# 查询TIBPAL20L8-10M供应辅BPAL20L8-7C, TIBPAL20R4-704户下BPAL20R6-7C加利BPAL20R8-7C TIBPAL20L8-10M, TIBPAL20R4-10M, TIBPAL20R6-10M, TIBPAL20R8-10M HIGH-PERFORMANCE IMPACT-X™ PAL® CIRCUITS

SRPS005D - D3307, OCTOBER 1989 - REVISED NOVEMBER 1995

High-Performance Operation:

f<sub>max</sub> (no feedback)

TIBPAL20R' -7C Series . . . 100 MHz

TIBPAL20R' -10M Series . . . 62.5 MHz

f<sub>max</sub> (internal feedback)

TIBPAL20R' -7C Series . . . 100 MHz

TIBPAL20R'-10M Series . . . 62.5 MHz

f<sub>max</sub> (external feedback)

TIBPAL20R' -7C Series . . . 74 MHz

TIBPAL20R' -10M Series . . . 50 MHz

**Propagation Delay** 

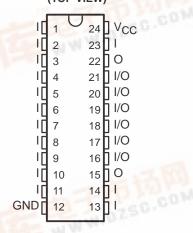
TIBPAL20L8-7C Series . . . 7 ns Max

TIBPAL20L8-10M Series . . . 10 ns Max

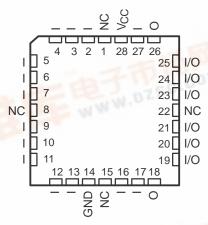
- Functionally Equivalent, but Faster Than Existing 24-Pin PLD Circuits
- Preload Capability on Output Registers Simplifies Testing
- Power-Up Clear on Registered Devices (All Register Outputs are Set Low, but Voltage Levels at the Output Pins Go High)
- Package Options Include Both Plastic and Ceramic Chip Carriers in Addition to Plastic and Ceramic DIPs
- Security Fuse Prevents Duplication
- Dependable Texas Instruments Quality and Reliability

DEVICE	I INPUTS	3-STATE O OUTPUTS	REGISTERED Q OUTPUTS	I/O PORT S
PAL20L8	14	2	0	6
PAL20R4	12	0	4 (3-state buffers)	4
PAL20R6	12	0	6 (3-state buffers)	2
PAL20R8	12	0	8 (3-state buffers)	0

# TIBPAL20L8' C SUFFIX . . . JT OR NT PACKAGE M SUFFIX . . . JT PACKAGE (TOP VIEW)



TIBPAL20L8'
C SUFFIX . . . FN PACKAGE
M SUFFIX . . . FK PACKAGE
(TOP VIEW)



NC — No internal connection
Pin assignments in operating mode

#### description

These programmable array logic devices feature high speed and functional equivalency when compared with currently available devices. These IMPACT-X™ circuits combine the latest Advanced Low-Power Schottky technology with proven titanium-tungsten fuses to provide reliable, high-performance substitutes for conventional TTL logic. Their easy programmability allows for quick design of custom functions and typically results in a more compact circuit board. In addition, chip carriers are available for futher reduction in board space.

All of the register outputs are set to a low level during power-up. Extra circuitry has been provided to allow loading of each register asynchronously to either a high or low state. This feature simplifies testing because the registers can be set to an initial state prior to executing the test sequence.

The TIBPAL20' C series is characterized from 0°C to 75°C. The TIBPAL20' M series is characterized for operation over the full military temperature range of –55°C to 125°C.

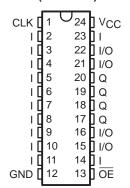
These devices are covered by U.S. Patent 4,410,987. IMPACT-X is a trademark of Texas Instruments Incorporated. PAL is a registered trademark of Advanced Micro Devices Inc.



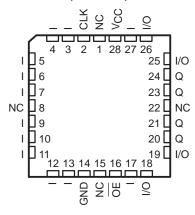
# TIBPAL20R4-7C, TIBPAL20R6-7C, TIBPAL20R8-7C TIBPAL20R4-10M, TIBPAL20R6-10M, TIBPAL20R8-10M HIGH-PERFORMANCE $IMPACT-X^{TM}$ $PAL^{\oplus}$ CIRCUITS

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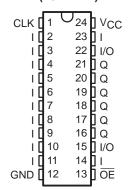


TIBPAL20R4'
C SUFFIX . . . FN PACKAGE
M SUFFIX . . . FK PACKAGE
(TOP VIEW)

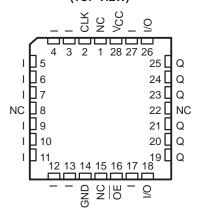


TIBPAL20R6'
C SUFFIX . . . JT OR NT PACKAGE
M SUFFIX . . . JT PACKAGE

(TOP VIEW)

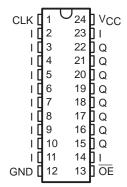


TIBPAL20R6'
C SUFFIX . . . FN PACKAGE
M SUFFIX . . . FK PACKAGE
(TOP VIEW)

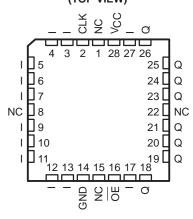


TIBPAL20R8'
C SUFFIX . . . JT OR NT PACKAGE
M SUFFIX . . . JT PACKAGE

(TOP VIEW)



TIBPAL20R8'
C SUFFIX ... FN PACKAGE
M SUFFIX ... FK PACKAGE
(TOP VIEW)

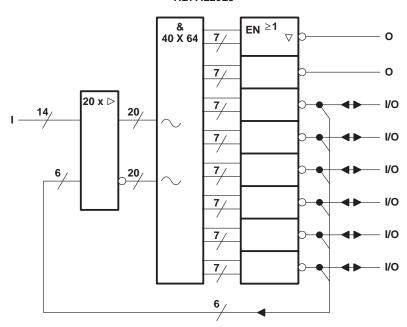


NC - No internal connection

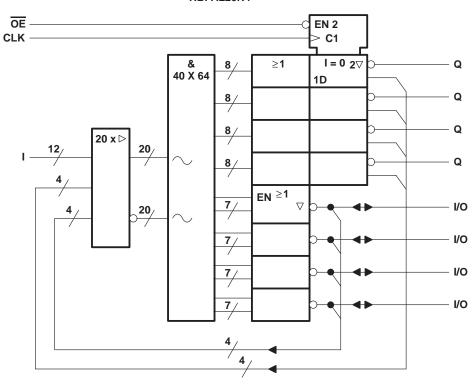
Pin assignments in operating mode

## functional block diagrams (positive logic)

#### TIBPAL20L8'



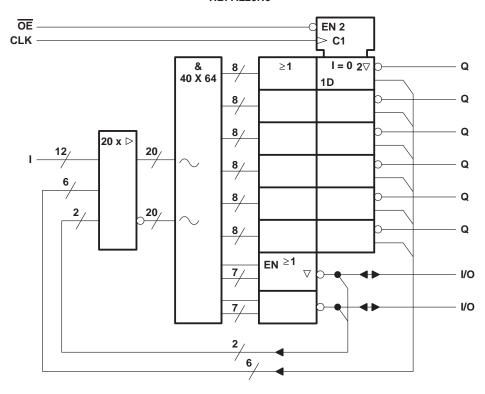
#### TIBPAL20R4'



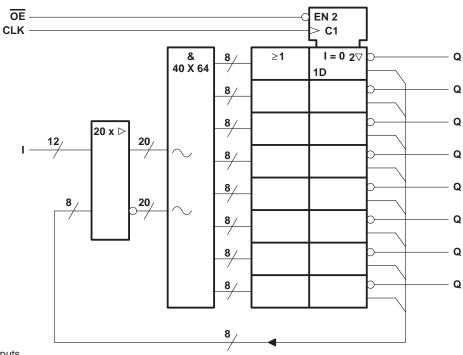


## functional block diagrams (positive logic)

#### TIBPAL20R6'



#### TIBPAL20R8'



 $\sim$  denotes fused inputs



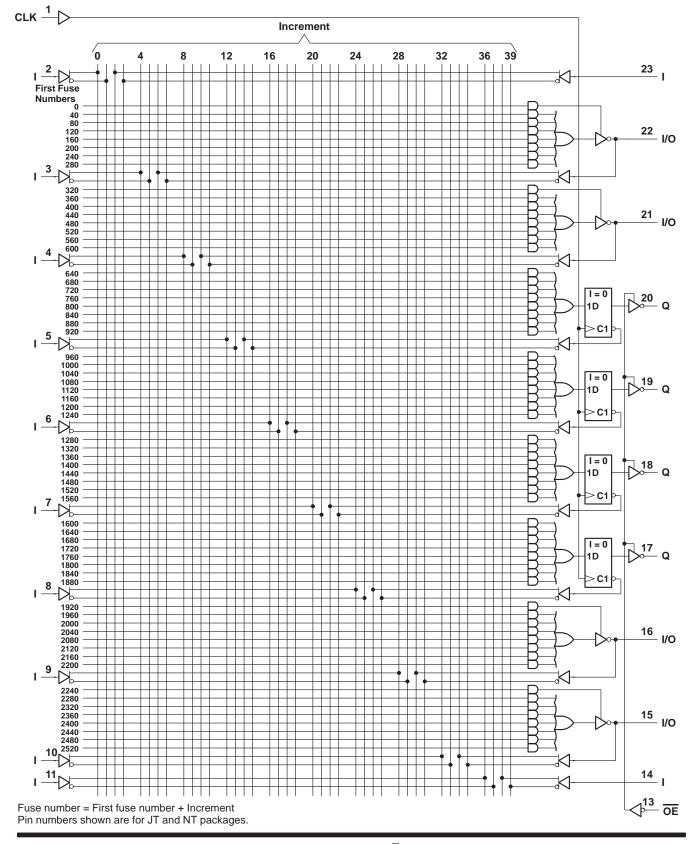
#### SRPS005D - D3307, OCTOBER 1989 - REVISED NOVEMBER 1995

## logic diagram (positive logic) Increment 36 39 I 2 5 First Fuse Numbers 0 80 120 22 — 0 160 200 240 360 400 440 480 21 I/O 640 720 <u>20</u> I/O 760 880 920 **-**960 1000 1040 1080 19 I/O 1200 ⇉⇃ 1280 1320 1360 1400 1440 18 I/O 1480 1520 1560 1600 1640 1680 <del>17</del> I/O 1720 1760 1800 1840 1880 ₃Ы 1920 1960 2000 2040 <u>16</u> I/O 2080 2120 2160 ₩ 2240 2280 2320 2360 1<u>5</u> o 2400 2440 2480 2520 10 20. <u>14</u> I <u>13</u> I Fuse number = First fuse number + Increment



Pin numbers shown are for JT and NT packages.

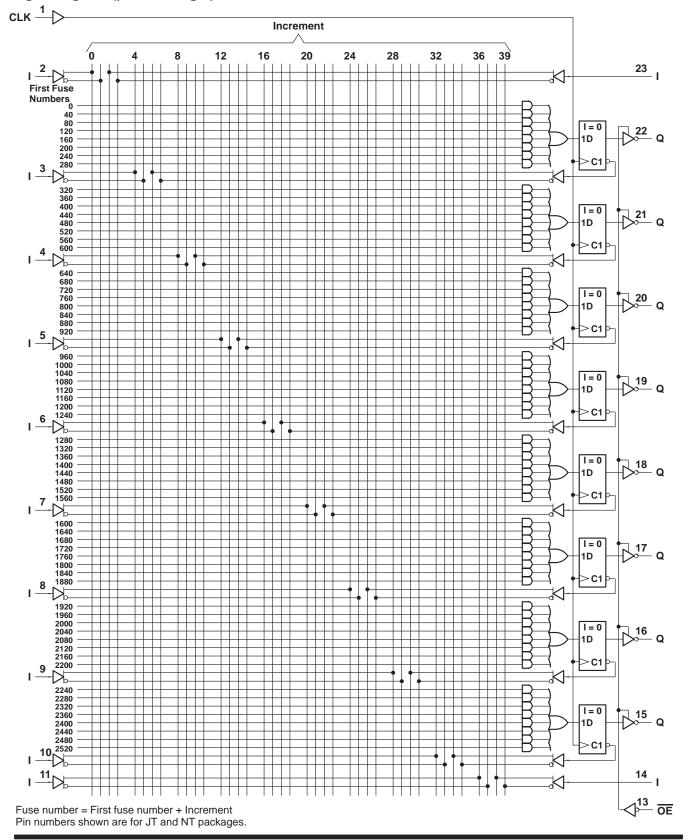
### logic diagram (positive logic)



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#### logic diagram (positive logic) CLK 1 Increment 0 8 12 16 20 24 28 32 36 39 23 \_\_\_ I I Do W. Numbers 0 <del>22</del> //O 120 N 320 360 400 440 I = 0 21 Q 1D 480 560 -C1 640 680 720 760 I = 0 1D 800 >C1 920 960 1000 1040 I = 0 <sup>19</sup> Q 1080 1120 1160 1D **⊳**C1 I 6 1240 1240 1280 1320 1360 1400 I = 0 <sup>18</sup> o 1D 1440 1480 1520 1600 1640 1680 1720 1760 I = 07.17 Q 1D 1800 1840 -**C**1 1880 1920 1960 2000 I = 0 16 Q 2040 2080 1D 2120 2160 **≥**C1 I — 2200 2240 2280 2320 2360 <u>15</u> I/O 2400 2440 2480 10,2520 N Fuse number = First fuse number + Increment Pin numbers shown are for JT and NT packages.

### logic diagram (positive logic)





# TIBPAL20L8-7C, TIBPAL20R4-7C, TIBPAL20R6-7C, TIBPAL20R8-7C HIGH-PERFORMANCE $IMPACT-X^{TM}$ $PAL^{\circledR}$ CIRCUITS

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## absolute maximum ratings over operating free-air temperature range (unless otherwise noted)

Supply voltage, V <sub>CC</sub> (see Note 1)	7 V
Input voltage (see Note 1)	5.5 V
Voltage applied to disabled output (see Note 1)	5.5 V
Operating free-air temperature range	0°C to 75°C
Storage temperature range	-65°C to 150°C

NOTE 1: These ratings apply except for programming pins during a programming cycle.

#### recommended operating conditions

			MIN	NOM	MAX	UNIT
VCC	Supply voltage		4.75	5	5.25	V
VIH	High-level input voltage (see Note 2)		2		5.5	V
VIL	Low-level input voltage (see Note 2)				0.8	V
ГОН	High-level output current				-3.2	mA
loL	Low-level output current				24	mA
f <sub>clock</sub> †	Clock frequency		0		100	MHz
t <sub>W</sub> †	Pulse duration, clock (see Note 2)	High	5			ns
'W'	ruise duration, clock (see Note 2)	Low	5			113
t <sub>su</sub> †	Setup time, input or feedback before clock↑		7			ns
t <sub>h</sub> †	Hold time, input or feedback after clock↑		0			ns
TA	Operating free-air temperature		0	25	75	°C

† f<sub>clock</sub>, t<sub>w</sub>, t<sub>su</sub>, and t<sub>h</sub> do not apply for TIBPAL20L8'.
NOTE 2: These are absolute voltage levels with respect to the ground pin of the device and include all overshoots due to system and/or tester noise. Testing these parameters should not be attempted without suitable equipment.



# TIBPAL20L8-7C, TIBPAL20R4-7C, TIBPAL20R6-7C, TIBPAL20R8-7C HIGH-PERFORMANCE *IMPACT-X* ™ *PAL*® CIRCUITS

SRPS005D - D3307, OCTOBER 1989 - REVISED NOVEMBER 1995

#### electrical characteristics over recommended operating free-air temperature range

PARAMETER		TEST CONDITIONS		MIN	TYP <sup>†</sup>	MAX	UNIT
VIK	$V_{CC} = 4.75 \text{ V},$	$I_{I} = -18 \text{ mA}$			-0.8	-1.5	V
VOH	$V_{CC} = 4.75 \text{ V},$	$I_{OH} = -3.2 \text{ mA}$		2.4	3.2		V
V <sub>OL</sub>	$V_{CC} = 4.75 \text{ V},$	$I_{OL} = 24 \text{ mA}$			0.3	0.5	V
lozH <sup>‡</sup>	V <sub>CC</sub> = 5.25 V,	$V_0 = 2.7 \text{ V}$				100	μΑ
lozL <sup>‡</sup>	V <sub>CC</sub> = 5.25 V,	V <sub>O</sub> = 0.4 V				-100	μΑ
IĮ	V <sub>CC</sub> = 5.25 V,	V <sub>I</sub> = 5.5 V				100	μΑ
I <sub>IH</sub> ‡	V <sub>CC</sub> = 5.25 V,	V <sub>I</sub> = 2.7 V				25	μΑ
I <sub>IL</sub> ‡	V <sub>CC</sub> = 5.25 V,	V <sub>I</sub> = 0.4 V			-80	-250	μΑ
IOS§	V <sub>CC</sub> = 5.25 V,	V <sub>O</sub> = 0.5 V		-30	-70	-130	mA
Icc	V <sub>CC</sub> = 5.25 V,	V <sub>I</sub> = 0,	Outputs open		150	210	mA
Ci	f = 1 MHz,	V <sub>I</sub> = 2 V			5		pF
Co	f = 1 MHz,	V <sub>O</sub> = 2 V	•		6		pF
C <sub>clk</sub>	f = 1 MHz,	V <sub>CLK</sub> = 2 V			6		pF

# switching characteristics over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

PARAMETER	FROM (INPUT)	TO (OUTPUT)		TEST CONDITION	MIN	TYP	MAX	UNIT
	W	ithout fee	edback		100			
f <sub>max</sub> ¶	with internal feedback (counter configuration)			100			MHz	
	with	external	feedback		74			
,	1.1/0	0.1/0	1 or 2 outputs switching		3	5.5	7	
<sup>t</sup> pd	I, I/O	O, I/O	8 outputs switching	R1 = 200 $\Omega$ ,	3	6	7.5	ns
t <sub>pd</sub>	CLK↑		Q	R2 = 390 $\Omega$ ,	2	4	6.5	ns
t <sub>pd</sub> #	CLK↑		Feedback input	See Figure 6			3	ns
t <sub>en</sub>	OE↓		Q			4	7.5	ns
<sup>t</sup> dis	OE↑		Q			4	7.5	ns
t <sub>en</sub>	I, I/O		O, I/O			6	9	ns
t <sub>dis</sub>	I, I/O		O, I/O			6	9	ns
t <sub>sk(o)</sub>	Skew betv	veen reg	istered outputs			0.5		ns

<sup>&</sup>lt;sup>†</sup> All typical values are at  $V_{CC} = 5 \text{ V}$ ,  $T_A = 25^{\circ}\text{C}$ .



<sup>‡</sup> I/O leakage is the worst case of IOZL and I<sub>IL</sub> or IOZH and I<sub>IH</sub> respectively.

Not more than one output should be shorted at a time, and the duration of the short circuit should not exceed one second. Vo is set at 0.5 V to avoid test problems caused by test equipment ground degradation.

 $<sup>\</sup>P$  See section for  $f_{max}$  specifications.

<sup>#</sup> This parameter applies to TIBPAL20R4' and TIBPAL20R6' only (see Figure 4 for illustration) and is calculated from the measured f<sub>max</sub> with internal feedback in the counter configuration.

This parameter is the measurement of the difference between the fastest and slowest tpd (CLK-to-Q) observed when multiple registered outputs are switching in the same direction.

# TIBPAL20L8-10M, TIBPAL20R4-10M, TIBPAL20R6-10M, TIBPAL20R8-10M HIGH-PERFORMANCE $IMPACT-X^{TM}$ $PAL^{\textcircled{\tiny{B}}}$ CIRCUITS

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#### absolute maximum ratings over operating free-air temperature range (unless otherwise noted)

Supply voltage, V <sub>CC</sub> (see Note 1)		. 7\	/
Input voltage (see Note 1)		5.5 √	/
Voltage applied to disabled output (see Note 1)		5.5 √	/
Operating free-air temperature range	$-55^{\circ}$ C to	125°C	)
Storage temperature range	-65°C to	150°C	2

NOTE 1: These ratings apply except for programming pins during a programming cycle.

### recommended operating conditions

			MIN	NOM	MAX	UNIT
Vcc	Supply voltage		4.5	5	5.5	V
VIH	High-level input voltage		2		5.5	V
VIL	Low-level input voltage				0.8	V
IOH	High-level output current				-2	mA
loL	Low-level output current				12	mA
f <sub>clock</sub> †	Clock frequency		0		62.5	MHz
t <sub>w</sub> †	Pulse duration, clock (see Note 2)	High	8			ns
'W'	ruise duration, clock (see Note 2)	Low	8			113
t <sub>su</sub> †	Setup time, input or feedback before clock↑		10			ns
t <sub>h</sub> †	Hold time, input or feedback after clock↑		0			ns
T <sub>A</sub>	Operating free-air temperature		<b>-</b> 55	25	125	°C

† f<sub>clock</sub>, t<sub>w</sub>, t<sub>su</sub>, and t<sub>h</sub> do not apply for TIBPAL20L8'.

NOTE 2: These are absolute voltage levels with respect to the ground pin of the device and include all overshoots due to system and/or tester noise. Testing these parameters should not be attempted without suitable equipment.



# TIBPAL20L8-10M, TIBPAL20R4-10M, TIBPAL20R6-10M, TIBPAL20R8-10M HIGH-PERFORMANCE $IMPACT-X \text{ }^{TM} PAL^{\textcircled{\tiny B}}$ CIRCUITS

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#### electrical characteristics over recommended operating free-air temperature range

PARAMETER		TEST CONDITIONS		MIN	TYP <sup>†</sup>	MAX	UNIT
VIK	V <sub>CC</sub> = 4.5 V,	I <sub>I</sub> = -18 mA			-0.8	-1.5	V
VOH	$V_{CC} = 4.5 \text{ V},$	$I_{OH} = -2 \text{ mA}$		2.4	3.2		V
V <sub>OL</sub>	$V_{CC} = 4.5 \text{ V},$	$I_{OL} = 12 \text{ mA}$			0.3	0.5	V
lozh <sup>‡</sup>	$V_{CC} = 5.5 \text{ V},$	V <sub>O</sub> = 2.7 V				20	μΑ
lozL <sup>‡</sup>	$V_{CC} = 5.5 V$ ,	$V_0 = 0.4 \ V$				-0.1	mA
lį	V <sub>CC</sub> = 5.5 V,	V <sub>I</sub> = 5.5 V				1	mA
I <sub>IH</sub> ‡ I/O ports	VCC = 5.5 V,	V <sub>I</sub> = 2.7 V				100	μА
All others	· CC = 5.5 · ;	V   - 2.7 V				25	μΛ
I <sub>IL</sub> ‡	$V_{CC} = 5.5 V$ ,	V <sub>I</sub> = 0.4 V			-0.08	-0.25	mA
IOS§	$V_{CC} = 5.5 \text{ V},$	V <sub>O</sub> = 0.5 V		-30	-70	-130	mA
Icc	$V_{CC} = 5.5 V$ ,	Outputs open			140	220	mA
	$V_{I} = 0,$	OE = V <sub>IH</sub>			140	220	ША
Ci	f = 1 MHz,	V <sub>I</sub> = 2 V			5		pF
Co	f = 1 MHz,	V <sub>O</sub> = 2 V			6		pF
C <sub>clk</sub>	f = 1 MHz,	V <sub>CLK</sub> = 2 V	·		6		pF

# switching characteristics over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

PARAMETER	FROM (INPUT)	TO (OUTPUT)	TEST CONDITION	MIN	TYP <sup>†</sup>	MAX	UNIT
	without feedback with internal feedback (counter configuration)			62.5			
f <sub>max</sub> ¶				62.5			MHz
	with externa	al feedback		50			
<sup>t</sup> pd	I, I/O	O, I/O	R1 = 390 $\Omega$ ,	1	6	10	ns
<sup>t</sup> pd	CLK↑	Q	$R2 = 750 \Omega$ ,	1	4	10	ns
t <sub>pd</sub> #	CLK↑	Feedback input	See Figure 6			5	ns
t <sub>en</sub>	OE↓	Q		1	4	10	ns
<sup>t</sup> dis	OE↑	Q		1	4	10	ns
t <sub>en</sub>	I, I/O	O, I/O		1	6	12	ns
<sup>t</sup> dis	I, I/O	O, I/O		1	6	10	ns

<sup>†</sup> All typical values are at  $V_{CC} = 5 \text{ V}$ ,  $T_A = 25^{\circ}\text{C}$ .



<sup>‡</sup> I/O leakage is the worst case of IOZL and I<sub>I</sub>L or IOZH and I<sub>I</sub>H respectively.

Not more than one output should be shorted at a time, and the duration of the short circuit should not exceed one second. Vo is set at 0.5 V to avoid test problems caused by test equipment ground degradation.

<sup>¶</sup> See section for f<sub>max</sub> specifications. f<sub>max</sub> with external feedback is not production tested but is calculated from the equation found in the f<sub>max</sub> specification section.

<sup>#</sup> This parameter applies to TIBPAL20R4' and TIBPAL20R6' only (see Figure 4 for illustration) and is calculated from the measured f<sub>max</sub> with internal feedback in the counter configuration.

# TIBPAL20L8-7C, TIBPAL20R4-7C, TIBPAL20R6-7C, TIBPAL20R8-7C TIBPAL20L8-10M, TIBPAL20R4-10M, TIBPAL20R6-10M, TIBPAL20R8-10M HIGH-PERFORMANCE $IMPACT-X^{TM}$ $PAL^{\textcircled{\tiny B}}$ CIRCUITS

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#### programming information

Texas Instruments programmable logic devices can be programmed using widely available software and inexpensive device programmers.

Complete programming specifications, algorithms, and the latest information on hardware, software, and firmware are available upon request. Information on programmers capable of programming Texas Instruments programmable logic is also available, upon request, from the nearest TI field sales office, local authorized TI distributor, or by calling Texas Instruments at (214) 997-5666.

### preload procedure for registered outputs (see Figure 1 and Note 3)

The output registers can be preloaded to any desired state during device testing. This permits any state to be tested without having to step through the entire state-machine sequence. Each register is preloaded individually by following the steps given below.

- Step 1. With  $V_{CC}$  at 5 volts and Pin 1 at  $V_{IL}$ , raise Pin 13 to  $V_{IHH}$ .
- Step 2. Apply either  $V_{II}$  or  $V_{IH}$  to the output corresponding to the register to be preloaded.
- Step 3. Pulse Pin 1, clocking in preload data.
- Step 4. Remove output voltage, then lower Pin 13 to  $V_{IL}$ . Preload can be verified by observing the voltage level at the output pin.

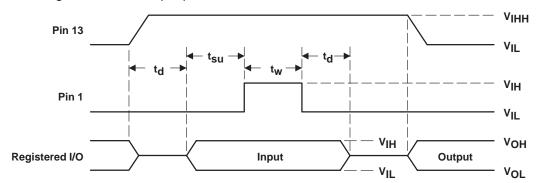


Figure 1. Preload Waveforms

NOTE 3:  $t_d = t_{SU} = t_h = 100$  ns to 1000 ns  $V_{IHH} = 10.25$  V to 10.75 v

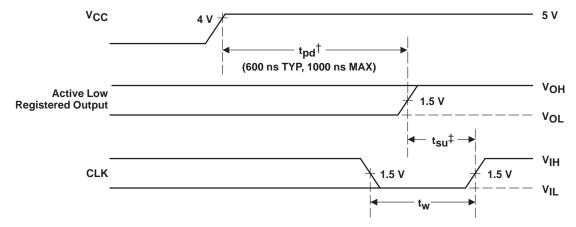


# TIBPAL20L8-7C, TIBPAL20R4-7C, TIBPAL20R6-7C, TIBPAL20R8-7C TIBPAL20L8-10M, TIBPAL20R4-10M, TIBPAL20R6-10M, TIBPAL20R8-10M HIGH-PERFORMANCE $IMPACT-X \text{ }^{TM} PAL^{\textcircled{B}} CIRCUITS$

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#### power-up reset (see Figure 2)

Following power up, all registers are reset to zero. This feature provides extra flexibility to the system designer and is especially valuable in simplifying state-machine initialization. To ensure a valid power-up reset, it is important that the rise of  $V_{CC}$  be monotonic. Following power-up reset, a low-to-high clock transition must not occur until all applicable input and feedback setup times are met.



<sup>†</sup> This is the power-up reset time and applies to registered outputs only. The values shown are from characterization data.

Figure 2. Power-Up Reset Waveforms

<sup>&</sup>lt;sup>‡</sup> This is the setup time for input or feedback.

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#### fmax SPECIFICATIONS

### f<sub>max</sub> without feedback, see Figure 3

In this mode, data is presented at the input to the flip-flop and clocked through to the Q output with no feedback. Under this condition, the clock period is limited by the sum of the data setup time and the data hold time ( $t_{su} + t_h$ ). However, the minimum  $f_{max}$  is determined by the minimum clock period ( $t_w$  high +  $t_w$  low).

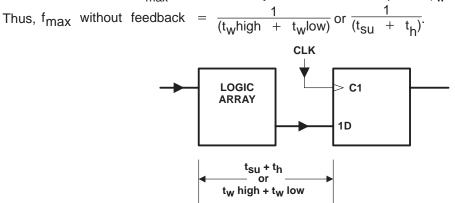


Figure 3. f<sub>max</sub> Without Feedback

### f<sub>max</sub> with internal feedback, see Figure 4

This configuration is most popular in counters and on-chip state-machine designs. The flip-flop inputs are defined by the device inputs and flip-flop outputs. Under this condition, the period is limited by the internal delay from the flip-flop outputs through the internal feedback and logic array to the inputs of the next flip-flop.

Thus, 
$$f_{max}$$
 with internal feedback =  $\frac{1}{(t_{su} + t_{pd} CLK - to - FB)}$ 

Where tpd CLK-to-FB is the deduced value of the delay from CLK to the input of the logic array.

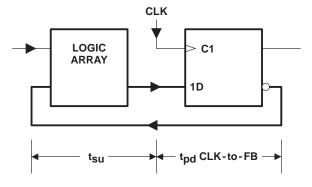


Figure 4. f<sub>max</sub> With Internal Feedback

# TIBPAL20L8-7C, TIBPAL20R4-7C, TIBPAL20R6-7C, TIBPAL20R8-7C TIBPAL20L8-10M, TIBPAL20R4-10M, TIBPAL20R6-10M, TIBPAL20R8-10M HIGH-PERFORMANCE $IMPACT-X \text{ }^{TM} PAL^{\textcircled{B}} CIRCUITS$

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#### fmax SPECIFICATIONS

### f<sub>max</sub> with external feedback, see Figure 5

This configuration is a typical state-machine design with feedback signals sent off-chip. This external feedback could go back to the device inputs or to a second device in a multi-chip state machine. The slowest path defining the period is the sum of the clock-to-output time and the input setup time for the external signals  $(t_{su} + t_{pd} CLK-to-Q)$ .

Thus,  $f_{max}$  with external feedback =  $\frac{1}{(t_{SU} + t_{pd} CLK - to - Q)}$ 

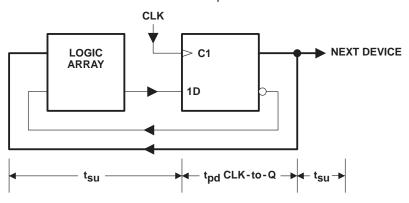
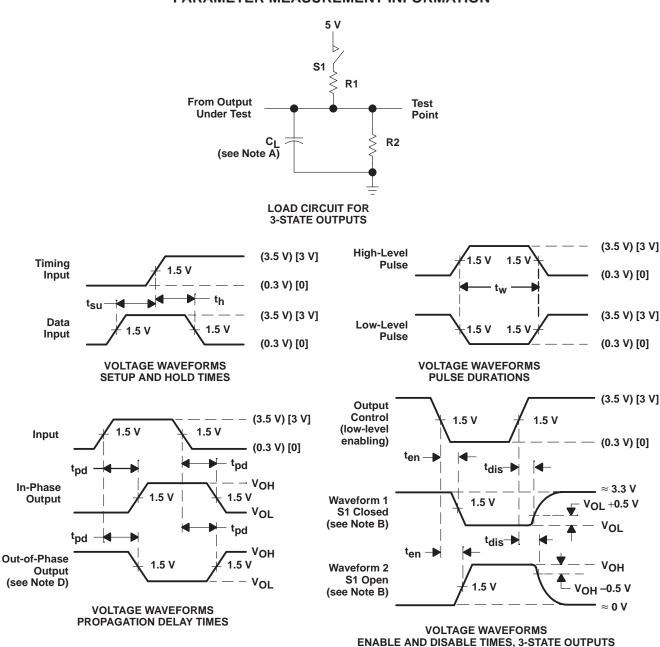


Figure 5. f<sub>max</sub> With External Feedback

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#### PARAMETER MEASUREMENT INFORMATION



NOTES: A.  $C_L$  includes probe and jig capacitance and is 50 pF for  $t_{pd}$  and  $t_{en}$ , 5 pF for  $t_{dis}$ .

- B. Waveform 1 is for an output with internal conditions such that the output is low except when disabled by the output control. Waveform 2 is for an output with internal conditions such that the output is high except when disabled by the output control.
- C. All input pulses have the following characteristics: PRR  $\leq$  10 MHz,  $t_f$  and  $t_f \leq$  2 ns, duty cycle = 50%. For C suffix, use the voltage levels indicated inparentheses ( ). For M suffix, use the voltage levels indicated in brackets [ ].
- D. When measuring propagation delay times of 3-state outputs, switch S1 is closed.
- E. Equivalent loads may be used for testing.

Figure 6. Load Circuit and Voltage Waveforms



## TIBPAL20L8-7C, TIBPAL20R4-7C, TIBPAL20R6-7C, TIBPAL20R8-7C TIBPAL20L8-10M, TIBPAL20R4-10M, TIBPAL20R6-10M, TIBPAL20R8-10M HIGH-PERFORMANCE IMPACT-X™ PAL® CIRCUITS

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#### TYPICAL CHARACTERISTICS

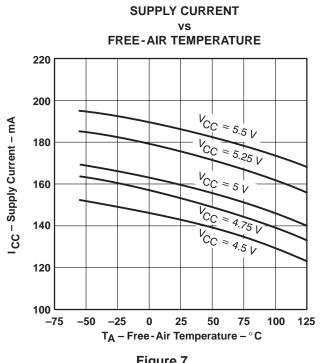


Figure 7

PROPAGATION DELAY TIME

VS

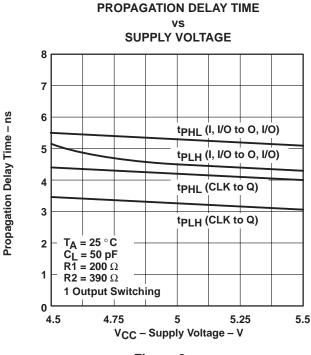


Figure 8

#### FREE-AIR TEMPERATURE 8 7 t<sub>PHL</sub> (I, I/O to O, I/O) Propagation Delay Time - ns 6 t<sub>PLH</sub> (I, I/O to O, I/O) 5 4 tpHL (CLK to Q) 3 t<sub>PLH</sub> (CLK to Q) $V_{CC} = 5 V$ 2 $C_L = 50 pF$ $R1 = 200 \Omega$ 1 $R2 = 390 \Omega$ 1 Output Switching n

Figure 9

25

TA - Free-Air Temperature - ° C

50

75

100

125

-75 -50 -25



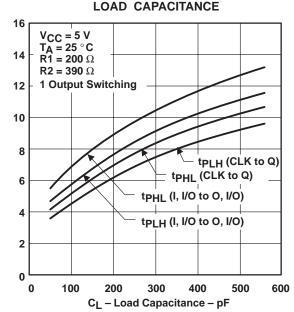


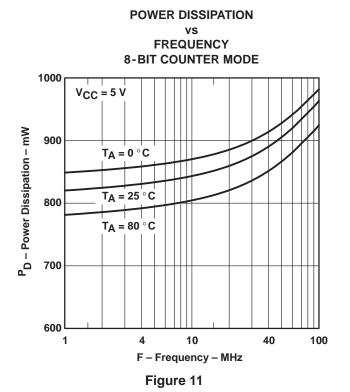
Figure 10

Propagation Delay Time - ns

# TIBPAL20L8-7C, TIBPAL20R4-7C, TIBPAL20R6-7C, TIBPAL20R8-7C TIBPAL20L8-10M, TIBPAL20R4-10M, TIBPAL20R6-10M, TIBPAL20R8-10M HIGH-PERFORMANCE $IMPACT-X^{TM}$ $PAL^{(B)}$ CIRCUITS

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#### TYPICAL CHARACTERISTICS



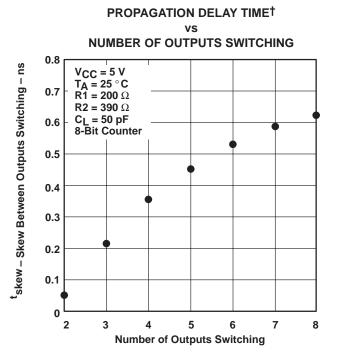


Figure 12

## PROPAGATION DELAY TIME

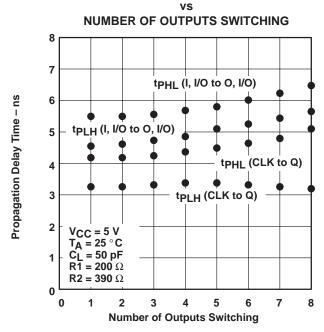


Figure 13

<sup>†</sup>Outputs switching in the same direction (tpLH compared to tpLH/tpHL to tpHL)



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