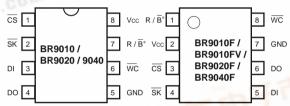
# 1, 2, and 4k bit EEPROMs for direct connection to serial ports BR9010 / BR9010F / BR9010FV / BR9020 / BR9020F / BR9040 / BR9040F

### Features

- •BR9010 / F / FV (1k bit): 64 words × 16 bits BR9020 / F (2k bit): 128 words × 16 bits BR9040 / F (4k bit): 256 words × 16 bits
- Single power supply operation
- Serial data input and output
- Automatic erase-before-write
- •Low current consumption
- -1.5mA (max.) active current: 3V
- -2μA (max.) standby current: 3V
- •Noise filter built into SK pin
- Compact DIP8, SOP8, SSOP-B8 packages (SSOP-B8 is available only with BR9010).
- •100,000 ERASE / WRITE cycles
- •10 years Data Retention
- Easily connects to serial port

# Pin assignments



\* This pin is N.C. (non connection) on BR9010

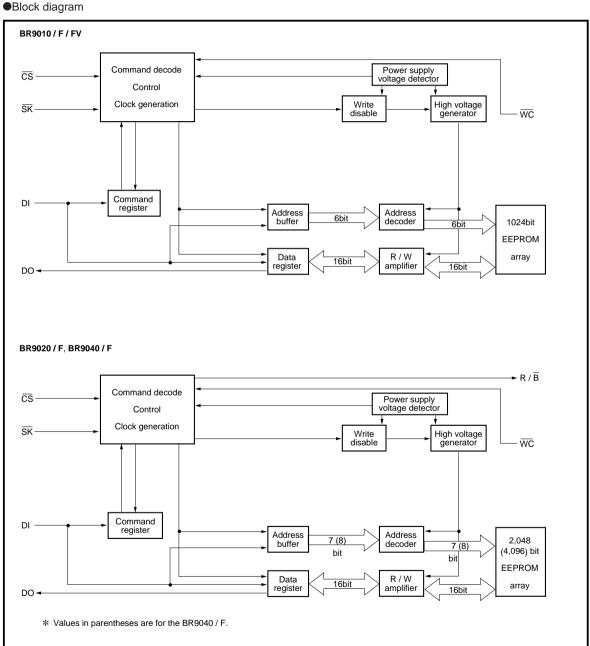
### Pin description

Pin name	Function						
CS	Chip select input						
SK	Serial data clock input						
DI	Operating code, address, and serial data input						
DO	Serial data output						
GND	Reference voltage for all I / O, 0V						
WC	Write control input						
R/B	READY, BUSY status signal output						
Vcc	Power supply connection						

### Overview

The BR90 series are serial EEPROMs that can be connected directly to a serial port and can be erased and written electrically. Writing and reading is performed in word units, using four types of operation commands. Communication occurs through  $\overline{CS}$ ,  $\overline{SK}$ , DI, and DO pins,  $\overline{WC}$  pin control is used to initiate a write disabled state, enabling these EEPROMs to be used as one-time ROMs. During writing, operation is checked via the internal status check.





# ● Absolute maximum ratings (Ta = 25°C)

Parameter	Symbol	Limits		Unit
Applied voltage	Vcc	- 0.3 ~ + 7.0		V
		DIP8	500*1	
Power dissipation	Pd	SOP8	350*2	mW
		SSOP-B8	300*3	
Storage temperature	Tstg	- 65 ~ + 125		°C
Operation temperature	Topr	- 40 ~ <b>+</b> 85		°C
Input voltage	_	- 0.3 ~ Vcc + 0.3		V

<sup>\*</sup> Reduced by 5.0mw\*1 / 3.5mw\*2 / 3.0mw\*3 for each increase in Ta of 1°C over 25°C.

# Recommended operating conditions

Parameter	Symbol	Limits	Unit
Dower ownsky voltogo	Vcc	2.7 to 5.5 (write)	V
Power supply voltage	VCC	2.0 to 5.5 (read)	V
Input voltage	Vin	0 ~ Vcc	V

# Electrical characteristics

BR9010 / F / FV: At 5V (unless otherwise noted,  $Ta = -40 \text{ to } + 85^{\circ}\text{C}$ ,  $Vcc = 5V \pm 10\%$ )

Parameter	Symbol	Min.	Тур.	Max.	Unit	Conditions
Input low level voltage 1	VIL1	_	_	0.3×	V	DI Pin
				Vcc		
Input high level voltage 1	V <sub>IH1</sub>	0.7×	_	_	V	DI Pin
		Vcc				
Input low level voltage 2	V <sub>IL2</sub>	_	_	0.2×	V	CS, SK, WC Pin
				Vcc		
Input high level voltage 2	V <sub>IH2</sub>	0.8 ×	_	_	V	CS, SK, WC Pin
		Vcc				
Output low level voltage	Vol	0	_	0.4	V	lo <sub>L</sub> = 2.1mA
Output high level voltage	Vон	Vcc-	_	Vcc	V	Iон = - 0.4mA
		0.4				
Input leak current	lu	- 1	_	1	μΑ	Vin = 0V ~ Vcc
Output leak current	ILO	- 1	_	1	μΑ	Vout = $0V \sim Vcc \overline{CS} = Vcc$
Consumption current	Icc1	_		2	mA	f = 1MHz tE / W = 10ms (WRITE)
during operation	Icc2	_	_	1	mA	f = 1MHz (READ)
Standby current	Isв	_		3	μΑ	$\overline{\text{CS}}$ , $\overline{\text{SK}}$ , DI, $\overline{\text{WC}}$ , = Vcc DO = OPEN
SK frequency	fsк			1	MHz	_

BR9010 / F / FV: At 3V (unless otherwise noted,  $Ta = -40 \text{ to} + 85^{\circ}\text{C}$ ,  $Vcc = 3V \pm 10\%$ )

Parameter	Symbol	Min.	Тур.	Max.	Unit	Conditions		
Input low level voltage 1	VIL1	_	_	0.3×	V	DI Pin		
				Vcc				
Input high level voltage 1	V <sub>IH1</sub>	0.7×	_	_	V	DI Pin		
		Vcc						
Input low level voltage 2	VIL2	_	_	0.2×	V	CS, SK, WC Pin		
				Vcc				
Input high level voltage 2	V <sub>IH2</sub>	0.8×	_	_	V	CS, SK, WC Pin		
		Vcc						
Output low level voltage	Vol	0	_	0.4	V	IoL = 100μA		
Output high level voltage	Vон	Vcc -	_	Vcc	V	$I_{OH} = -100 \mu A$		
		0.4						
Input leak current	lц	-1	_	1	μΑ	Vin = 0 ~ Vcc		
Output leak current	ILO	-1	_	1	μΑ	$V_{OUT} = 0 \sim V_{CC} \overline{CS} = V_{CC}$		
Consumption current	Icc1	_	_	1.5	mA	f = 1MHz tE / W = 15ms (WRITE)		
during operation	Icc2	_		500	μΑ	f = 1MHz (READ)		
Standby current	Isa	_	_	2	μΑ	$\overline{\text{CS}}$ , $\overline{\text{SK}}$ , DI, $\overline{\text{WC}}$ , = Vcc DO = OPEN		
SK frequency	fsĸ		_	1	MHz	_		

# •Electrical characteristics

•BR9020 / F: At 5V (unless otherwise noted,  $Ta = -40 \text{ to} + 85^{\circ}\text{C}$ ,  $Vcc = 5V \pm 10\%$ )

Parameter	Symbol	Min.	Тур.	Max.	Unit	Conditions
Input low level voltage 1	VIL1	_	_	0.3 × Vcc	V	DI Pin
Input high level voltage 1	V <sub>IH1</sub>	0.7 × Vcc	_	_	V	DI Pin
Input low level voltage 2	VIL2	_		0.2 × Vcc	V	CS, SK, WC Pin
Input high level voltage 2	V <sub>IH2</sub>	0.8 × Vcc	-	_	V	CS, SK, WC Pin
Output low level voltage	Vol	0	I	0.4	V	IoL = 2.1mA
Output high level voltage	Vон	Vcc - 0.4	I	Vcc	V	Iон = - 0.4mA
Input leak current	lμ	<b>– 1</b>	-	1	μΑ	Vin = 0V ~ Vcc
Output leak current	ILO	<b>–</b> 1	_	1	μΑ	Vout = 0V ~ Vcc $\overline{\text{CS}}$ = Vcc
Consumption current	Icc1	_	-	2	mA	fsk = 1MHz tE / W = 10ms (WRITE)
during operation	Icc2	_	I	1	mA	fsk = 1MHz (READ)
Standby current	Isa	_		3	μΑ	$\overline{\text{CS}}$ , $\overline{\text{SK}}$ , DI, $\overline{\text{WC}}$ , = Vcc DO, R / $\overline{\text{B}}$ = OPEN
SK frequency	fsк	_	_	1	MHz	_

# $\bullet$ BR9020 / F: At 3V (unless otherwise noted, Ta = -40 to +85°C, Vcc = 3V $\pm$ 10%)

Parameter	Symbol	Min.	Тур.	Max.	Unit	Conditions
Input low level voltage 1	VIL1	_	_	0.3 × Vcc	V	DI Pin
Input high level voltage 1	V <sub>IH1</sub>	0.7 × Vcc		_	V	DI Pin
Input low level voltage 2	V <sub>IL2</sub>	_		0.2 × Vcc	V	CS, SK, WC Pin
Input high level voltage 2	V <sub>IH2</sub>	0.8 × Vcc	_	_	V	CS, SK, WC Pin
Output low level voltage	Vol	0	_	0.4	V	IoL = 100μA
Output high level voltage	Vон	Vcc - 0.4		Vcc	V	Іон = − 100μА
Input leak current	lu	- 1	_	1	μΑ	Vin = 0V ~ Vcc
Output leak current	ILO	<b>– 1</b>		1	μΑ	Vout = 0V ~ Vcc $\overline{CS}$ = Vcc
Consumption current	Icc1	_	_	1.5	mA	fsk = 1MHz tE / W = 15ms (WRITE)
during operation	Icc2	_	_	500	μΑ	fsk = 1MHz (READ)
Standby current	Isa	_	_	2	μΑ	$\overline{\text{CS}}$ , $\overline{\text{SK}}$ , DI, $\overline{\text{WC}}$ , = Vcc DO, R / $\overline{\text{B}}$ = OPEN
SK frequency	fsк	_	_	1	MHz	_

# Electrical characteristics

 $\bullet$ BR9040 / F: At 5V (unless otherwise noted, Ta = -40 to +85°C, Vcc = 5V  $\pm$  10%)

Parameter	Symbol	Min.	Тур.	Max.	Unit	Conditions
Input low level voltage 1	VIL1	_	_	0.3 × Vcc	V	DI Pin
Input high level voltage 1	V <sub>IH1</sub>	0.7 × Vcc	_	_	٧	DI Pin
Input low level voltage 2	VIL2	_	_	0.2 × Vcc	V	CS, SK, WC Pin
Input high level voltage 2	V <sub>IH2</sub>	0.8 × Vcc	_	_	V	CS, SK, WC Pin
Output low level voltage	Vol	0	_	0.4	V	IoL = 2.1mA
Output high level voltage	Vон	Vcc - 0.4	_	Vcc	٧	Іон = - 0.4mA
Input leak current	lu	- 1	_	1	μΑ	VIN = 0V ~ VCC
Output leak current	ILO	- 1	_	1	μΑ	Vout = 0V ~ Vcc $\overline{\text{CS}}$ = Vcc
Consumption current	Icc1	_	_	2	mA	fsk = 1MHz tE / W = 10ms (WRITE)
during operation	Icc2	_	_	1	mA	fsk = 1MHz (READ)
Standby current	lsв	_	_	3	μΑ	$\overline{\text{CS}}$ , $\overline{\text{SK}}$ , DI, $\overline{\text{WC}}$ , = Vcc DO, R / $\overline{\text{B}}$ = OPEN
SK frequency	fsк	_	_	1	MHz	_

# $\bullet$ BR9040 / F: At 3V (unless otherwise noted, Ta = -40 to +85°C, Vcc = 3V $\pm$ 10%)

Parameter	Symbol	Min.	Тур.	Max.	Unit	Conditions
Input low level voltage 1	VIL1	_	_	0.3 × Vcc	V	DI Pin
Input high level voltage 1	V <sub>IH1</sub>	0.7 × Vcc	_	_	V	DI Pin
Input low level voltage 2	VIL2	_		0.2 × Vcc	V	CS, SK, WC Pin
Input high level voltage 2	V <sub>IH2</sub>	0.8 × Vcc		_	V	CS, SK, WC Pin
Output low level voltage	Vol	0		0.4	V	IoL = 100μA
Output high level voltage	Vон	Vcc - 0.4	ı	Vcc	V	Іон = — 100µА
Input leak current	lu	<b>- 1</b>		1	μА	Vin = 0V ~ Vcc
Output leak current	ILO	<b>– 1</b>		1	μА	Vout = 0V ~ Vcc $\overline{\text{CS}}$ = Vcc
Consumption current	Icc1	_		1.5	mA	fsk = 1MHz tE / W = 15ms (WRITE)
during operation	Icc2	_		500	μА	fsk = 1MHz (READ)
Standby current	lsв	_	_	2	μА	$\overline{\text{CS}}$ , $\overline{\text{SK}}$ , DI, $\overline{\text{WC}}$ , = Vcc DO, R / $\overline{\text{B}}$ = OPEN
CK fraguancy	<b>6</b>	_	_	1	MHz	Vcc = 3.0 ~ 3.3V
SK frequency	fsк	_	_	750	kHz	Vcc = 2.7 ~ 3.0V

# Operation timing characteristics

BR9010 / F / FV: At 5V (unless otherwise noted,  $Ta = -40 \text{ to} + 85^{\circ}\text{C}$ ,  $Vcc = 5V \pm 10\%$ )

Parameter	Symbol	Min.	Тур.	Max.	Unit
CS setup time	tcss	200	_	_	ns
CS hold time	tсsн	0	_	_	ns
Data setup time	tois	150	_	_	ns
Data hold time	tын	150	_	_	ns
DO rise delay time	t <sub>PD1</sub>	_	_	350	ns
DO fall delay time	t <sub>PD0</sub>	_	_	350	ns
Self-timing programming cycle	t <sub>E</sub> /w	_	_	10	ms
CS minimum high level time	tcs	1	_	_	μs
Time when DO goes High-Z (via CS)	tон	0	_	400	ns
Data clock high level time	twн	450	_	_	ns
Data clock low level time	tw∟	450	_	_	ns
Write control setup time	twcs	0	_	_	ns
Write control hold time	twcн	0	_	_	ns

# $\bullet$ BR9010 / F / FV: At 3V (unless otherwise noted, Ta = -40 to +85°C, Vcc = 3V $\pm$ 10%)

Parameter	Symbol	Min.	Тур.	Max.	Unit
CS setup time	tcss	200	_	_	ns
CS hold time	tсsн	0	_	_	ns
Data setup time	tois	150	_	_	ns
Data hold time	tын	150	_	_	ns
DO rise delay time	t <sub>PD1</sub>	_	_	350	ns
DO fall delay time	t <sub>PD0</sub>	_	_	350	ns
Self-timing programming cycle	te/w	_	_	15	ms
CS minimum high level time	tcs	1	_	_	μs
Time when DO goes High-Z (via $\overline{\text{CS}}$ )	tон	0	_	400	ns
Data clock high level time	twн	450	_	_	ns
Data clock low level time	tw∟	450	_	_	ns
Write control setup time	twcs	0	_	_	ns
Write control hold time	twcн	0	_	_	ns

# Operation timing characteristics

BR9020 / F / FV: At 5V (unless otherwise noted,  $Ta = -40 \text{ to } + 85^{\circ}\text{C}$ ,  $Vcc = 5V \pm 10\%$ )

Parameter	Symbol	Min.	Тур.	Max.	Unit
CS setup time	tcss	200	_	_	ns
CS hold time	tсsн	0	_	_	ns
Data setup time	tois	150	_	_	ns
Data hold time	tын	150	_	_	ns
DO rise delay time	t <sub>PD1</sub>	_	_	350	ns
DO fall delay time	t <sub>PD0</sub>	_	_	350	ns
Self-timing programming cycle	t <sub>E</sub> /w	_	_	10	ms
CS minimum high level time	tcs	1	_	_	μs
READY / BUSY display valid time	tsv	_	_	1	μs
Time when DO goes High-Z (via CS)	tон	0	_	400	ns
Data clock high level time	twн	450	_	_	ns
Data clock low level time	tw∟	450	_	_	ns
Write control setup time	twcs	0	_	_	ns
Write control hold time	twcн	0	_	_	ns

# $\bullet$ BR9020 / F / FV: At 3V (unless otherwise noted, Ta = -40 to +85°C, Vcc = 3V $\pm$ 10%)

Parameter	Symbol	Min.	Тур.	Max.	Unit
CS setup time	tcss	200	_	_	ns
CS hold time	tсsн	0	_	_	ns
Data setup time	tois	150	_	_	ns
Data hold time	tын	150	_	_	ns
DO rise delay time	t <sub>PD1</sub>	_	_	350	ns
DO fall delay time	t <sub>PD0</sub>	_	_	350	ns
Self-timing programming cycle	te/w	_	_	15	ms
CS minimum high level time	tcs	1	_	_	μs
READY / BUSY display valid time	tsv	_	_	1	μs
Time when DO goes High-Z (via CS)	tон	0	_	400	ns
Data clock high level time	twн	450	_	_	ns
Data clock low level time	twL	450	_	_	ns
Write control setup time	twcs	0	_	_	ns
Write control hold time	twcн	0	_	_	ns

# Operation timing characteristics

BR9040 / F: At 5V (unless otherwise noted,  $Ta = -40 \text{ to} + 85^{\circ}\text{C}$ ,  $Vcc = 5V \pm 10\%$ )

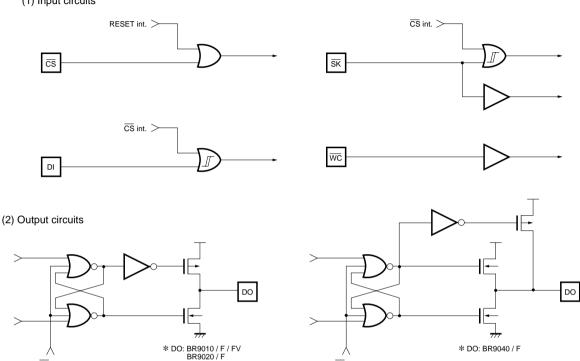
Parameter	Symbol	Min.	Тур.	Max.	Unit
CS setup time	tcss	200	_	_	ns
CS hold time	tсsн	0	_	_	ns
Data setup time	tois	150	_	_	ns
Data hold time	tын	150	_	_	ns
DO rise delay time	<b>t</b> PD1	_	_	350	ns
DO fall delay time	t <sub>PD0</sub>	_	_	350	ns
Self-timing programming cycle	t <sub>E</sub> /w	_	_	10	ms
CS minimum high level time	tcs	1	_	_	μs
READY / BUSY display valid time	<b>t</b> sv	_	_	1	μs
Time when DO goes High-Z (via CS)	tон	0	_	400	ns
Data clock high level time	twн	500	_	_	ns
Data clock low level time	twL	500	_	_	ns
Write control setup time	twcs	0	_	_	ns
Write control hold time	twcн	0	_	_	ns

# •BR9040 / F: At 3V (unless otherwise noted, $Ta = -40 \text{ to} + 85^{\circ}\text{C}$ , $Vcc = 3V \pm 10\%$ )

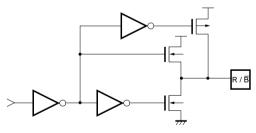
Parameter	Symbol	Min.	Тур.	Max.	Unit
CS setup time	tcss	200	_	_	ns
CS hold time	tсsн	0	_	_	ns
Data setup time	tois	150	_	_	ns
Data hold time	<b>t</b> DIH	150	_	_	ns
DO rise delay time Vcc = 3.0 ~ 3.3V	<b>t</b> PD1	_	_	350	ns
DO fall delay time Vcc = 3.0 ~ 3.3V	t <sub>PD0</sub>	_	_	350	ns
DO rise delay time Vcc = 2.7 ~ 3.0V	<b>t</b> PD1	_	_	500	ns
DO fall delay time Vcc = 2.7 ~ 3.0V	t <sub>PD0</sub>	_	_	500	ns
Self-timing programming cycle	te/w	_	_	15	ms
CS minimum high level time	tcs	1	_	_	μs
READY / BUSY display valid time	tsv	_	_	1	μs
Time when DO goes High-Z (via $\overline{\text{CS}}$ )	tон	0	_	400	ns
Data clock high level time Vcc = 3.0 ~ 3.3V	twн	500	_	_	ns
Data clock low level time Vcc = 3.0 ~ 3.3V	twL	500	_	_	ns
Data clock high level time Vcc = 2.7 ~ 3.0V	twн	650	_	_	ns
Data clock low level time Vcc = 2.7 ~ 3.0V	twL	650	_	_	ns
Write control setup time	twcs	0	_	_	ns
Write control hold time	twcн	0	_	_	ns

# ●Input / output circuits

### (1) Input circuits



OE int.



R / B: BR9020 / F, BR9040 / F

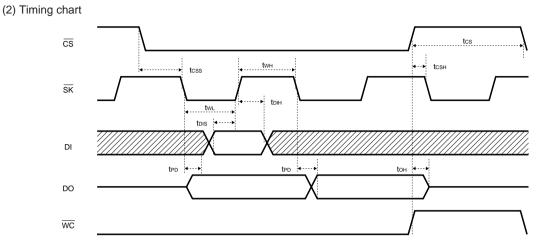
# Circuit operation

ŌĒ int.

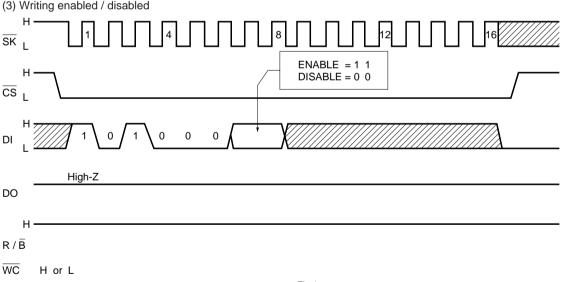
# (1) Command mode

Command		Start bit	Operating code	Address	Data
Read	(READ)	1010	1000	A0 A1 A2 A3 A4 A5 (A6) <sup>☆2</sup> (A7) <sup>☆1</sup>	
Write	(WRITE)	1010	0100	A0 A1 A2 A3 A4 A5 (A6) <sup>☆2</sup> (A7) <sup>☆1</sup>	D0 D1—D14 D15
Erase / Write enabled	(EWEN)	1010	0011	* * * * * * *	
Erase / Write disable	(EWDS)	1010	0000	* * * * * * * *	

<sup>\*</sup> Either V<sub>IH</sub> or V<sub>IL</sub>



- Data is read in on the rising edge of SK. Data is output in synchronism with the SK falling edge.
- ullet During a READ operation, data is output from DO in synchronization with the  $\overline{\mbox{SK}}$  rise.
- WC is related to the write command only. Read, erase / write enable, erase / write disable commands can be executed irrespective of the state of WC.



- Fig.1
- 1) When the power supply is turned on, the latch used to acknowledge writing is reset in the same way as when the write disable command is executed. Before entering the write mode, the write enabled mode must first be entered. Once the write enabled mode has been recognized, it remains valid until the write disabled mode is entered, or the power supply is turned off.
- 2) The clock is no longer necessary after the first 16 clock pulses have been received. Any subsequent input will be ignored.
- 3) WC does not exist for either the write enabled or write disabled command, so WC may be either HIGH or LOW when the command is being input.
- 4) Commands are received in these modes by means of 8-bit operating codes. Please be aware that, after an operating code has been entered, commands will not be canceled even if  $\overline{\text{CS}}$  is set to HIGH. (To cancel a command, sith and the action of the action of the command and the cancel of the command o

# Circuit operation

 $R/\overline{B}$  $\overline{WC}$ 

H or L

(4) Read cycle

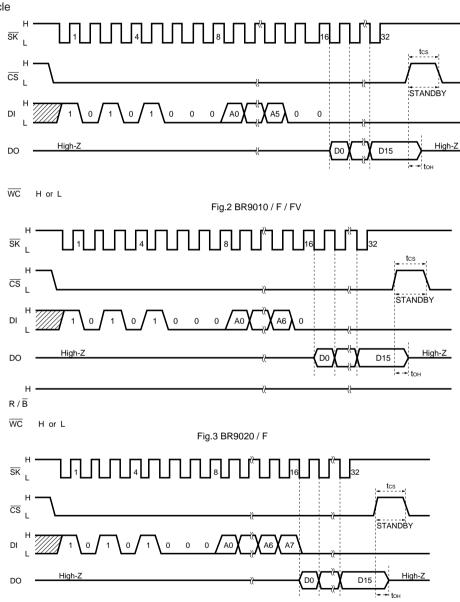


Fig.4 BR9040 / F

<sup>1)</sup> After the fall of the 16th clock pulse, 16-bit data is output from the DO pin in synchronization with the falling edge of the  $\overline{SK}$  signal. (DO output changes at a time lag of  $t_{PD0}$ ,  $t_{PD1}$  because of internal circuit delay following the falling edge of the  $\overline{SK}$  signal. During the  $t_{PD0}$  and  $t_{PD1}$  timing, the  $t_{PD}$  time should be assured before data is read, to avoid the previous data being lost. See the synchronized

# Circuit operation

(5) Writing cycle

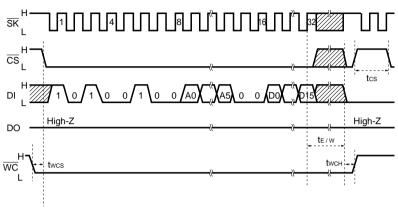


Fig.5 BR9010 / F / FV

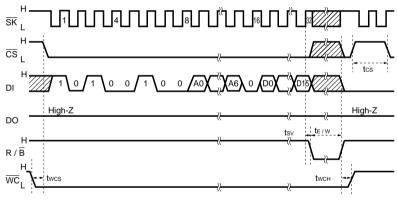


Fig.6 BR9020 / F

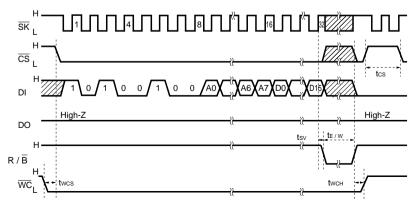


Fig.7 BR9040 / F

- 1) During input in the write mode,  $\overline{CS}$  must be LOW, but once writing starts,  $\overline{CS}$  may be either HIGH or LOW. However, if  $\overline{CS}$  and  $\overline{WC}$  share the same connection, both  $\overline{CS}$  and  $\overline{WC}$  should be set to LOW during writing operations.
  - (If the WC pin is set to HIGH during a writing operation, writing will be forcibly interrupted at that point. If this happens, the data for that address may be lost, in which case it should be rewritten to that address.)
- 2) Following input of a write command,  $\overline{CS}$  goes HIGH. If  $\overline{CS}$  is then set to LOW, data will be received from  $\overline{SK}$  and DI, because the command reception status has been entered.
  - If  $\overline{\text{CS}}$  remains LOW following command input, however, without first going HIGH, command input will be canceled until  $\overline{\text{CS}}$  is set to HIGH.
- 3) Starting from the rising edge of the 32nd clock, the R /  $\overline{B}$  pin goes LOW after RSV has elapsed.
- 4) The R /  $\overline{B}$  pin is LOW during writing operations. (Following the rising edge of  $\overline{SK}$  after the last data D15 has been read, the internal timer circuit is activated, and writing of data in the memory cell is automatically completed during te/w.) At this point,  $\overline{SK}$  input may be either HIGH or LOW during te/w.
- 5) Following input of a write command, if  $\overline{CS}$  falls while  $\overline{SK}$  is LOW, the R /  $\overline{B}$  status can be displayed from the DO pin. (See the section on READY /  $\overline{BUSY}$  states.)
- (6) READY / BUSY display (R / B pin and DO pin)
- 1) This display outputs the internal status signal; the R /  $\overline{B}$  pin outputs the HIGH or LOW status at all times. The display can also be output from the DO pin. Following completion of the writing command, if  $\overline{CS}$  falls while  $\overline{SK}$  is LOW, either HIGH or LOW is output. (The display can also be output without using the R /  $\overline{B}$  pin, leaving it open.)
- 2) When writing data to a memory cell, the READY /  $\overline{BUSY}$  display is output from the rise of the 32nd clock pulse of the  $\overline{SK}$  signal after tsv, from the R /  $\overline{B}$  pin.

 $R / \overline{B}$  display = LOW: writing in progress

(The internal timer circuit is activated, and after the te/w timing has been created, the timer circuit stops automatically. Writing of data to the memory cell is done during the te/w timing, during which time other commands cannot be received.)

 $R / \overline{B}$  display = HIGH: command standby state

(Writing of data to the memory cell has been completed and the next command can be received.)

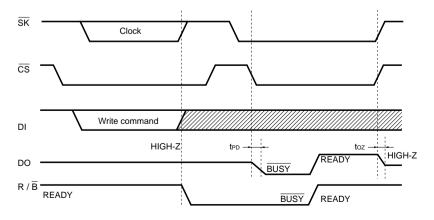


Fig. 8 R /  $\overline{B}$  status output timing

### Operation notes

- (1) Turning the power supply on and off
- 1) When the power supply is turned on and off,  $\overline{CS}$  should be set to HIGH (= Vcc).
- 2) When  $\overline{CS}$  is LOW, the command input reception state (active) is entered. If the power supply is turned on in this state, erroneous operations and erroneous writing can occur because of noise and other factors. To avoid this, make sure  $\overline{CS}$  is set to HIGH (= Vcc) before turning on the power supply.

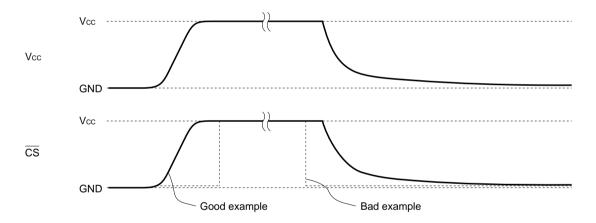
(Good example) Here, the  $\overline{CS}$  pin is pulled up to Vcc.

When turning off the power supply, wait at least 10msec before turning it on again. Failing to observe this condition can result in the internal circuit failing to be reset when the power supply is turned on.

(Bad example)  $\overline{CS}$  is LOW when the power supply is turned on or off

In this case, because  $\overline{\text{CS}}$  remains LOW, the EEPROM may perform erroneous operations or write erroneous data because of noise or other factors.

\* Please be aware that the case shown in this example can also occur if CS input is HIGH-Z.



### (2) Noise countermeasures

1) SKnoise

If noise occurs at the rise of the  $\overline{SK}$  clock input, the clock is assumed to be excessive, and this can cause malfunction because the bits are out of alignment.

2) WC noise

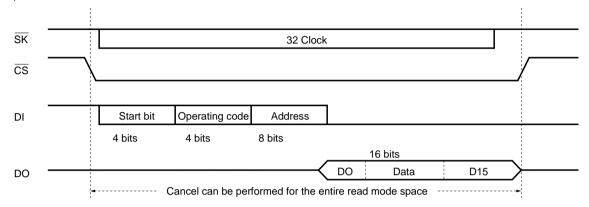
During a writing operation, noise at the  $\overline{WC}$  pin can be erroneously judged to be data, and this can cause writing to be forcibly interrupted.

3) Vcc noise

Noise and surges on the power supply line can cause malfunction. We recommend installing a bypass capacitor between the power supply and ground to eliminate this problem.

### (3) Canceling modes

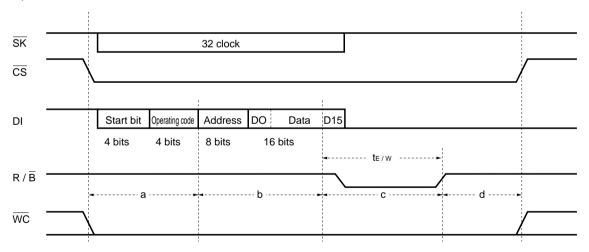
1) Read commands



WC H or L

Cancellation method: CS HIGH

### 2) Write commands



### Canceling methods

- a: Canceled by setting  $\overline{\text{CS}}$  HIGH. The  $\overline{\text{WC}}$  pin is not involved.
- b: If the WC pin goes HIGH for even a second, writing is forcibly interrupted. Cancellation occurs even if the CS pin is HIGH. At this point, data has not been written to the memory, so the data in the designated address has not yet been changed.
- c: The operation is forcibly canceled by setting the WC pin to HIGH or turning off the power supply (although we do not recommend using this method). The data in the designated address is not guaranteed and should be written once again.
- d: If  $\overline{CS}$  is set to HIGH while the R /  $\overline{B}$  signal is HIGH (following the te/w timing), the IC is reset internally, and waits for the next command to be input.

# ●External dimensions (Units: mm)

