop Bits | | 1 or 2 |
| Bits per Channel | | 8 |

Table 10.4: Possible UART Settings

⁽¹⁾ Uses RS232 protocol, but voltage levels are 0V to VDD_USB (requires external RS232 transceiver chip).

The UART interface is capable of resetting BlueCore4-ROM Plug-n-Go upon reception of a break signal. A break is identified by a continuous logic low (0V) on the UART_RX terminal, as shown in Figure 10.11. If t_{BRK} is longer than the value, defined by the PS Key PSKEY_HOST_IO_UART_RESET_TIMEOUT, (0x1a4), a reset will occur. This feature allows a host to initialise the system to a known state. Also, BlueCore4-ROM Plug-n-Go can emit a break character that may be used to wake the host.

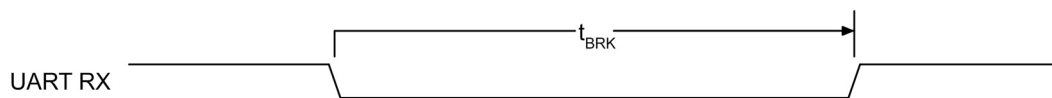


Figure 10.11: Break Signal

Note:

The DFU boot loader must be loaded into the Flash device before the UART or USB interfaces can be used. This initial flash programming can be done via the SPI.

Table 10.5 shows a list of commonly used baud rates and their associated values for the PS Key PSKEY_UART_BAUD_RATE (0x204). There is no requirement to use these standard values. Any baud rate within the supported range can be set in the PS Key according to the formula in Equation 10.7.

$$\text{BaudRate} = \frac{\text{PSKEY_UART_BAUD_RATE}}{0.004096}$$

Equation 10.7: Baud Rate

| Baud Rate | Persistent Store Value | | Error |
|-----------|------------------------|-------|--------|
| | Hex | Dec | |
| 1200 | 0x0005 | 5 | 1.73% |
| 2400 | 0x000a | 10 | 1.73% |
| 4800 | 0x0014 | 20 | 1.73% |
| 9600 | 0x0027 | 39 | -0.82% |
| 19200 | 0x004f | 79 | 0.45% |
| 38400 | 0x009d | 157 | -0.18% |
| 57600 | 0x00ec | 236 | 0.03% |
| 76800 | 0x013b | 315 | 0.14% |
| 115200 | 0x01d8 | 472 | 0.03% |
| 230400 | 0x03b0 | 944 | 0.03% |
| 460800 | 0x075f | 1887 | -0.02% |
| 921600 | 0x0ebf | 3775 | 0.00% |
| 1382400 | 0x161e | 5662 | -0.01% |
| 1843200 | 0x1d7e | 7550 | 0.00% |
| 2764800 | 0x2c3d | 11325 | 0.00% |

Table 10.5: Standard Baud Rates

10.4.1 UART Bypass

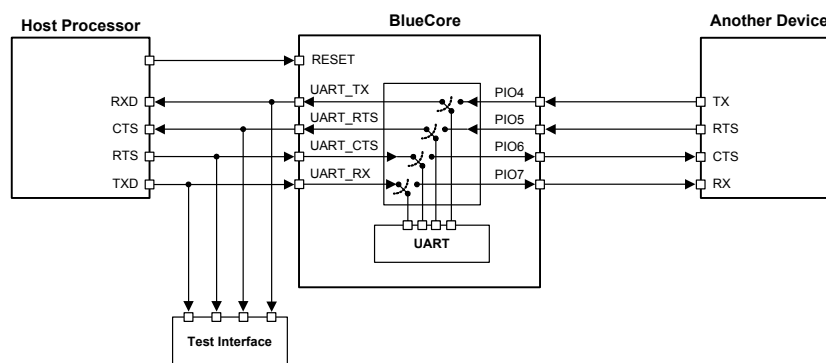


Figure 10.12: UART Bypass Architecture

10.4.2 UART Configuration While RESET is Active

The UART interface for BlueCore4-ROM Plug-n-Go while the chip is being held in reset is tri-state. This will allow the user to daisy chain devices onto the physical UART bus. The constraint on this method is that any devices connected to this bus must tri-state when BlueCore4-ROM Plug-n-Go reset is de-asserted and the firmware begins to run.

10.4.3 UART Bypass Mode

Alternatively, for devices that do not tri-state the UART bus, the UART bypass mode on BlueCore4-ROM Plug-n-Go can be used. The default state of BlueCore4-ROM Plug-n-Go after reset is de-asserted; this is for the host UART bus to be connected to the BlueCore4-ROM Plug-n-Go UART, thereby allowing communication to BlueCore4-ROM Plug-n-Go via the UART. All UART bypass mode connections are implemented using CMOS technology and have signalling levels of 0V and VDD_PADS.⁽¹⁾

In order to apply the UART bypass mode, a BCCMD command will be issued to BlueCore4-ROM Plug-n-Go. Upon this issue, it will switch the bypass to PIO[7:4] as Figure 10.12 indicates. Once the bypass mode has been invoked, BlueCore4-ROM Plug-n-Go will enter the Deep Sleep state indefinitely.

In order to re-establish communication with BlueCore4-ROM Plug-n-Go, the chip must be reset so that the default configuration takes effect.

It is important for the host to ensure a clean Bluetooth disconnection of any active links before the bypass mode is invoked. Therefore, it is not possible to have active Bluetooth links while operating the bypass mode.

10.4.4 Current Consumption in UART Bypass Mode

The current consumption for a device in UART bypass mode is equal to the values quoted for a device in standby mode.

⁽¹⁾ The range of the signalling level for the standard UART described in section 10.4 and the UART bypass may differ between CSR BlueCore devices, as the power supply configurations are chip dependent. For BlueCore4-ROM Plug-n-Go, the standard UART is supplied by VDD_USB, so has signalling levels of 0V and VDD_USB. Whereas in the UART bypass mode, the signals appear on PIO[4:7] which are supplied by VDD_PADS, therefore the signalling levels are 0V and VDD_PADS.

10.5 USB Interface

BlueCore4-ROM Plug-n-Go devices contain a full speed (12Mbps/s) USB interface that is capable of driving a USB cable directly. No external USB transceiver is required. The device operates as a USB peripheral, responding to requests from a master host controller such as a PC. Both the OHCI and the UHCI standards are supported. The set of USB endpoints implemented can behave as specified in the USB section of the Bluetooth specification v2.0+EDR or alternatively can appear as a set of endpoints appropriate to USB audio devices such as speakers.

As USB is a master/slave oriented system (in common with other USB peripherals), BlueCore4-ROM Plug-n-Go only supports USB Slave operation.

10.5.1 USB Data Connections

The USB data lines emerge as pins USB_DP and USB_DN. These terminals are connected to the internal USB I/O buffers of the BlueCore4-ROM Plug-n-Go, therefore, have a low output impedance. To match the connection to the characteristic impedance of the USB cable, resistors must be placed in series with USB_DP/USB_DN and the cable.

10.5.2 USB Pull-Up Resistor

BlueCore4-ROM Plug-n-Go features an internal USB pull-up resistor. This pulls the USB_DP pin weakly high when BlueCore4-ROM Plug-n-Go is ready to enumerate. It signals to the PC that it is a full speed (12Mbit/s) USB device.

The USB internal pull-up is implemented as a current source, and is compliant with section 7.1.5 of the USB specification v1.2. The internal pull-up pulls USB_DP high to at least 2.8V when loaded with a $15k\Omega \pm 5\%$ pull-down resistor (in the hub/host) when $VDD_PADS=3.1V$. This presents a Thevenin resistance to the host of at least 900Ω . Alternatively, an external $1.5k\Omega$ pull-up resistor can be placed between a PIO line and D+ on the USB cable. The firmware must be alerted to which mode is used by setting PS Key PSKEY_USB_PIO_PULLUP appropriately. The default setting uses the internal pull-up resistor.

10.5.3 Power Supply

The USB specification dictates that the minimum output high voltage for USB data lines is 2.8V. To safely meet the USB specification, the voltage on the VDD_USB supply terminals must be an absolute minimum of 3.1V. CSR recommends 3.3V for optimal USB signal quality.

10.5.4 Self-Powered Mode

In self-powered mode, the circuit is powered from its own power supply and not from the VBUS (5V) line of the USB cable. It draws only a small leakage current (below 0.5mA) from VBUS on the USB cable. This is the easier mode for which to design, as the design is not limited by the power that can be drawn from the USB hub or root port. However, it requires that VBUS be connected to BlueCore4-ROM Plug-n-Go via a resistor network (R_{vb1} and R_{vb2}), so BlueCore4-ROM Plug-n-Go can detect when VBUS is powered up. BlueCore4-ROM Plug-n-Go will not pull USB_DP high when VBUS is off.

Self-powered USB designs (powered from a battery or PSU) must ensure that a PIO line is allocated for USB pull-up purposes. A 1.5K Ω 5% pull-up resistor between USB_DP and the selected PIO line should be fitted to the design. Failure to fit this resistor may result in the design failing to be USB compliant in self-powered mode. The internal pull-up in BlueCore is only suitable for bus-powered USB devices, e.g., dongles.

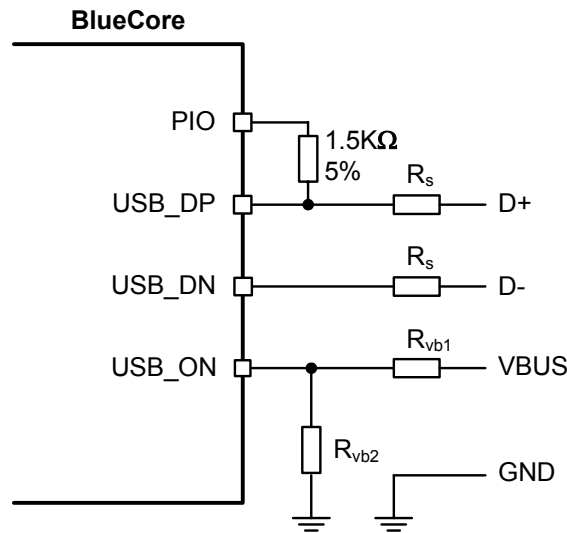


Figure 10.13: USB Connections for Self-Powered Mode

The terminal marked USB_ON can be any free PIO pin. The PIO pin selected must be registered by setting PSKEY_USB_PIO_VBUS to the corresponding pin number.

Note:

USB_ON is shared with BlueCore4-ROM Plug-n-Go PIO terminals.

| Identifier | Value | Function |
|------------|---------------------|---------------------------------|
| R_s | 27 Ω nominal | Impedance matching to USB cable |
| R_{vb1} | 22k Ω 5% | VBUS ON sense divider |
| R_{vb2} | 47k Ω 5% | VBUS ON sense divider |

Table 10.6: USB Interface Component Values

10.5.5 Bus-Powered Mode

In bus-powered mode, the application circuit draws its current from the 5V VBUS supply on the USB cable. BlueCore4-ROM Plug-n-Go negotiates with the PC during the USB enumeration stage about how much current it is allowed to consume.

For Class 2 Bluetooth applications, CSR recommends that the regulator used to derive 3.3V from VBUS is rated at 100mA average current and should be able to handle peaks of 120mA without foldback or limiting. In bus-powered mode, BlueCore4-ROM Plug-n-Go requests 100mA during enumeration.

For Class 1 Bluetooth applications, the USB power descriptor should be altered to reflect the amount of power required. This is accomplished by setting the PS Key PSKEY_USB_MAX_POWER (0x2c6). This is higher than for a Class 2 application due to the extra current drawn by the Transmit RF PA.

When selecting a regulator, be aware that VBUS may go as low as 4.4V. The inrush current (when charging reservoir and supply decoupling capacitors) is limited by the USB specification. See USB Specification v1.1, section 7.2.4.1. Some applications may require soft start circuitry to limit inrush current if more than 10 μ F is present between VBUS and GND.

The 5V VBUS line emerging from a PC is often electrically noisy. As well as regulation down to 3.3V and 1.8V, applications should include careful filtering of the 5V line to attenuate noise that is above the voltage regulator bandwidth. Excessive noise on the 1.8V supply to the analogue supply pins of BlueCore4-ROM Plug-n-Go will result in reduced receive sensitivity and a distorted RF transmit signal.

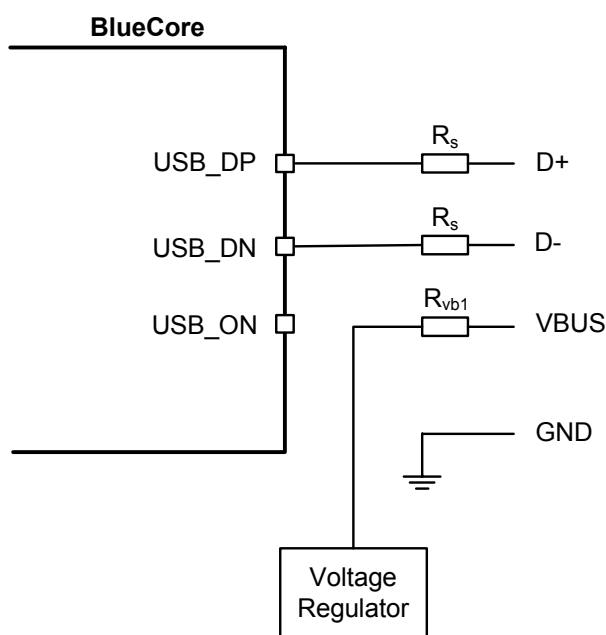


Figure 10.14: USB Connections for Bus-Powered Mode

10.5.6 Suspend Current

All USB devices must permit the USB controller to place them in a USB suspend mode. While in USB Suspend, bus-powered devices must not draw more than 0.5mA from USB VBUS (self-powered devices may draw more than 0.5mA from their own supply). This current draw requirement prevents operation of the radio by bus-powered devices during USB Suspend.

The voltage regulator circuit itself should draw only a small quiescent current (typically less than 100µA) to ensure adherence to the suspend current requirement of the USB specification. This is not normally a problem with modern regulators. Ensure that external LEDs and/or amplifiers can be turned off by BlueCore4-ROM Plug-n-Go. The entire circuit must be able to enter the suspend mode. Refer to separate CSR documentation for more details on USB Suspend.

10.5.7 Detach and Wake_Up Signalling

BlueCore4-ROM Plug-n-Go can provide out-of-band signalling to a host controller by using the control lines called USB_DETACH and USB_WAKE_UP. These are outside the USB specification (no wires exist for them inside the USB cable), but can be useful when embedding BlueCore4-ROM Plug-n-Go into a circuit where no external USB is visible to the user. Both control lines are shared with PIO pins and can be assigned to any PIO pin by setting the PS Keys PSKEY_USB_PIO_DETACH and PSKEY_USB_PIO_WAKEUP to the selected PIO number.

USB_DETACH is an input which, when asserted high, causes BlueCore4-ROM Plug-n-Go to put USB_DP and USB_DN in a high impedance state and turns off the pull-up resistor on DP. This detaches the device from the bus and is logically equivalent to unplugging the device. When USB_DETACH is taken low, BlueCore4-ROM Plug-n-Go will connect back to USB and await enumeration by the USB host.

USB_WAKE_UP is an active high output (used only when USB_DETACH is active) to wake up the host and allow USB communication to recommence. It replaces the function of the software USB WAKE_UP message (which runs over the USB cable) and cannot be sent while BlueCore4-ROM Plug-n-Go is effectively disconnected from the bus.

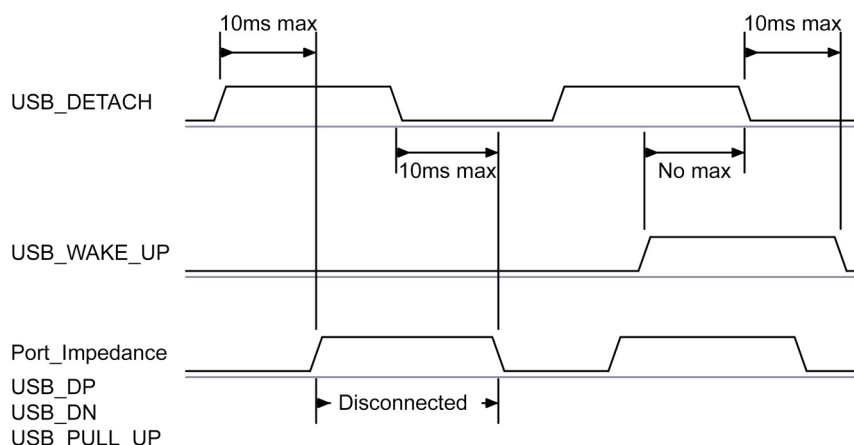


Figure 10.15: USB_DETACH and USB_WAKE_UP Signal

10.5.8 USB Driver

A USB Bluetooth device driver is required to provide a software interface between BlueCore4-ROM Plug-n-Go and Bluetooth software running on the host computer. Suitable drivers are available from <http://www.csrsupport.com>.

10.5.9 USB 1.1 Compliance

BlueCore4-ROM Plug-n-Go is qualified to the USB Specification v1.1, details of which are available from www.usb.org. The specification contains valuable information on aspects such as PCB track impedance, supply inrush current and product labelling.

Although BlueCore4-ROM Plug-n-Go meets the USB specification, CSR cannot guarantee that an application circuit designed around the chip is USB compliant. The choice of application circuit, component choice and PCB layout all affect USB signal quality and electrical characteristics. The information in this document is intended as a guide and should be read in association with the USB specification, with particular attention being given to Chapter 7.

Independent USB qualification must be sought before an application is deemed USB compliant and can bear the USB logo. Such qualification can be obtained from a USB plugfest or from an independent USB test house.

Terminals USB_DP and USB_DN adhere to the USB specification v2.0 (Chapter 7) electrical requirements.

10.5.10 USB 2.0 Compatibility

BlueCore4-ROM Plug-n-Go is compatible with USB v2.0 host controllers; under these circumstances the two ends agree the mutually acceptable rate of 12Mbps/s according to the USB v2.0 specification.

10.6 Serial Peripheral Interface

BlueCore4-ROM Plug-n-Go uses 16-bit data and 16-bit address serial peripheral interface, where transactions may occur when the internal processor is running or is stopped. This section details the considerations required when interfacing to BlueCore4-ROM Plug-n-Go via the four dedicated serial peripheral interface terminals. Data may be written or read one word at a time or the auto increment feature may be used to access blocks.

10.6.1 Instruction Cycle

The BlueCore4-ROM Plug-n-Go is the slave and receives commands on SPI_MOSI and outputs data on SPI_MISO. Table 10.7 shows the instruction cycle for an SPI transaction.

| | | |
|---|--------------------------|---|
| 1 | Reset the SPI interface | Hold SPI_CSB high for two SPI_CLK cycles |
| 2 | Write the command word | Take SPI_CSB low and clock in the 8 bit command |
| 3 | Write the address | Clock in the 16-bit address word |
| 4 | Write or read data words | Clock in or out 16-bit data word(s) |
| 5 | Termination | Take SPI_CSB high |

Table 10.7: Instruction Cycle for an SPI Transaction

With the exception of reset, SPI_CSB must be held low during the transaction. Data on SPI_MOSI is clocked into the BlueCore4-ROM Plug-n-Go on the rising edge of the clock line SPI_CLK. When reading, BlueCore4-ROM Plug-n-Go will reply to the master on SPI_MISO with the data changing on the falling edge of the SPI_CLK. The master provides the clock on SPI_CLK. The transaction is terminated by taking SPI_CSB high.

Sending a command word and the address of a register for every time it is to be read or written is a significant overhead, especially when large amounts of data are to be transferred. To overcome this BlueCore4-ROM Plug-n-Go offers increased data transfer efficiency via an auto increment operation. To invoke auto increment, SPI_CSB is kept low, which auto increments the address, while providing an extra 16 clock cycles for each extra word to be written or read.

10.6.2 Writing to BlueCore4-ROM Plug-n-Go

To write to BlueCore4-ROM Plug-n-Go, the 8-bit write command (00000010) is sent first (C[7:0]) followed by a 16-bit address (A[15:0]). The next 16-bits (D[15:0]) clocked in on SPI_MOSI are written to the location set by the address (A). Thereafter for each subsequent 16-bits clocked in, the address (A) is incremented and the data written to consecutive locations until the transaction terminates when SPI_CSB is taken high.

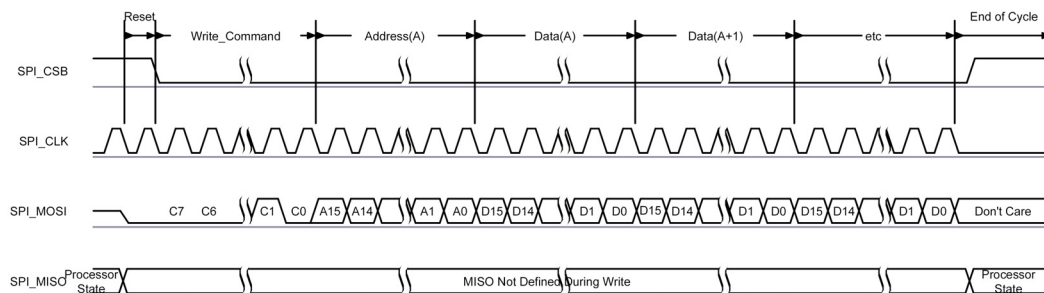


Figure 10.16: Write Operation

10.6.3 Reading from BlueCore4-ROM Plug-n-Go

Reading from BlueCore4-ROM Plug-n-Go is similar to writing to it. An 8-bit read command (00000011) is sent first (C[7:0]), followed by the address of the location to be read (A[15:0]). BlueCore4-ROM Plug-n-Go then outputs on SPI_MISO a check word during T[15:0] followed by the 16-bit contents of the addressed location during bits D[15:0].

The check word is composed of {command, address [15:8]}. The check word may be used to confirm a read operation to a memory location. This overcomes the problems encountered with typical serial peripheral interface slaves, whereby it is impossible to determine whether the data returned by a read operation is valid data or the result of the slave device not responding.

If SPI_CSB is kept low, data from consecutive locations is read out on SPI_MISO for each subsequent 16 clocks, until the transaction terminates when SPI_CSB is taken high.

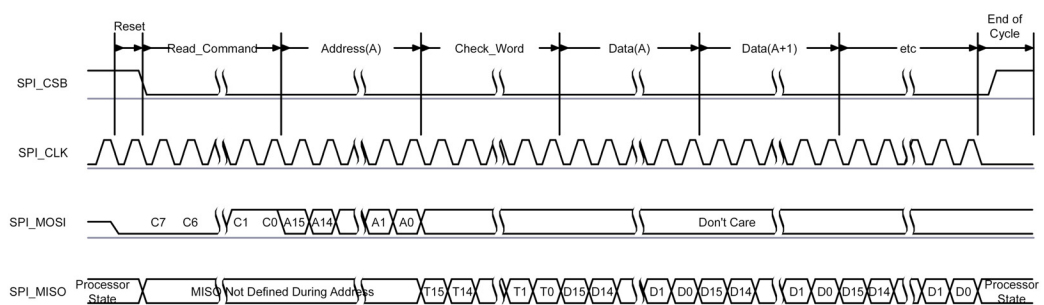


Figure 10.17: Read Operation

10.6.4 Multi-Slave Operation

BlueCore4-ROM Plug-n-Go should not be connected in a multi-slave arrangement by simple parallel connection of slave MISO lines. When BlueCore4-ROM Plug-n-Go is deselected (SPI_CSB = 1), the SPI_MISO line does not float. Instead, BlueCore4-ROM Plug-n-Go outputs 0 if the processor is running or 1 if it is stopped.

10.7 PCM CODEC Interface

Pulse Code Modulation (PCM) is a standard method used to digitise audio (particularly voice) for transmission over digital communication channels. Through its PCM interface, BlueCore4-ROM Plug-n-Go has hardware support for continual transmission and reception of PCM data, thus reducing processor overhead for wireless headset applications. BlueCore4-ROM Plug-n-Go offers a bi-directional digital audio interface that routes directly into the baseband layer of the on-chip firmware. It does not pass through the HCI protocol layer.

Hardware on BlueCore4-ROM Plug-n-Go allows the data to be sent to and received from a SCO connection. ⁽¹⁾

Up to three SCO connections can be supported by the PCM interface at any one time.

BlueCore4-ROM Plug-n-Go can operate as the PCM interface master generating an output clock of 128, 256 or 512kHz. When configured as PCM interface slave, it can operate with an input clock up to 2048kHz. BlueCore4-ROM Plug-n-Go is compatible with a variety of clock formats, including Long Frame Sync, Short Frame Sync and GCI timing environments.

It supports 13-bit or 16-bit linear, 8-bit μ -law or A-law companded sample formats at 8ksamples/s and can receive and transmit on any selection of three of the first four slots following PCM_SYNC. The PCM configuration options are enabled by setting the PS Key PS KEY_PCM_CONFIG32 (0x1b3).

BlueCore4-ROM Plug-n-Go interfaces directly to PCM audio devices including the following:

- Qualcomm MSM 3000 series and MSM 5000 series CDMA baseband devices
- OKI MSM7705 four channel A-law and μ -law CODEC
- Motorola MC145481 8-bit A-law and μ -law CODEC
- Motorola MC145483 13-bit linear CODEC
- STW 5093 and 5094 14-bit linear CODECs
- BlueCore4-ROM Plug-n-Go is also compatible with the Motorola SSI™ interface

⁽¹⁾ Subject to firmware support. Contact CSR for current status.

10.7.1 PCM Interface Master/Slave

When configured as the master of the PCM interface, BlueCore4-ROM Plug-n-Go generates PCM_CLK and PCM_SYNC.

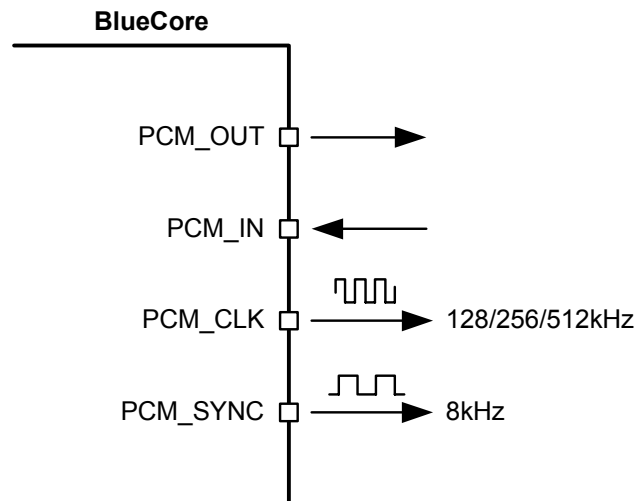


Figure 10.18: BlueCore4-ROM Plug-n-Go as PCM Interface Master

When configured as the Slave of the PCM interface, BlueCore4-ROM Plug-n-Go accepts PCM_CLK rates up to 2048kHz.

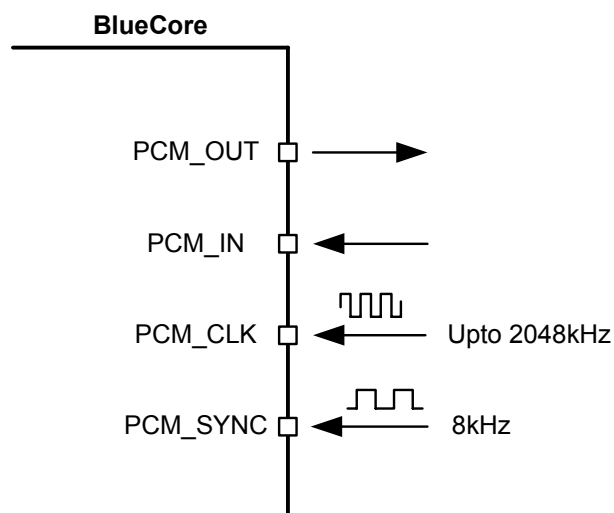


Figure 10.19: BlueCore4-ROM Plug-n-Go as PCM Interface Slave

10.7.2 Long Frame Sync

Long Frame Sync is the name given to a clocking format that controls the transfer of PCM data words or samples. In Long Frame Sync, the rising edge of PCM_SYNC indicates the start of the PCM word. When BlueCore4-ROM Plug-n-Go is configured as PCM master, generating PCM_SYNC and PCM_CLK, then PCM_SYNC is 8-bits long. When BlueCore4-ROM Plug-n-Go is configured as PCM Slave, PCM_SYNC may be from two consecutive falling edges of PCM_CLK to half the PCM_SYNC rate, i.e., 62.5µs long.

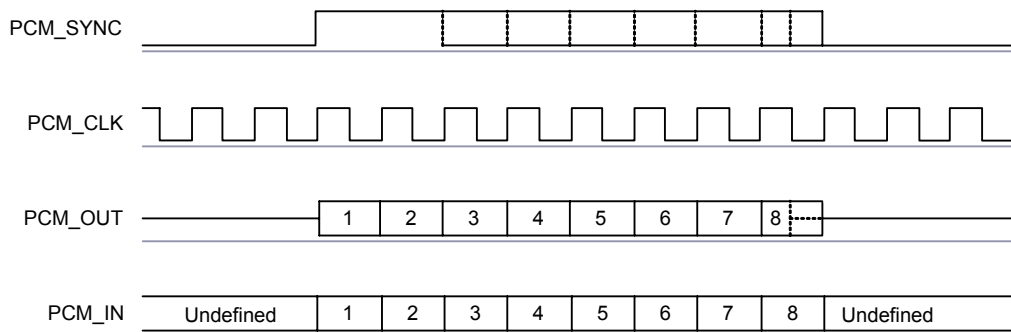


Figure 10.20: Long Frame Sync (Shown with 8-bit Companded Sample)

BlueCore4-ROM Plug-n-Go samples PCM_IN on the falling edge of PCM_CLK and transmits PCM_OUT on the rising edge. PCM_OUT may be configured to be high impedance on the falling edge of PCM_CLK in the LSB position or on the rising edge.

10.7.3 Short Frame Sync

In Short Frame Sync, the falling edge of PCM_SYNC indicates the start of the PCM word. PCM_SYNC is always one clock cycle long.

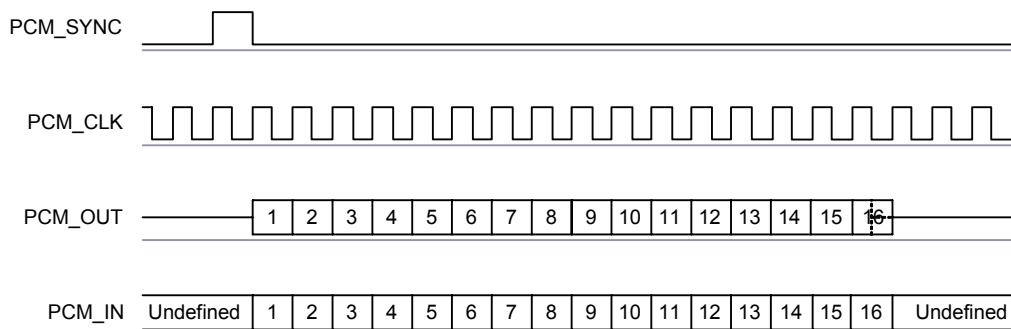


Figure 10.21: Short Frame Sync (Shown with 16-bit Sample)

As with Long Frame Sync, BlueCore4-ROM Plug-n-Go samples PCM_IN on the falling edge of PCM_CLK and transmits PCM_OUT on the rising edge. PCM_OUT may be configured to be high impedance on the falling edge of PCM_CLK in the LSB position or on the rising edge.

10.7.4 Multi-slot Operation

More than one SCO connection over the PCM interface is supported using multiple slots. Up to three SCO connections can be carried over any of the first four slots.

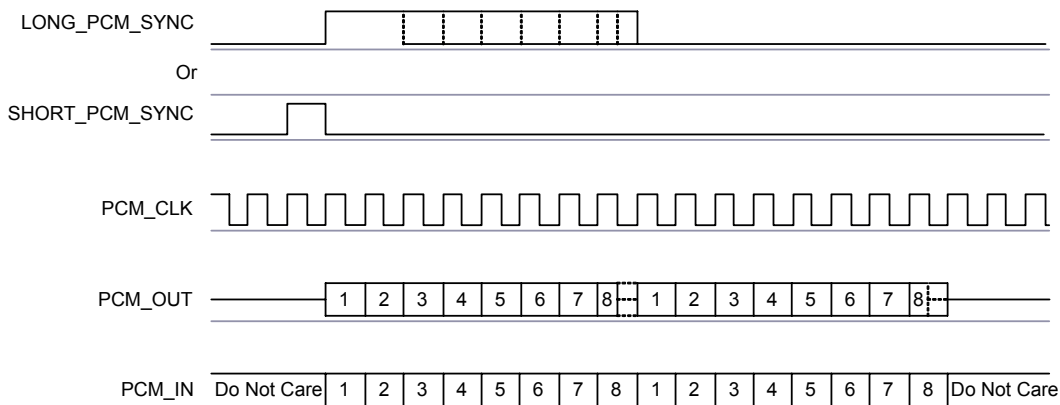


Figure 10.22: Multi-slot Operation with Two Slots and 8-bit Companded Samples

10.7.5 GCI Interface

BlueCore4-ROM Plug-n-Go is compatible with the General Circuit Interface (GCI), a standard synchronous 2B+D ISDN timing interface. The two 64Kbps B channels can be accessed when this mode is configured.

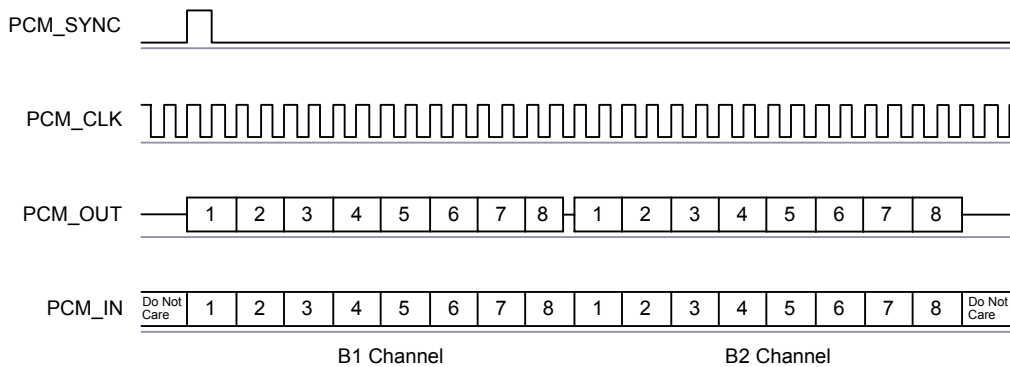


Figure 10.23: GCI Interface

The start of frame is indicated by the rising edge of PCM_SYNC and runs at 8kHz. With BlueCore4-ROM Plug-n-Go in Slave mode, the frequency of PCM_CLK can be up to 4.096MHz.

10.7.6 Slots and Sample Formats

BlueCore4-ROM Plug-n-Go can receive and transmit on any selection of the first four slots following each sync pulse. Slot durations can be either 8 or 16 clock cycles. Durations of 8 clock cycles may only be used with 8-bit sample formats. Durations of 16 clocks may be used with 8-bit, 13-bit or 16-bit sample formats.

BlueCore4-ROM Plug-n-Go supports 13-bit linear, 16-bit linear and 8-bit μ -law or A-law sample formats. The sample rate is 8ksamples/s. The bit order may be little or big endian. When 16-bit slots are used, the 3 or 8 unused bits in each slot may be filled with sign extension, padded with zeros or a programmable 3-bit audio attenuation compatible with some Motorola CODECs.

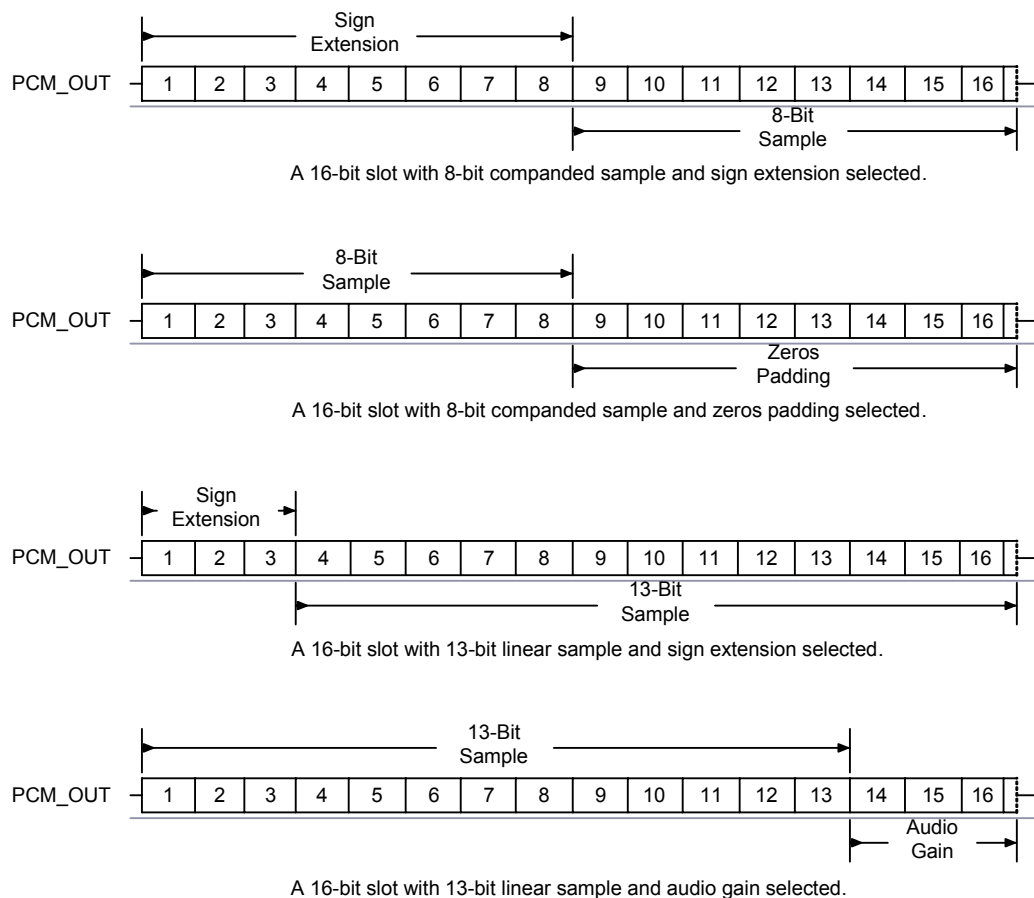


Figure 10.24: 16-Bit Slot Length and Sample Formats

10.7.7 Additional Features

BlueCore4-ROM Plug-n-Go has a mute facility that forces PCM_OUT to be 0. In master mode, PCM_SYNC may also be forced to 0 while keeping PCM_CLK running which some CODECS use to control power down.

10.7.8 PCM Timing Information

| Symbol | Parameter | | Min | Typ | Max | Unit |
|-------------------|--|---|-----|-----|-----|----------|
| f_{mclk} | PCM_CLK frequency | 4MHz DDS generation. Selection of frequency is programmable. See Table 10.10. | - | 128 | - | kHz |
| | | | | 256 | | |
| | | | | 512 | | |
| | | 48MHz DDS generation. Selection of frequency is programmable. See Table 10.11 and PCM_CLK and PCM_SYNC Generation on page 75. | 2.9 | | - | kHz |
| - | PCM_SYNC frequency | | - | 8 | | kHz |
| $t_{mclkh}^{(a)}$ | PCM_CLK high | 4MHz DDS generation | 980 | - | - | ns |
| $t_{mckl}^{(a)}$ | PCM_CLK low | 4MHz DDS generation | 730 | - | | ns |
| - | PCM_CLK jitter | 48MHz DDS generation | | | 21 | ns pk-pk |
| $t_{dmclksynch}$ | Delay time from PCM_CLK high to PCM_SYNC high | | - | - | 20 | ns |
| $t_{dmclkpout}$ | Delay time from PCM_CLK high to valid PCM_OUT | | - | - | 20 | ns |
| $t_{dmcklsyncl}$ | Delay time from PCM_CLK low to PCM_SYNC low (Long Frame Sync only) | | - | - | 20 | ns |
| $t_{dmckhsyncl}$ | Delay time from PCM_CLK high to PCM_SYNC low | | - | - | 20 | ns |
| $t_{dmcklpoutz}$ | Delay time from PCM_CLK low to PCM_OUT high impedance | | - | - | 20 | ns |
| $t_{dmckhpoutz}$ | Delay time from PCM_CLK high to PCM_OUT high impedance | | - | - | 20 | ns |
| $t_{supinckl}$ | Set-up time for PCM_IN valid to PCM_CLK low | | 30 | - | - | ns |
| $t_{hpinckl}$ | Hold time for PCM_CLK low to PCM_IN invalid | | 10 | - | - | ns |

Table 10.8: PCM Master Timing

(a) Assumes normal system clock operation. Figures will vary during low power modes, when system clock speeds are reduced.

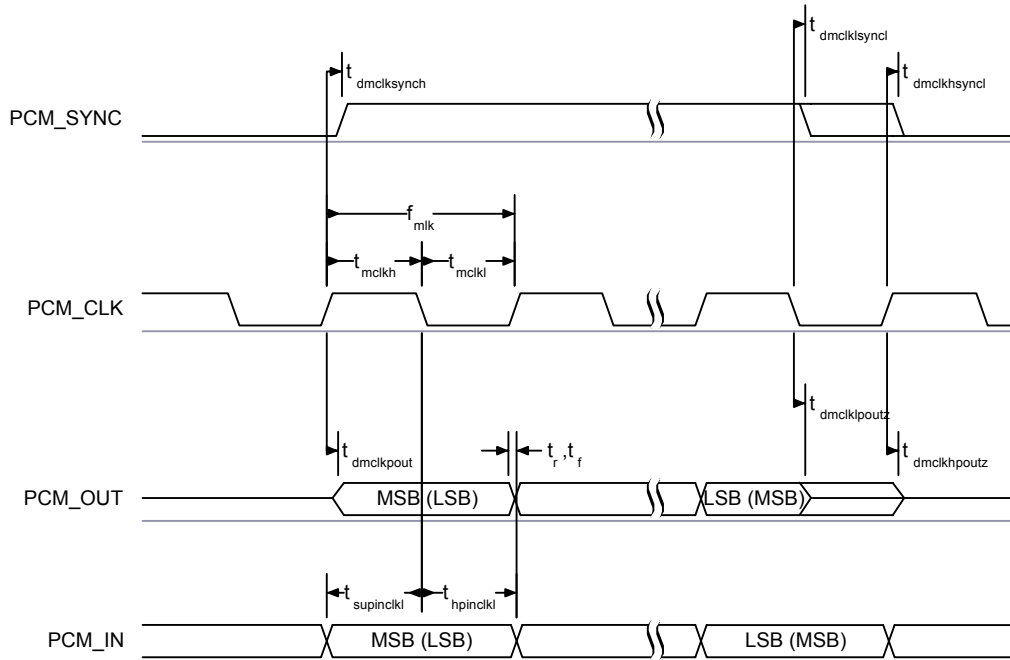


Figure 10.25: PCM Master Timing Long Frame Sync

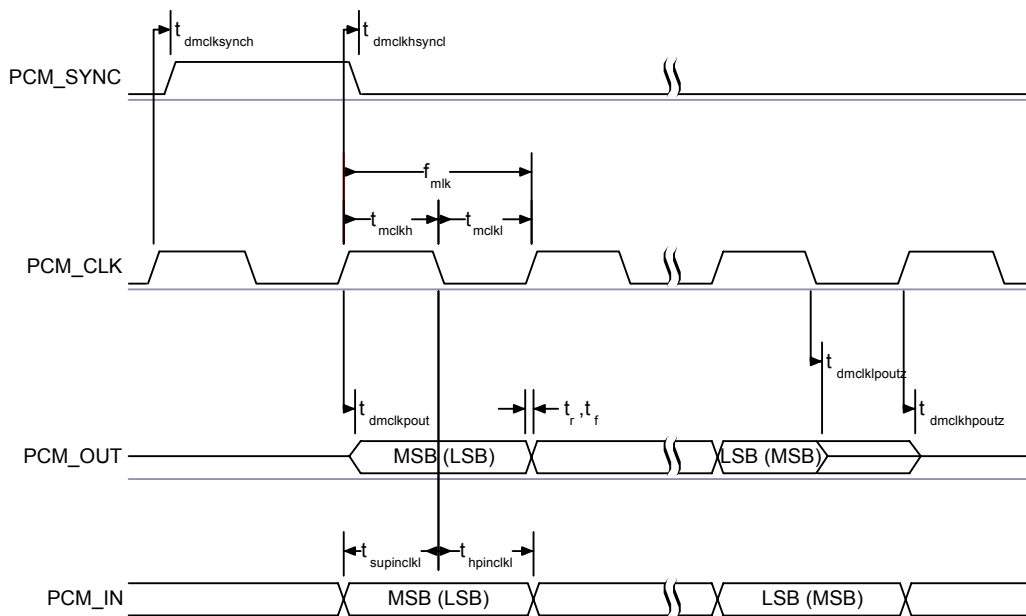


Figure 10.26: PCM Master Timing Short Frame Sync

| Symbol | Parameter | Min | Typ | Max | Unit |
|--------------------------|--|-----|-----|------|------|
| f_{sclk} | PCM clock frequency (Slave mode: input) | 64 | - | 2048 | kHz |
| f_{sclk} | PCM clock frequency (GCI mode) | 128 | - | 4096 | kHz |
| t_{sckl} | PCM_CLK low time | 200 | - | - | ns |
| t_{scklh} | PCM_CLK high time | 200 | - | - | ns |
| $t_{\text{hsclksynch}}$ | Hold time from PCM_CLK low to PCM_SYNC high | 30 | - | - | ns |
| $t_{\text{susclksynch}}$ | Set-up time for PCM_SYNC high to PCM_CLK low | 30 | - | - | ns |
| t_{dpout} | Delay time from PCM_SYNC or PCM_CLK whichever is later, to valid PCM_OUT data (Long Frame Sync only) | - | - | 20 | ns |
| $t_{\text{dsclkhout}}$ | Delay time from CLK high to PCM_OUT valid data | - | - | 20 | ns |
| t_{dpoutz} | Delay time from PCM_SYNC or PCM_CLK low, whichever is later, to PCM_OUT data line high impedance | - | - | 20 | ns |
| $t_{\text{supinsckl}}$ | Set-up time for PCM_IN valid to CLK low | 30 | - | - | ns |
| t_{hpinsckl} | Hold time for PCM_CLK low to PCM_IN invalid | 30 | - | - | ns |

Table 10.9: PCM Slave Timing

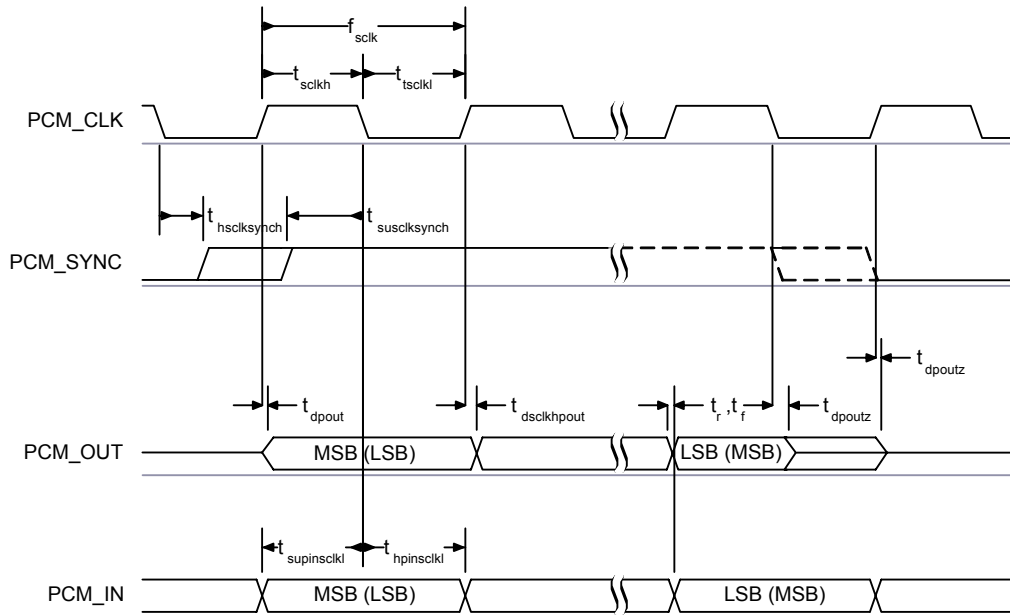


Figure 10.27: PCM Slave Timing Long Frame Sync

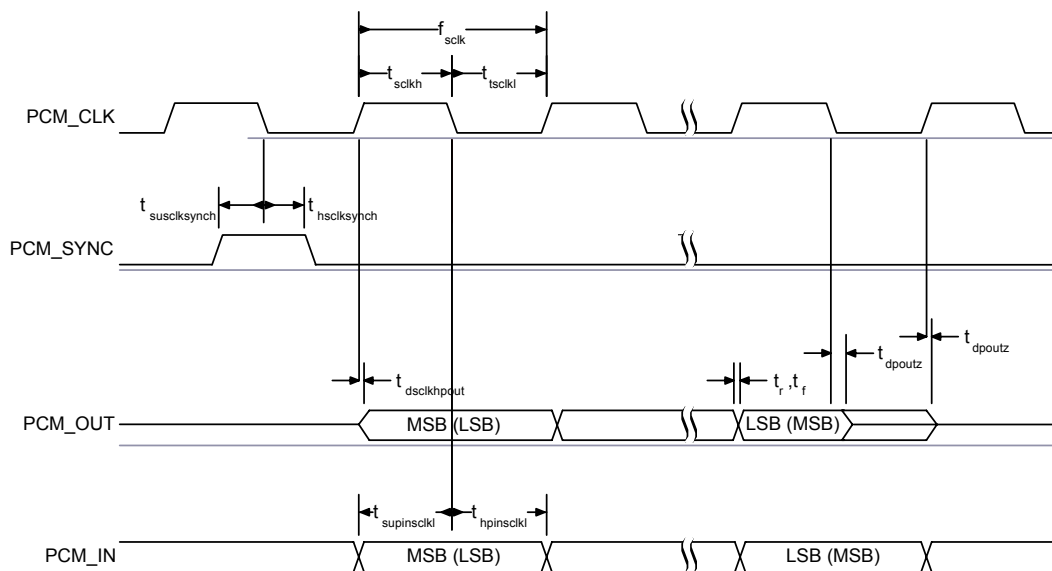


Figure 10.28: PCM Slave Timing Short Frame Sync

PCM_CLK and PCM_SYNC Generation

BlueCore4-ROM Plug-n-Go has two methods of generating PCM_CLK and PCM_SYNC in master mode. The first is generating these signals by Direct Digital Synthesis (DDS) from BlueCore4-ROM Plug-n-Go internal 4MHz clock (which is used in BlueCore2-External). Using this mode limits PCM_CLK to 128, 256 or 512kHz and PCM_SYNC to 8kHz. The second is generating PCM_CLK and PCM_SYNC by DDS from an internal 48MHz clock (which allows a greater range of frequencies to be generated with low jitter but consumes more power). This second method is selected by setting bit 48M_PCM_CLK_GEN_EN in PSKEY_PCM_CONFIG32. When in this mode and with long frame sync, the length of PCM_SYNC can be either 8 or 16 cycles of PCM_CLK, determined by LONG_LENGTH_SYNC_EN in PSKEY_PCM_CONFIG32.

The Equation 10.8 describes PCM_CLK frequency when being generated using the internal 48MHz clock:

$$f = \frac{\text{CNT_RATE}}{\text{CNT_LIMIT}} \times 24\text{MHz}$$

Equation 10.8: PCM_CLK Frequency When Being Generated Using the Internal 48MHz Clock

The frequency of PCM_SYNC relative to PCM_CLK can be set using Equation 10.9:

$$f = \frac{\text{PCM_CLK}}{\text{SYNC_LIMIT} \times 8}$$

Equation 10.9: PCM_SYNC Frequency Relative to PCM_CLK

CNT_RATE, CNT_LIMIT and SYNC_LIMIT are set using PSKEY_PCM_LOW_JITTER_CONFIG. As an example, to generate PCM_CLK at 512kHz with PCM_SYNC at 8kHz, set PSKEY_PCM_LOW_JITTER_CONFIG to 0x08080177.

10.7.9 PCM Configuration

The PCM configuration is set using two PS Keys, PSKEY_PCM_CONFIG32 detailed in Table 10.10 and PSKEY_PCM_LOW_JITTER_CONFIG in Table 10.11. The default for PSKEY_PCM_CONFIG32 is 0x00800000, i.e., first slot following sync is active, 13-bit linear voice format, long frame sync and interface master generating 256kHz PCM_CLK from 4MHz internal clock with no tri-state of PCM_OUT.

| Name | Bit Position | Description |
|----------------------------|--------------|---|
| - | 0 | Set to 0 |
| SLAVE_MODE_EN | 1 | 0 = master mode with internal generation of PCM_CLK and PCM_SYNC. 1 = slave mode requiring externally generated PCM_CLK and PCM_SYNC. |
| SHORT_SYNC_EN | 2 | 0 = long frame sync (rising edge indicates start of frame). 1 = short frame sync (falling edge indicates start of frame). |
| - | 3 | Set to 0. |
| SIGN_EXTEND_EN | 4 | 0 = padding of 8 or 13-bit voice sample into a 16-bit slot by inserting extra LSBs. When padding is selected with 13-bit voice sample, the 3 padding bits are the audio gain setting; with 8-bit sample the 8 padding bits are zeroes. 1 = sign-extension. |
| LSB_FIRST_EN | 5 | 0 = MSB first of transmit and receive voice samples. 1 = LSB first of transmit and receive voice samples. |
| TX_TRISTATE_EN | 6 | 0 = drive PCM_OUT continuously. 1 = tri-state PCM_OUT immediately after falling edge of PCM_CLK in the last bit of an active slot, assuming the next slot is not active. |
| TX_TRISTATE_RISING_EDGE_EN | 7 | 0 = tri-state PCM_OUT immediately after falling edge of PCM_CLK in last bit of an active slot, assuming the next slot is also not active. 1 = tri-state PCM_OUT after rising edge of PCM_CLK. |
| SYNC_SUPPRESS_EN | 8 | 0 = enable PCM_SYNC output when master. 1 = suppress PCM_SYNC whilst keeping PCM_CLK running. Some CODECS utilise this to enter a low power state. |
| GCI_MODE_EN | 9 | 1 = enable GCI mode |
| MUTE_EN | 10 | 1 = force PCM_OUT to 0 |
| 48M_PCM_CLK_GEN_EN | 11 | 0 = set PCM_CLK and PCM_SYNC generation via DDS from internal 4 MHz clock. 1 = set PCM_CLK and PCM_SYNC generation via DDS from internal 48 MHz clock. |
| LONG_LENGTH_SYNC_EN | 12 | 0 = set PCM_SYNC length to 8 PCM_CLK cycles. 1 = set length to 16 PCM_CLK cycles. Only applies for long frame sync and with 48M_PCM_CLK_GEN_EN set to 1. |
| - | [20:16] | Set to 0b00000 |

| Name | Bit Position | Description |
|-----------------|--------------|--|
| MASTER_CLK_RATE | [22:21] | Selects 128 (0b01), 256 (0b00), 512 (0b10) kHz PCM_CLK frequency when master and 48M_PCM_CLK_GEN_EN (bit 11) is low. |
| ACTIVE_SLOT | [26:23] | Default is 0001. Ignored by firmware. |
| SAMPLE_FORMAT | [28:27] | Selects between 13 (0b00), 16 (0b01), 8 (0b10) bit sample with 16 cycle slot duration or 8 (0b11) bit sample with 8 cycle slot duration. |

Table 10.10: PSKEY_PCM_CONFIG32 Description

| Name | Bit Position | Description |
|------------|--------------|--|
| CNT_LIMIT | [12:0] | Sets PCM_CLK counter limit |
| CNT_RATE | [23:16] | Sets PCM_CLK count rate |
| SYNC_LIMIT | [31:24] | Sets PCM_SYNC division relative to PCM_CLK |

Table 10.11: PSKEY_PCM_LOW_JITTER_CONFIG Description

10.8 I/O Parallel Ports

Fifteen lines of programmable bi-directional input/outputs (I/O) are provided. PIO[11:8] and PIO[3:0] are powered from VDD_PIO. PIO[7:4] are powered from VDD_PADS. AIO [2:0] are powered from VDD_MEM.

Fifteen lines of programmable bi-directional input/outputs (I/O) are provided. PIO[11:8] and PIO[3:0] are powered from VDD_PIO. PIO[7:4] are powered from VDD_PADS. AIO [2:0] are powered from VDD_USB.

PIO lines can be configured through software to have either weak or strong pull-ups or pull-downs. All PIO lines are configured as inputs with weak pull-downs at reset.

PIO[0] and PIO[1] are normally dedicated to RXEN and TXEN respectively, but they are available for general use.

Any of the PIO lines can be configured as interrupt request lines or as wake-up lines from sleep modes. PIO[6] or PIO[2] can be configured as a request line for an external clock source. This is useful when the clock to BlueCore4-ROM Plug-n-Go is provided from a system application specific integrated circuit (ASIC). Using PSKEY_CLOCK_REQUEST_ENABLE (0x246), this terminal can be configured to be low when BlueCore4-ROM Plug-n-Go is in Deep Sleep and high when a clock is required. The clock must be supplied within 4ms of the rising edge of PIO[6] or PIO[2] to avoid losing timing accuracy in certain Bluetooth operating modes.

BlueCore4-ROM Plug-n-Go has three general purpose analogue interface pins, AIO[0], AIO[1] and AIO[2] also known as the extended PIO lines. These are used to access internal circuitry and control signals. One pin is allocated to decoupling for the on-chip band gap reference voltage; the other two may be configured to provide additional functionality.

Auxiliary functions available via these pins include an 8-bit ADC and an 8-bit DAC. Typically the ADC is used for battery voltage measurement. Signals selectable at these pins include the band gap reference voltage and a variety of clock signals: 48, 24, 16, 8MHz and the XTAL clock frequency. When used with analogue signals, the voltage range is constrained by the analogue supply voltage (1.8V). When configured to drive out digital level signals (e.g., clocks), the output voltage level is determined by VDD_USB.

10.8.1 PIO Defaults for BlueCore4-ROM Plug-n-Go

CSR cannot guarantee that these terminal functions remain the same. Refer to the software release note for the implementation of these PIO lines, as they are firmware build-specific.

10.9 I²C Interface

PIO[8:6] can be used to form a master I²C interface. The interface is formed using software to drive these lines. Therefore, it is suited only to relatively slow functions such as driving a dot matrix liquid crystal display (LCD), keyboard scanner or EEPROM.

Notes:

PIO lines need to be pulled-up through 2.2k Ω resistors.

PIO[7:6] dual functions, UART bypass and EEPROM support, therefore, devices using an EEPROM cannot support UART bypass mode.

For connection to EEPROMs, refer to CSR documentation on I²C EEPROMs for use with BlueCore. This provides information on the type of devices currently supported.

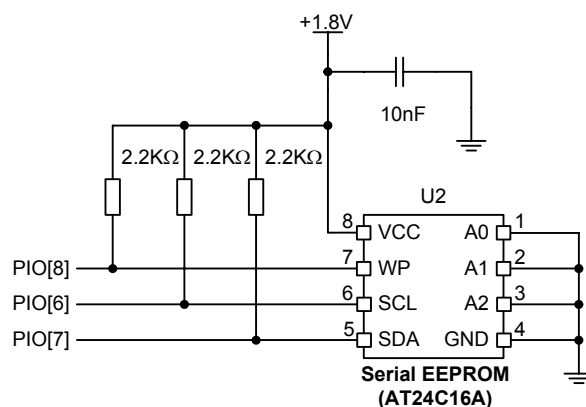


Figure 10.29: Example EEPROM Connection

10.10 TCXO Enable OR Function

An OR function exists for clock enable signals from a host controller and BlueCore4-ROM Plug-n-Go where either device can turn on the clock without having to wake up the other device. PIO[3] can be used as the host clock enables input and PIO[2] can be used as the OR output with the TCXO enable signal from BlueCore4-ROM Plug-n-Go.

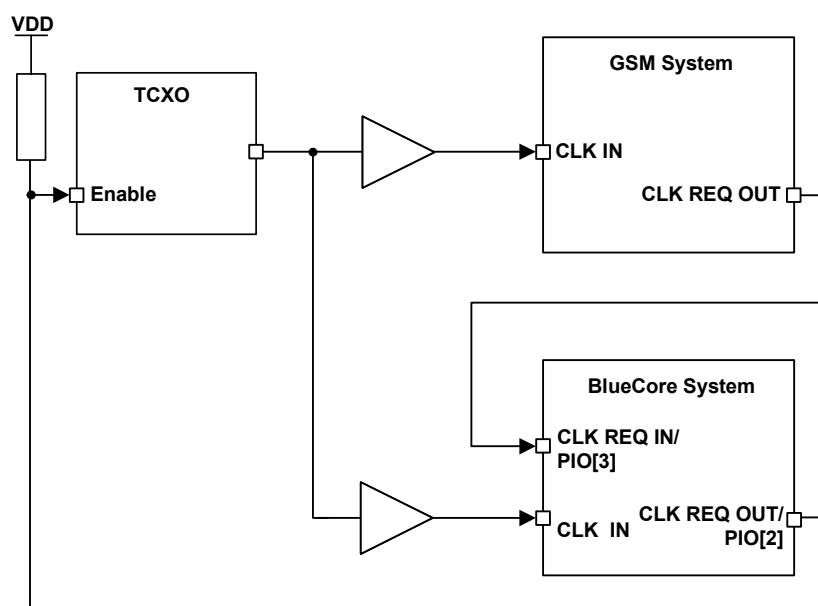


Figure 10.30: Example TXCO Enable OR Function

On reset and up to the time the PIO has been configured, PIO[2] will be tri-state. Therefore, the developer must ensure that the circuitry connected to this pin is pulled via a 470kΩ resistor to the appropriate power rail. This ensures that the TCXO is oscillating at start up.

10.11 RESET and RESETB

BlueCore4-ROM Plug-n-Go may be reset from several sources:

- RESET or RESETB pins
- Power on reset
- A UART break character
- Via a software configured watchdog timer

The RESET pin is an active high reset and is internally filtered using the internal low frequency clock oscillator. A reset will be performed between 1.5ms and 4.0ms following RESET being active. It is recommended that RESET be applied for a period greater than 5ms. The RESETB pin is the active low version of RESET and is OR'd on-chip with the active high RESET, with either causing the reset function.

The power on reset occurs when the VDD_CORE supply falls below typically 1.5V and is released when VDD_CORE rises above typically 1.6V.

At reset the digital I/O pins are set to inputs for bi-directional pins and outputs are tri-state. The PIOs have weak pull-downs.

Following a reset, BlueCore4-ROM Plug-n-Go assumes the maximum XTAL_IN frequency, which ensures that the internal clocks run at a safe (low) frequency until BlueCore4-ROM Plug-n-Go is configured for the actual XTAL_IN frequency. If no clock is present at XTAL_IN, the oscillator in BlueCore4-ROM Plug-n-Go free runs, again at a safe frequency.

10.11.1 Pin States on Reset

Table 10.12 shows the pin states of BlueCore4-ROM Plug-n-Go on reset.

| Pin Name | State: BlueCore4-ROM Plug-n-Go |
|-----------|--------------------------------------|
| PIO[11:0] | Input with weak pull-down |
| PCM_OUT | Tri-state with weak pull-down |
| PCM_IN | Input with weak pull-down |
| PCM_SYNC | Input with weak pull-down |
| PCM_CLK | Input with weak pull-down |
| UART_TX | Output tri-state with weak pull-up |
| UART_RX | Input with weak pull-down |
| UART_RTS | Output tri-state with weak pull-up |
| UART_CTS | Input with weak pull-down |
| USB_DP | Input with weak pull-down |
| USB_DN | Input with weak pull-down |
| SPI_CSB | Input with weak pull-up |
| SPI_CLK | Input with weak pull-down |
| SPI_MOSI | Input with weak pull-down |
| SPI_MISO | Output tri-state with weak pull-down |
| AIO[2:0] | Output, driving low |
| RESET | Input with weak pull-down |
| RESETB | Input with weak pull-up |
| TEST_EN | Input with strong pull-down |
| AUX_DAC | High impedance |
| RF_IN | High impedance |
| XTAL_IN | High impedance, 250k to XTAL_OUT |
| XTAL_OUT | High impedance, 250k to XTAL_IN |

Table 10.12: Pin States of BlueCore4-ROM Plug-n-Go on Reset

10.11.2 Status after Reset

The chip status after a reset is as follows:

- Warm Reset: Baud rate and RAM data remain available
- Cold Reset⁽¹⁾: Baud rate and RAM data not available

⁽¹⁾ A Cold Reset is either Power cycle, system reset (firmware fault code) or Reset signal. See section 10.11.

10.12 Power Supply

10.12.1 Voltage Regulator (Plug-n-Go)

An on-chip linear voltage regulator can be used to power the 1.8V dependent supplies. It is advised that a smoothing circuit using a 2.2 μ F low ESR capacitor and 2.2 Ω resistor be placed on the output VDD_ANA.

In the Plug-n-Go package, an internal 2.2 Ω resistor is provided between the regulator output VDD_ANA and VDD_DIG.

The regulator is switched into a low power mode when the device is sent into Deep Sleep mode. When the on-chip regulator is not required VDD_ANA is a 1.8V input and VREG_IN must be either open circuit or tied to VDD_ANA.

10.12.2 Sequencing

It is recommended that VDD_CORE, VDD_RADIO and VDD_ANA be powered at the same time. The order of powering supplies for VDD_CORE, VDD_PIO, VDD_PADS and VDD_USB is not important. However, if VDD_CORE is not present, all inputs have a weak pull-down irrespective of the reset state.

10.12.3 Sensitivity to Disturbances

CSR recommends if supplying BlueCore4-ROM Plug-n-Go from an external voltage source that VDD_ANA and VDD_RADIO should have less than 10mV rms noise levels between 0 to 10MHz. In addition, avoid single tone frequencies. CSR recommends a simple RC filter for VDD_CORE, as this reduces transients put back onto the power supply rails.

The remaining supplies VDD_MEM, VDD_PIO, VDD_PADS and VDD_USB can be connected together with the VREG_IN to the 3.3V supply and simply decoupled as shown in Figure 13.1.

The transient response of the regulator is also important. At the start of a packet, power consumption will jump to high levels. See the average current consumption section. The regulator should have a response time of 20 μ s or less; it is essential that the power rail recovers quickly.

10.12.4 VREG_EN Pin

The regulator enable pin, VREG_EN, can be used to enable and disable the BlueCore4-ROM Plug-n-Go device if the on-chip regulator is being used. The pin is active high and has an internal weak pull-up to enable the regulator if VREG_EN is not connected.

11 Product Reliability Tests

| Die | Test Conditions | Specification | Sample Size |
|---------------|------------------|----------------|----------------|
| ESD | Human Body Model | JEDEC | 36 |
| Latch-up | ±200mA | JEDEC | 6 |
| Early Life | 125°C | 48 – 168 hours | 240 |
| Hot Life Test | 125°C | 1000 hours | 320 (240 FITs) |

| Package | Test Conditions | Specification | Sample Size |
|--|--------------------------------|---|-------------|
| Moisture Sensitivity Precon JEDEC Level 3 | (125°C 24 hours) 30°C/60%RH | 192 hours five re-flow simulation cycles | 308 |
| Temperature Cycling | -65°C to +150°C | 500 cycles | 77 |
| AutoClave (Steam) | 121°C at 100% RH | 96 hours | 77 |
| HAST | 130°C/85% RH | 96 hours | 77 |
| Thermal Shock | -55/125°C | 100 cycles | 77 |
| High Temperature Storage | 150°C | 1000 hours | 77 |

12 Product Reliability Tests for BlueCore4-ROM Plug-n-Go Automotive

12.1 AEC-Q100

The reliability tests in this section follow the tests outlined in the AEC-Q100 and were performed on BlueCore4-ROM Plug-n-Go in VFBGA 10 x 10mm 96 I/O (lead-free solder balls). Samples are electrically tested at ambient temperature.

This package qualification will (where moisture sensitivity preconditioning is required) use IPC/Jedec MSL3, i.e., the finished product is allowed a maximum exposure to a $\leq 30^{\circ}\text{C}/60\%\text{RH}$ environment for 168 hours before mounting.

As part of CSR's automotive test program, customers will have access to the initial device reliability test report. They will also have access to a quarterly reliability test report update for automotive parts.

| Die | Test Conditions | Specification | Sample Size |
|---------------|--|---------------|-------------|
| ESD | Human Body Model | JEDEC | 24 |
| Early Life | 125°C VDD _{max} | 48 hours | 2400 |
| Hot Life Test | 125°C VDD _{max} | 1000 hours | 90, 77, 77 |

| Package | Test Conditions | Specification | Sample Size |
|--|---|---|-----------------|
| Moisture Sensitivity Precon JEDEC Level 3 | (125°C 24 hours) $30^{\circ}\text{C}/60\%\text{RH}$ | 192 hours five reflow simulation cycles | 783 |
| Temperature Cycling | $-65/150^{\circ}\text{C}$ | 500 cycles | 231 from Precon |
| Autoclave (Steam) | $121^{\circ}\text{C}/100\%\text{RH}$ | 96 hours | 231 from Precon |
| Temperature Humidity Bias | $85^{\circ}\text{C}/85\%\text{RH}$ Vdd _{max} | 1000 hours | 231 from Precon |
| Thermal Shock | $-55/125^{\circ}\text{C}$ | 100 cycles | 77 from Precon |
| High Temperature Storage | 150°C | 1000 hours | 77 |

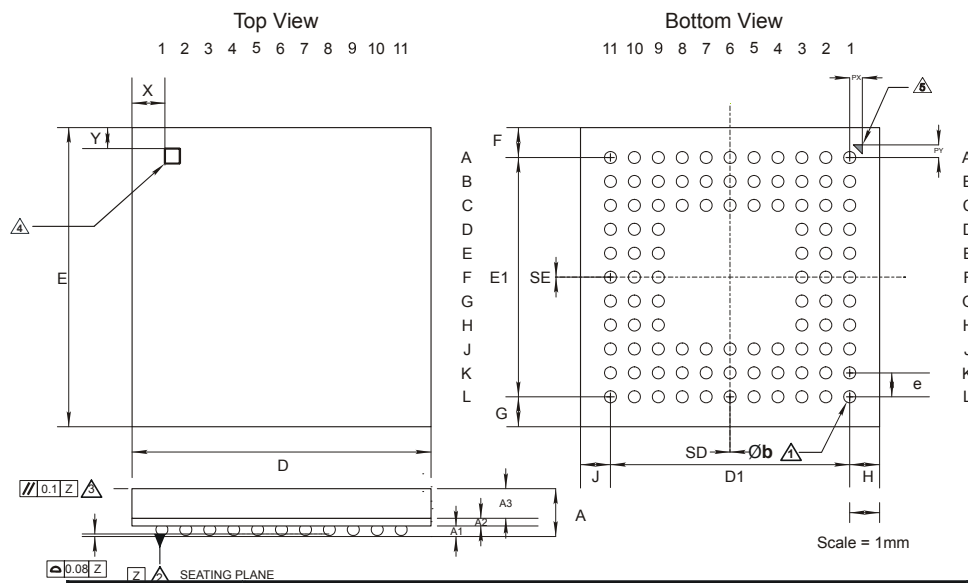
| Other | Test Conditions | Sample Size |
|----------------------------------|--|--|
| Bond Shear | Acid decapsulation of finished product | 30 bonds |
| Wire Pull | Acid decapsulation of finished product | 60 wires from Precon and temperature cycling |
| Solder Ball Shear | Two reflow cycles | 150 balls |
| Visual Inspection and Dimensions | N/A | 30 devices |

BlueCore™4-ROM Plug-n-Go™ Data Sheet



14 Package Dimensions

14.1 10 x 10 LFBGA 96-Ball 1.6mm Package



| Description | | 96-Ball Low-Profile Fine-Pitch Ball Grid Array (LFBGA) | | |
|-------------------|---------|--|---------|--|
| Size | | 10 x 10 x 1.6mm | | |
| Pitch | | 0.8mm | | |
| Package Ball Land | | Solder mask defined. Solder mask aperture 300µm Ø | | |
| Dimension | Minimum | Typical | Maximum | Notes |
| A | | | 1.6 | ¹ Dimension b is measured at the maximum solder ball diameter parallel to datum plane Z ² Datum Z is defined by the spherical crowns of the solder balls ³ Parallelism measurement shall exclude any effect of mark on top surface of package ⁴ Top-side polarity mark. The dimensions of the square polarity mark are 0.5 x 0.5mm. ⁵ TBA Bottom-side polarity mark. The dimensions of the triangular polarity mark are 0.30 x 0.30 x 0.42mm. |
| A1 | 0.30 | 0.35 | 0.40 | |
| A2 | | 0.26 | | |
| A3 | | 0.80 | | |
| b | 0.35 | 0.40 | 0.45 | |
| D | 9.90 | 10.00 | 10.10 | |
| E | 9.90 | 10.00 | 10.10 | |
| e | | 0.80 | | |
| D1 | | 8.00 | | |
| E1 | | 8.00 | | |
| F | 0.950 | 1.000 | 1.050 | |
| G | 0.950 | 1.000 | 1.050 | |
| H | 0.950 | 1.000 | 1.050 | |
| J | 0.950 | 1.000 | 1.050 | |
| PD | | 0.300 | | |
| PX | | 0.420 | | |
| PE | | 0.300 | | |
| PY | | 0.420 | | |
| SD | | 0 | | |
| SE | | 0 | | |
| X | | 1.10 | | |
| Y | | 0.70 | | |
| JEDEC | | MO-210 | | |
| Unit | | mm | | |

Figure 14.1: BlueCore4-ROM Plug-n-Go 96-Ball LFBGA 1.6mm Package Dimensions



15 Ordering Information

15.1 BlueCore4-ROM Plug-n-Go

| Interface Version | Package | | | Order Number |
|-------------------|----------------------------|-----------------|-----------------|----------------------|
| | Type | Size | Shipment Method | |
| UART and USB | 96-Ball LFBGA (Pb free) | 10 x 10 x 1.6mm | Tape and reel | BC41B143A-ANN-E4 (a) |

(a) Until BlueCore4-ROM Plug-n-Go reaches **Production** status order number is BC41B143AES-ANN-E4.

Minimum Order Quantity

2kpcs taped and reeled

16 Contact Information

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17 Document References

| Document: | Reference |
|---|--|
| Specification of the Bluetooth system | v1.1, 22 February 2001 and v1.2, 05 November 2003 |
| Bluetooth Core Specification v2.0 + EDR | v2.0+EDR, 8 November 2004 |
| Bluetooth Test Document v2.0+EDR | v2.0.e.0, 5 November 2004 |
| Universal Serial Bus Specification | v1.1, 23 September 1998 |
| Selection of Flash Memory for Use with BlueCore | CSR document bcore-an-001P |
| Selection of I ² C EEPROMS for Use with BlueCore | CSR document bcore-an-008P |
| IA-481-2 | 16mm, 24mm, 32mm, 44mm and 56mm Embossed Carrier Taping of Surface Mount Components for Automatic Handling |
| EIA-541 | Packaging Material Standards for ESD Sensitive Items |
| EIA-583 | Packaging Material Standards for Electrostatic Discharge (ESD) Sensitive Items |
| IPC / JEDEC J-STD-033 | Standard for Handling, Packing, Shipping and Use of Moisture / Reflow Sensitive Surface Mount Devices |

18 Terms and Definitions

| | |
|---------------|--|
| 8DPSK | 8 phase Differential Phase Shift Keying |
| $\pi/4$ DQPSK | $\pi/4$ rotated Differential Quaternary Phase Shift Keying |
| BlueCore® | Group term for CSR's range of Bluetooth chips |
| Bluetooth™ | Set of technologies providing audio and data transfer over short-range radio connections |
| ACL | Asynchronous Connection-Less. Bluetooth data packet |
| ADC | Analogue to Digital Converter |
| AFH | Adaptive Frequency Hopping |
| AGC | Automatic Gain Control |
| A-law | Audio encoding standard |
| ALU | Arithmetic Logic Unit |
| API | Application Programming Interface |
| ASIC | Application Specific Integrated Circuit |
| BCSP | BlueCore™ Serial Protocol |
| BER | Bit Error Rate. Used to measure the quality of a link |
| BIST | Built-In Self-Test |
| BMC | Burst Mode Controller |
| CDMA | Code Division Multiple Access |
| CMOS | Complementary Metal Oxide Semiconductor |
| CODEC | Coder Decoder |
| CQDDR | Channel Quality Driven Data Rate |
| CRC | Cyclic Redundancy Check |
| CSB | Chip Select (Active Low) |
| CSR | Cambridge Silicon Radio |
| CTS | Clear to Send |
| CVSD | Continuous Variable Slope Delta Modulation |
| DAC | Digital to Analogue Converter |
| dBm | Decibels relative to 1mW |
| DDS | Direct Digital Synthesis |
| DC | Direct Current |
| DFU | Device Firmware Upgrade |
| DNL | Differential Linearity Error |
| DSP | Digital Signal Processor |
| EDR | Enhanced Data Rate |
| eSCO | Extended SCO |
| ESR | Equivalent Series Resistance |
| FIR | Finite Impulse Response |

| | |
|-------------------|---|
| FSK | Frequency Shift Keying |
| GCI | General Circuit Interface |
| GFSK | Gaussian Frequency Shift Keying |
| GSM | Global System for Mobile communications |
| HCI | Host Controller Interface |
| I ² C™ | Inter-Integrated Circuit |
| IF | Intermediate Frequency |
| IIR | Infinite Impulse Response |
| INL | Integral Linearity Error |
| IQ Modulation | In-Phase and Quadrature Modulation |
| ISDN | Integrated Services Digital Network |
| ISM | Industrial, Scientific and Medical |
| Kalimba | DSP core for CSR's range of chips |
| ksps | KiloSamples Per Second |
| L2CAP | Logical Link Control and Adaptation Protocol (protocol layer) |
| LC | Link Controller |
| LCD | Liquid Crystal Display |
| LFPGA | Low profile Fine Ball Grid Array |
| LMP | Link Manager Protocol |
| LNA | Low Noise Amplifier |
| LPF | Low Pass Filter |
| LSB | Least-Significant Bit |
| MCU | MicroController Unit |
| μ-law | Audio Encoding Standard |
| MIPS | Million Instructions Per Second |
| MMU | Memory Management Unit |
| MISO | Master In Serial Out |
| NOB | Number Of Bits |
| OHCI | Open Host Controller Interface |
| PA | Power Amplifier |
| PCM | Pulse Code Modulation. Refers to digital voice data |
| PDA | Personal Digital Assistant |
| Persistent Store | Storage of BlueCore's configuration values in non-volatile memory |
| PIO | Parallel Input Output |
| PICS | Profile Implementation Confirmation Statement |
| pk-pk | Peak to Peak |
| PLL | Phase Lock Loop |
| ppm | parts per million |
| PS Key | Persistent Store Key |

| | |
|--------|--|
| RAM | Random Access Memory |
| REB | Read enable (Active Low) |
| REF | Reference. Represents dimension for reference use only. |
| RF | Radio Frequency |
| RFCOMM | Protocol layer providing serial port emulation over L2CAP |
| RISC | Reduced Instruction Set Computer |
| rms | root mean squared |
| RSSI | Receive Signal Strength Indication |
| RTS | Ready To Send |
| RX | Receive or Receiver |
| SCO | Synchronous Connection-Oriented. Voice oriented Bluetooth packet |
| SDK | Software Development Kit |
| SDP | Service Discovery Protocol |
| SIG | Special Interest Group |
| SINAD | Signal to Noise ratio And Distortion |
| SNR | Signal to Noise Ratio |
| SPDIF | Sony and Philips Interface Specification |
| SPI | Serial Peripheral Interface |
| SSI | Synchronous Serial Interface |
| TBD | To Be Defined |
| TCXO | Temperature Controlled crystal Oscillator |
| TX | Transmit or Transmitter |
| UART | Universal Asynchronous Receiver Transmitter |
| UHCI | Upper Host Control Interface |
| USB | Universal Serial Bus or Upper Side Band (depending on context) |
| VCO | Voltage Controlled Oscillator |
| VFBGA | Very Fine Ball Grid Array |
| VM | Virtual Machine |
| W-CDMA | Wideband Code Division Multiple Access |
| WEB | Write Enable (Active Low) |

19 Document History

| Date | Revision | Reason for Change |
|--------|----------|--|
| FEB 05 | a | Original publication of this document. (CSR reference: BC41B143A-ds-001Pa) |
| MAR 05 | a | Document identification number revised to BC41B143A-ds-003Pa. Amended Device Diagram. Amended VDD_USB terminal function description. Added Balun and Filter block description. Minor amends. |
| APR 05 | b | Amended maximum baud rate to 3M baud and added additional data rates. |
| JUL 05 | c | <p>Electrical Characteristics and Radio Characteristics - Basic Data Rate updated to reflect a radio performance temperature range of -40°C to +85°C.</p> <p>Updated Auxilliary DAC in Description of Functional Blocks</p> <p>Amendment to note (a) concerning specified output voltage in the Auxilliary DAC table (Input/Output Terminal Characteristics) in Electrical Characteristics.</p> <p>Amendment to note (g) concerning VREG_EN and VREG_IN in Linear Regulator table in Electrical Characteristics.</p> <p>Power Consumption moved from Radio Characteristics to Electrical Characteristics section.</p> <p>Changed title of Record of Changes to Document History; changed title of Acronyms and Abbreviations to Terms and Definitions.</p> |

BlueCore™4-ROM Plug-n-Go™

Product Data Sheet

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