捷多邦,专业PCB打样工厂,24小时加**多N74AVCH1T45**

SINGLE-BIT DUAL-SUPPLY BUS TRANSCEIVER

WITH CONFIGURABLE VOLTAGE TRANSLATION AND 3-STATE OUTPUTS

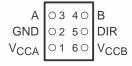
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- Available in the Texas Instruments
 NanoStar™ and NanoFree™ Packages
- Control Inputs V_{IH}/V_{IL} Levels Are Referenced to V_{CCA} Voltage
- Fully Configurable Dual-Rail Design Allows Each Port to Operate Over the Full 1.2-V to 3.6-V Power-Supply Range
- I/Os Are 4.6-V Tolerant
- I_{off} Supports Partial-Power-Down Mode Operation
- Bus Hold on Data Inputs Eliminates the Need for External Pullup/Pulldown Resistors
- Latch-Up Performance Exceeds 100 mA Per JESD 78, Class II
- ESD Protection Exceeds JESD 22
 - 2000-V Human-Body Model (A114-A)
 - 200-V Machine Model (A115-A)
 - 1000-V Charged-Device Model (C101)

DBV OR DCK PACKAGE (TOP VIEW)



YEP OR YZP PACKAGE (BOTTOM VIEW)



description/ordering information

This single-bit noninverting bus transceiver uses two separate configurable power-supply rails. The A port is designed to track V_{CCA} . V_{CCA} accepts any supply voltage from 1.2 V to 3.6 V. The B port is designed to track V_{CCB} . V_{CCB} accepts any supply voltage from 1.2 V to 3.6 V. This allows for universal low-voltage bidirectional translation between any of the 1.2-V, 1.5-V, 1.8-V, 2.5-V, and 3.3-V voltage nodes.

The SN74AVCH1T45 is designed for asynchronous communication between data buses. The device transmits data from the A bus to the B bus or from the B bus to the A bus, depending on the logic level at the direction-control (DIR) input.

The SN74AVCH1T45 is designed so that the DIR input is powered by V_{CCA} .

ORDERING INFORMATION

| TA | PACKAGET | PACKAGE [†] | | | |
|---------------|--|----------------------|------------------|------------|--|
| | NanoStar™ – WCSP (DSBGA) 0.23-mm Large Bump – YEP | | SN74AVCH1T45YEPR | 玛阿 | |
| -40°C to 85°C | NanoFree™ – WCSP (DSBGA) 0.23-mm Large Bump – YZP (Pb-free) | Tape and reel | SN74AVCH1T45YZPR | SC -UFL IN | |
| | SOT (SOT-23) – DBV | Tape and reel | SN74AVCH1T45DBVR | ET1_ | |
| | SOT (SC-70) – DCK | Tape and reel | SN74AVCH1T45DCKR | TF_ | |

[†] Package drawings, standard packing quantities, thermal data, symbolization, and PCB design guidelines are available at www.ti.com/sc/package.

Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.





DBV/DCK: The actual top-side marking has one additional character that designates the assembly/test site.

YEP/YZP: The actual top-side marking has three preceding characters to denote year, month, and sequence code, and one following character to designate the assembly/test site. Pin 1 identifier indicates solder-bump composition (1 = SnPb, • = Pb-free).

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description/ordering information (continued)

This device is fully specified for partial-power-down applications using I_{off}. The I_{off} circuitry disables the outputs, preventing damaging current backflow through the device when it is powered down.

The V_{CC} isolation feature ensures that if either V_{CC} input is at GND, then both outputs are in the high-impedance state. The bus-hold circuitry on the powered-up side always stays active.

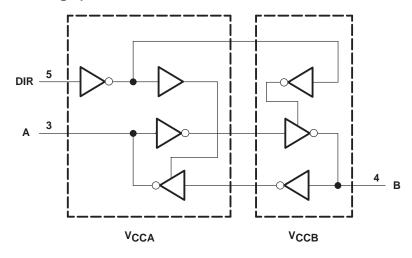
Active bus-hold circuitry holds unused or undriven inputs at a valid logic state. Use of pullup or pulldown resistors with the bus-hold circuitry is not recommended.

NanoStar™ and NanoFree™ package technology is a major breakthrough in IC packaging concepts, using the die as the package.

FUNCTION TABLE

| INPUT DIR | OPERATION |
|--------------|-----------------|
| L | B data to A bus |
| Н | A data to B bus |

logic diagram (positive logic)





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absolute maximum ratings over operating free-air temperature range (unless otherwise noted)

| Supply voltage range, V _{CCA} and V _{CCB} | –0.5 V to 4.6 V |
|--|--|
| Control inputs | |
| Voltage range applied to any output in the high-impedance or power-off state, Vo | |
| (see Note 1): A port | 0.5 V to 4.6 V |
| B port | 0.5 V to 4.6 V |
| Voltage range applied to any output in the high or low state, VO | |
| (see Notes 1 and 2): A port | |
| B port | \cdot -0.5 V to V _{CCB} + 0.5 V |
| Input clamp current, I_{IK} ($V_I < 0$) | –50 mA |
| Output clamp current, I _{OK} (V _O < 0) | |
| Continuous output current, IO | ±50 mA |
| Continuous current through V _{CCA} , V _{CCB} , or GND | |
| Package thermal impedance, θ_{JA} (see Note 3): DBV package | |
| DCK package | |
| YEP/YZP package | |
| Storage temperature range, T _{stg} | –65°C to 150°C |

[†] Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

NOTES: 1. The input voltage and output negative-voltage ratings may be exceeded if the input and output current ratings are observed.

- 2. The output positive-voltage rating may be exceeded up to 4.6 V maximum if the output current rating is observed.
- 3. The package thermal impedance is calculated in accordance with JESD 51-7.

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recommended operating conditions (see Notes 4 through 8)

| | | | VCCI | Vcco | MIN | MAX | UNIT |
|-------|----------------------------|-----------------------------------|-----------------|------------------|-------------------------|-------------------------|------|
| VCCA | Supply voltage | | | | 1.2 | 3.6 | V |
| Vссв | Supply voltage | | | | 1.2 | 3.6 | V |
| | | . | 1.2 V to 1.95 V | | V _{CCI} ×0.65 | | |
| VIH | High-level input voltage | Data inputs (see Note 7) | 1.95 V to 2.7 V | | 1.6 | | V |
| | voltage | (300 14010 1) | 2.7 V to 3.6 V | | 2 | | |
| | | . | 1.2 V to 1.95 V | | | $V_{CCI} \times 0.35$ | |
| VIL | Low-level input voltage | Data inputs (see Note 7) | 1.95 V to 2.7 V | | | 0.7 | V |
| | voltage | (See Note 1) | 2.7 V to 3.6 V | | | 0.8 | |
| | | DIR | 1.2 V to 1.95 V | | V _{CCA} × 0.65 | | |
| VIH | High-level input voltage | (referenced to V _{CCA}) | 1.95 V to 2.7 V | | 1.6 | | V |
| | voltage | (see Note 8) | 2.7 V to 3.6 V | | 2 | | |
| | | DIR | 1.2 V to 1.95 V | | | V _{CCA} × 0.35 | |
| VIL | Low-level input voltage | (referenced to V _{CCA}) | 1.95 V to 2.7 V | | | 0.7 | V |
| | voltage | (see Note 8) | 2.7 V to 3.6 V | | | 0.8 | |
| VI | Input voltage | | | | 0 | 3.6 | V |
| ., | 0 | Active state | | | 0 | Vcco | ., |
| Vo | Output voltage | 3-state | | | 0 | 3.6 | V |
| | | | | 1.2 V | | -3 | |
| | | | | 1.4 V to 1.6 V | | -6 | |
| lOH | High-level output currer | nt | | 1.65 V to 1.95 V | | -8 | mA |
| | | | | 2.3 V to 2.7 V | | -9 | |
| | | | | 3 V to 3.6 V | | -12 | |
| | | | | 1.2 V | | 3 | |
| | | | | 1.4 V to 1.6 V | | 6 | |
| loL | Low-level output currer | t | | 1.65 V to 1.95 V | | 8 | mA |
| | | | | 2.3 V to 2.7 V | | 9 | |
| | | | | 3 V to 3.6 V | | 12 | |
| Δt/Δν | Input transition rise or f | all rate | | | | 5 | ns/V |
| TA | Operating free-air temp | erature | | | -40 | 85 | °C |

NOTES: 4. V_{CCI} is the V_{CC} associated with the data input port.

- 5. V_{CCO} is the V_{CC} associated with the output port.
- All unused data inputs of the device must be held at V_{CCI} or GND to ensure proper device operation. Refer to the TI application report, Implications of Slow or Floating CMOS Inputs, literature number SCBA004.
- 7. For V_{CCI} values not specified in the data sheet, V_{IH} min = $V_{CCI} \times 0.7$ V, V_{IL} max = $V_{CCI} \times 0.3$ V.
- 8. For V_{CCI} values not specified in the data sheet, V_{IH} min = V_{CCA} × 0.7 V, V_{IL} max = V_{CCA} × 0.3 V.

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electrical characteristics over recommended operating free-air temperature range (unless otherwise noted) (see Notes 9 and 10)

| | | TEGT 001/DU | FIGNIC | | ., | T, | Δ = 25°C | ; | -40°C to 85°C | | LINUT | |
|-------------------|-------------------------|--|----------------|----------------|----------------|-----|----------|-------|--------------------|-------|-------|--|
| PARAI | METER | TEST CONDI | IIONS | VCCA | VCCB | MIN | TYP | MAX | MIN | MAX | UNIT | |
| | | $I_{OH} = -100 \mu A$ | | 1.2 V to 3.6 V | 1.2 V to 3.6 V | | | | V _{CCO} - | 0.2 V | | |
| | | $I_{OH} = -3 \text{ mA}$ | | 1.2 V | 1.2 V | | 0.95 | | | | | |
| ., | | $I_{OH} = -6 \text{ mA}$ |],, ,, | 1.4 V | 1.4 V | | | | 1.05 | | ., | |
| VOH | | $I_{OH} = -8 \text{ mA}$ | $V_I = V_{IH}$ | 1.65 V | 1.65 V | | | | 1.2 | | V | |
| | | $I_{OH} = -9 \text{ mA}$ | | 2.3 V | 2.3 V | | | | 1.75 | | | |
| | | $I_{OH} = -12 \text{ mA}$ | | 3 V | 3 V | | | | 2.3 | | | |
| | | I _{OL} = 100 μA | | 1.2 V to 3.6 V | 1.2 V to 3.6 V | | | | | 0.2 | | |
| Vol | | I _{OL} = 3 mA | VI = VIL | 1.2 V | 1.2 V | | 0.15 | | | | | |
| | | $I_{OL} = 6 \text{ mA}$ | | 1.4 V | 1.4 V | | | | | 0.35 | ., | |
| | | I _{OL} = 8 mA | | 1.65 V | 1.65 V | | | | | 0.45 | V | |
| | | I _{OL} = 9 mA | 1 | 2.3 V | 2.3 V | | | | | 0.55 | | |
| | | I _{OL} = 12 mA | 1 | 3 V | 3 V | | | | | 0.7 | | |
| IĮ | DIR input | V _I = V _{CCA} or GNE |) | 1.2 V to 3.6 V | 1.2 V to 3.6 V | | ±0.025 | ±0.25 | | ±1 | μΑ | |
| | V _I = 0.42 V | | | 1.2 V | 1.2 V | | 25 | | | | | |
| | | V _I = 0.49 V | | 1.4 V | 1.4 V | | | | 15 | | | |
| IBHL [†] | | V _I = 0.58 V | | 1.65 V | 1.65 V | | | | 25 | | μΑ | |
| | | V _I = 0.7 V | | 2.3 V | 2.3 V | | | | 45 | | | |
| | | V _I = 0.8 V | | 3.3 V | 3.3 V | | | | 100 | | | |
| | | V _I = 0.78 V | | 1.2 V | 1.2 V | | -25 | | | | | |
| | | V _I = 0.91 V | | 1.4 V | 1.4 V | | | | -15 | | | |
| _{lвнн} ‡ | | V _I = 1.07 V | | 1.65 V | 1.65 V | | | | -25 | | μΑ | |
| | | V _I = 1.6 V | | 2.3 V | 2.3 V | | | | -45 | | | |
| | | V _I = 2 V | | 3.3 V | 3.3 V | | | | -100 | | | |
| | | | | 1.2 V | 1.2 V | | 50 | | | | | |
| | | | | 1.6 V | 1.6 V | | | | 125 | | | |
| IBHLOS | } | $V_I = 0$ to V_{CC} | | 1.95 V | 1.95 V | | | | 200 | | μΑ | |
| | | | | 2.7 V | 2.7 V | | | | 300 | | | |
| | | | | 3.6 V | 3.6 V | | | | 500 | | | |
| | | | | 1.2 V | 1.2 V | | -50 | | | | | |
| | | | | 1.6 V | 1.6 V | | | | -125 | | | |
| Івнно | ¶ | V _I = 0 to V _{CC} | 1.95 V | 1.95 V | | | | -200 | | μΑ | | |
| | ышо | | 2.7 V | 2.7 V | | | | -300 | | | | |
| | | | 3.6 V | 3.6 V | | | | -500 | | | | |

[†] The bus-hold circuit can sink at least the minimum low sustaining current at VIL max. IBHL should be measured after lowering VIN to GND and then raising it to V_{IL} max.



[‡] The bus-hold circuit can source at least the minimum high sustaining current at V_{IH} min. I_{BHH} should be measured after raising V_{IN} to V_{CC} and then lowering it to $V_{\mbox{\scriptsize IH}}$ min.

[§] An external driver must source at least IBHLO to switch this node from low to high.

An external driver must sink at least I_{BHHO} to switch this node from high to low.

NOTES: 9. V_{CCO} is the V_{CC} associated with the output port.

10. V_{CCI} is the V_{CC} associated with the input port.

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electrical characteristics over recommended operating free-air temperature range (unless otherwise noted) (see Notes 9 and 10) (continued)

| DADA | METER | TEST SOMBITIONS | ,, | ., | T, | _A = 25°C | ; | -40°C to | 85°C | LINUT |
|-----------------|----------------|--|----------------|----------------|-----|---------------------|------|----------|------|-------|
| PARA | METER | TEST CONDITIONS | VCCA | VCCB | MIN | TYP | MAX | MIN | MAX | UNIT |
| | A port | VV 04-00V | 0 V | 0 to 3.6 V | | ±0.1 | ±1 | | ±5 | |
| loff | B port | V_{I} or $V_{O} = 0$ to 3.6 V | 0 to 3.6 V | 0 V | | ±0.1 | ±1 | | ±5 | μΑ |
| loz | A or B ports | V _O = V _{CCO} or GND | 1.2 V to 3.6 V | 1.2 V to 3.6 V | | ±0.5 | ±2.5 | | ±5 | μΑ |
| | - | | 1.2 V to 3.6 V | 1.2 V to 3.6 V | | | | | 10 | |
| ICCA | | $V_I = V_{CCI}$ or GND, $I_O = 0$ | 0 V | 3.6 V | | | | | -2 | μΑ |
| | | | 3.6 V | 0 V | | | | | 10 | |
| | | | 1.2 V to 3.6 V | 1.2 V to 3.6 V | | | | | 10 | |
| ICCB | | $V_I = V_{CCI}$ or GND, $I_O = 0$ | 0 V | 3.6 V | | | | | 10 | μΑ |
| | | | 3.6 V | 0 V | | | | | -2 | |
| ICCA | + ICCB | $V_I = V_{CCI}$ or GND, $I_O = 0$ | 1.2 V to 3.6 V | 1.2 V to 3.6 V | | | | | 20 | μΑ |
| Ci | Control inputs | V _I = 3.3 V or GND | 3.3 V | 3.3 V | | 2.5 | | | | pF |
| C _{io} | A or B ports | V _O = 3.3 V or GND | 3.3 V | 3.3 V | | 6 | | | | pF |

NOTES: 9. $V_{\mbox{CCO}}$ is the $V_{\mbox{CC}}$ associated with the output port.

switching characteristics over recommended operating free-air temperature range, $V_{CCA} = 1.2 \text{ V}$ (see Figure 11)

| DADAMETED | FROM | то | V _{CCB} = 1.2 V | V _{CCB} = 1.5 V | V _{CCB} = 1.8 V | V _{CCB} = 2.5 V | V _{CCB} = 3.3 V | | | | | | | | | | | | | | | | | | | | |
|--------------------|---------|----------|--------------------------|--------------------------|--------------------------|--------------------------|--------------------------|------|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|---|-----|-----|-----|-----|-----|----|
| PARAMETER | (INPUT) | (OUTPUT) | TYP | TYP | TYP | TYP | TYP | UNIT | | | | | | | | | | | | | | | | | | | |
| tPLH | Δ. | | 3.3 | 2.7 | 2.4 | 2.3 | 2.4 | | | | | | | | | | | | | | | | | | | | |
| t _{PHL} | Α | В | 3.3 | 2.7 | 2.4 | 2.3 | 2.4 | ns | | | | | | | | | | | | | | | | | | | |
| tPLH | В | Δ. | 3.3 | 3.1 | 2.9 | 2.8 | 2.7 | | | | | | | | | | | | | | | | | | | | |
| t _{PHL} | В | Α | 3.3 | 3.1 | 2.9 | 2.8 | 2.7 | ns | | | | | | | | | | | | | | | | | | | |
| t _{PHZ} | DID | | 5.1 | 5.2 | 5.3 | 5.2 | 3.7 | | | | | | | | | | | | | | | | | | | | |
| t _{PLZ} | DIR | Α | 5.1 | 5.2 | 5.3 | 5.2 | 3.7 | ns | | | | | | | | | | | | | | | | | | | |
| t _{PHZ} | DID | | 5.3 | 4.3 | 4 | 3.3 | 3.7 | | | | | | | | | | | | | | | | | | | | |
| tPLZ | DIR | В | 5.3 | 4.3 | 4 | 3.3 | 3.7 | ns | | | | | | | | | | | | | | | | | | | |
| t _{PZH} † | | | 8.5 | 6.9 | 6.4 | 5.5 | 6.1 | | | | | | | | | | | | | | | | | | | | |
| t _{PZL} † | DIR | Α | 8.5 | 6.9 | 6.4 | 5.5 | 6.1 | ns | | | | | | | | | | | | | | | | | | | |
| t _{PZH} † | DID | | 8.3 | 7.8 | 7.7 | 7.5 | 5.9 | | | | | | | | | | | | | | | | | | | | |
| t _{PZL} † | DIR | DIR | DIR | DIR | DIR | DIR | DIR | DIR | DIR | DIR | DIR | DIR | DIR | DIR | DIR | DIR | DIR | DIR | DIR | DIR | В | 8.3 | 7.8 | 7.7 | 7.5 | 5.9 | ns |

[†] The enable time is a calculated value, derived using the formula shown in the *enable times* section, page 16.

^{10.} V_{CCI} is the V_{CC} associated with the input port.

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switching characteristics over recommended operating free-air temperature range, V_{CCA} = 1.5 V \pm 0.1 V (see Figure 11)

| PARAMETER | FROM | TO | V _{CCB} = 1.2 V | V _{CCB} = ± 0.7 | | V _{CCB} = ± 0.1 | | V _{CCB} = | | V _{CCB} = ± 0.5 | | UNIT | | | | | | | | | | | | | | | | |
|--------------------|---------|----------|--------------------------|--------------------------|------|--------------------------|------|--------------------|------|--------------------------|------|------|-----|-----|-----|-----|-----|-----|---|-----|--|------|--|----|--|------|--|------|
| | (INPUT) | (OUTPUT) | TYP | MIN | MAX | MIN | MAX | MIN | MAX | MIN | MAX | | | | | | | | | | | | | | | | | |
| t _{PLH} | Δ. | | 2.9 | 0.7 | 5.6 | 0.6 | 5.2 | 0.5 | 4.2 | 0.5 | 3.8 | | | | | | | | | | | | | | | | | |
| t _{PHL} | Α | В | 2.9 | 0.7 | 5.6 | 0.6 | 5.2 | 0.5 | 4.2 | 0.5 | 3.8 | ns | | | | | | | | | | | | | | | | |
| t _{PLH} | | | 2.6 | 0.6 | 5.5 | 0.4 | 5.3 | 0.3 | 4.9 | 0.3 | 4.8 | | | | | | | | | | | | | | | | | |
| t _{PHL} | В | А | 2.6 | 0.6 | 5.5 | 0.4 | 5.3 | 0.3 | 4.9 | 0.3 | 4.8 | ns | | | | | | | | | | | | | | | | |
| t _{PHZ} | DID | Δ. | 3.8 | 1.6 | 6.7 | 1.5 | 6.8 | 0.3 | 6.9 | 0.9 | 6.9 | | | | | | | | | | | | | | | | | |
| tPLZ | DIR | Α | 3.8 | 1.6 | 6.7 | 1.5 | 6.8 | 0.3 | 6.9 | 0.9 | 6.9 | ns | | | | | | | | | | | | | | | | |
| t _{PHZ} | DID | | 5.1 | 1.8 | 8.1 | 1.6 | 7.1 | 1.1 | 4.7 | 1.4 | 4.5 | | | | | | | | | | | | | | | | | |
| t _{PLZ} | DIR | В | 5.1 | 1.8 | 8.1 | 1.6 | 7.1 | 1.1 | 4.7 | 1.4 | 4.5 | ns | | | | | | | | | | | | | | | | |
| t _{PZH} † | DIR | | | Δ. | 7.7 | | 13.6 | | 12.4 | | 9.6 | | 9.3 | | | | | | | | | | | | | | | |
| t _{PZL} † | | A | 7.7 | | 13.6 | | 12.4 | | 9.6 | | 9.3 | ns | | | | | | | | | | | | | | | | |
| t _{PZH} † | DIR | | 6.7 | | 12.3 | | 12 | | 11.1 | | 10.7 | | | | | | | | | | | | | | | | | |
| t _{PZL} † | | DIR | DIR | DIR | DIR | DIR | DIR | DIR | DIR | DIR | DIR | DIR | DIR | DIR | DIR | DIR | DIR | DIR | В | 6.7 | | 12.3 | | 12 | | 11.1 | | 10.7 |

[†] The enable time is a calculated value, derived using the formula shown in the enable times section, page 16.

switching characteristics over recommended operating free-air temperature range, V_{CCA} = 1.8 V \pm 0.15 V (see Figure 11)

| PARAMETER | FROM | TO | V _{CCB} = 1.2 V | V _{CCB} = | | V _{CCB} = ± 0.1 | | V _{CCB} = | | VCCB = | | UNIT | | | | | | | | | | | | | | | | | | | |
|--------------------|---------|----------|--------------------------|--------------------|------|--------------------------|------|--------------------|------|--------|------|------|-----|-----|-----|-----|-----|-----|-----|-----|-----|-------|-----|--|------|--|------|--|-----|--|-----|
| | (INPUT) | (OUTPUT) | TYP | MIN | MAX | MIN | MAX | MIN | MAX | MIN | MAX | | | | | | | | | | | | | | | | | | | | |
| t _{PLH} | ٨ | ь | 2.8 | 0.6 | 5.3 | 0.5 | 5 | 0.4 | 3.9 | 0.4 | 3.4 | 20 | | | | | | | | | | | | | | | | | | | |
| tPHL | Α | В | 2.8 | 0.6 | 5.3 | 0.5 | 5 | 0.4 | 3.9 | 0.4 | 3.4 | ns | | | | | | | | | | | | | | | | | | | |
| tPLH | В | Α | 2.3 | 0.5 | 5.2 | 0.4 | 5 | 0.3 | 4.6 | 0.2 | 4.4 | | | | | | | | | | | | | | | | | | | | |
| tPHL | В | А | 2.3 | 0.5 | 5.2 | 0.4 | 5 | 0.3 | 4.6 | 0.2 | 4.4 | ns | | | | | | | | | | | | | | | | | | | |
| t _{PHZ} | DID | А | 3.8 | 1.6 | 5.9 | 1.6 | 5.9 | 1.6 | 5.9 | 0.5 | 6 | | | | | | | | | | | | | | | | | | | | |
| t _{PLZ} | DIR | А | 3.8 | 1.6 | 5.9 | 1.6 | 5.9 | 1.6 | 5.9 | 0.5 | 6 | ns | | | | | | | | | | | | | | | | | | | |
| ^t PHZ | 2 | | 5 | 1.8 | 7.7 | 1.4 | 6.8 | 1 | 4.4 | 1.4 | 4.3 | | | | | | | | | | | | | | | | | | | | |
| tPLZ | DIR | В | 5 | 1.89 | 7.7 | 1.4 | 6.8 | 1 | 4.4 | 1.4 | 4.3 | ns | | | | | | | | | | | | | | | | | | | |
| t _{PZH} † | DIR | 212 | 515 | DID | DID | | 7.3 | | 12.9 | | 11.8 | | 9 | | 8.7 | | | | | | | | | | | | | | | | |
| t _{PZL} † | | A | 7.3 | | 12.9 | | 11.8 | | 9 | | 8.7 | ns | | | | | | | | | | | | | | | | | | | |
| t _{PZH} † | DIR | DID D | 6.5 | | 11.2 | | 10.9 | | 9.8 | | 9.4 | | | | | | | | | | | | | | | | | | | | |
| t _{PZL} † | | DIR | DIR | DIR | DIR | DIR | DIR | DIR | DIR | DIR | DIR | DIR | DIR | DIR | DIR | DIR | DIR | DIR | DIR | DIR | DIR | DIR B | 6.5 | | 11.2 | | 10.9 | | 9.8 | | 9.4 |

[†] The enable time is a calculated value, derived using the formula shown in the *enable times* section, page 16.

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switching characteristics over recommended operating free-air temperature range, V_{CCA} = 2.5 V \pm 0.2 V (see Figure 11)

| PARAMETER | FROM | TO | V _{CCB} = 1.2 V | V _{CCB} = ± 0.7 | | V _{CCB} = ± 0.1 | | V _{CCB} = ± 0.2 | | V _{CCB} = ± 0.5 | | UNIT | | | | | | | | | | | | | | | | |
|--------------------|---------|----------|--------------------------|--------------------------|------|--------------------------|------|--------------------------|-----|--------------------------|-----|------|-----|-----|-----|-----|-----|-----|---|-----|--|-----|--|-----|--|---|--|-----|
| | (INPUT) | (OUTPUT) | TYP | MIN | MAX | MIN | MAX | MIN | MAX | MIN | MAX | | | | | | | | | | | | | | | | | |
| t _{PLH} | ٨ | В | 2.6 | 0.5 | 4.9 | 0.4 | 4.6 | 0.3 | 3.4 | 0.3 | 3 | | | | | | | | | | | | | | | | | |
| t _{PHL} | А | В | 2.6 | 0.5 | 4.9 | 0.4 | 4.6 | 0.3 | 3.4 | 0.3 | 3 | ns | | | | | | | | | | | | | | | | |
| ^t PLH | | | 2.2 | 0.4 | 4.2 | 0.3 | 3.8 | 0.2 | 3.4 | 0.2 | 3.3 | | | | | | | | | | | | | | | | | |
| t _{PHL} | В | Α | 2.2 | 0.4 | 4.2 | 0.3 | 3.8 | 0.2 | 3.4 | 0.2 | 3.3 | ns | | | | | | | | | | | | | | | | |
| t _{PHZ} | DID | Δ. | 2.8 | 0.3 | 3.8 | 0.8 | 3.8 | 0.4 | 3.8 | 0.5 | 3.8 | | | | | | | | | | | | | | | | | |
| tPLZ | DIR | Α | 2.8 | 0.3 | 3.8 | 0.8 | 3.8 | 0.4 | 3.8 | 0.5 | 3.8 | ns | | | | | | | | | | | | | | | | |
| t _{PHZ} | DID | В | 4.9 | 2 | 7.6 | 1.5 | 6.5 | 0.6 | 4.1 | 1 | 4 | | | | | | | | | | | | | | | | | |
| tPLZ | DIR | В | 4.9 | 2 | 7.6 | 1.5 | 6.5 | 0.6 | 4.1 | 1 | 4 | ns | | | | | | | | | | | | | | | | |
| t _{PZH} † | DID. | Δ. | 7.1 | | 11.8 | | 10.3 | | 7.5 | | 7.3 | | | | | | | | | | | | | | | | | |
| t _{PZL} † | DIR | A | 7.1 | | 11.8 | | 10.3 | | 7.5 | | 7.3 | ns | | | | | | | | | | | | | | | | |
| t _{PZH} † | DIR | | 5.4 | | 8.6 | | 8.1 | | 7 | | 6.6 | | | | | | | | | | | | | | | | | |
| t _{PZL} † | | DIR | DIR | DIR | DIR | DIR | DIR | DIR | DIR | DIR | DIR | DIR | DIR | DIR | DIR | DIR | DIR | DIR | В | 5.4 | | 8.6 | | 8.1 | | 7 | | 6.6 |

[†]The enable time is a calculated value, derived using the formula shown in the enable times section, page 16.

switching characteristics over recommended operating free-air temperature range, V_{CCA} = 3.3 V \pm 0.3 V (see Figure 11)

| PARAMETER | FROM (INPUT) | TO | V _{CCB} = 1.2 V | V _{CCB} = | | V _{CCB} = ± 0.1 | | V _{CCB} = ± 0.2 | | V _{CCB} = ± 0.3 | | UNIT | | | | | | | | | | | | | | | | |
|--------------------|-----------------|----------|--------------------------|--------------------|------|--------------------------|-----|--------------------------|-----|--------------------------|-----|------|-----|-----|-----|-----|-----|-----|---|-----|--|-----|--|-----|--|-----|--|-----|
| | (INPUI) | (OUTPUT) | TYP | MIN | MAX | MIN | MAX | MIN | MAX | MIN | MAX | | | | | | | | | | | | | | | | | |
| tPLH | Δ. | В | 2.6 | 0.4 | 4.7 | 0.3 | 4.4 | 0.2 | 3.3 | 0.2 | 2.8 | | | | | | | | | | | | | | | | | |
| t _{PHL} | А | В | 2.6 | 0.4 | 4.7 | 0.3 | 4.4 | 0.2 | 3.3 | 0.2 | 2.8 | ns | | | | | | | | | | | | | | | | |
| tPLH | 6 | Δ. | 2.2 | 0.4 | 3.8 | 0.3 | 3.4 | 0.2 | 3 | 0.1 | 2.8 | | | | | | | | | | | | | | | | | |
| t _{PHL} | В | Α | 2.2 | 0.4 | 3.8 | 0.3 | 3.4 | 0.2 | 3 | 0.1 | 2.8 | ns | | | | | | | | | | | | | | | | |
| t _{PHZ} | DID. | ۸ | 3.1 | 1.3 | 4.3 | 1.3 | 4.3 | 1.3 | 4.3 | 1.3 | 4.3 | | | | | | | | | | | | | | | | | |
| t _{PLZ} | DIR | Α | 3.1 | 1.3 | 4.3 | 1.3 | 4.3 | 1.3 | 4.3 | 1.3 | 4.3 | ns | | | | | | | | | | | | | | | | |
| t _{PHZ} | DID | _ | 4 | 0.7 | 7.4 | 0.6 | 6.5 | 0.7 | 4 | 1.5 | 3.9 | | | | | | | | | | | | | | | | | |
| tPLZ | DIR | В | 4 | 0.7 | 7.4 | 0.6 | 6.5 | 0.7 | 4 | 1.5 | 3.9 | ns | | | | | | | | | | | | | | | | |
| t _{PZH} † | DID | Δ. | 6.2 | | 11.2 | | 9.9 | | 7 | | 6.7 | | | | | | | | | | | | | | | | | |
| t _{PZL} † | DIR | DIR A | 6.2 | | 11.2 | | 9.9 | | 7 | | 6.7 | ns | | | | | | | | | | | | | | | | |
| t _{PZH} † | DIR | В | 5.7 | | 8.9 | | 8.5 | | 7.2 | | 6.8 | | | | | | | | | | | | | | | | | |
| t _{PZL} † | | DIR | DIR | DIR | DIR | DIR | DIR | DIR | DIR | DIR | DIR | DIR | DIR | DIR | DIR | DIR | DIR | DIR | R | 5.7 | | 8.9 | | 8.5 | | 7.2 | | 6.8 |

[†] The enable time is a calculated value, derived using the formula shown in the enable times section, page 16.

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operating characteristics, $T_A = 25^{\circ}C$

| P/ | ARAMETER | TEST CONDITIONS | V _{CCA} = V _{CCB} = 1.2 V | V _{CCA} = V _{CCB} = 1.5 V | V _{CCA} = V _{CCB} = 1.8 V | V _{CCA} = V _{CCB} = 2.5 V | V _{CCA} = V _{CCB} = 3.3 V | UNIT | |
|-------|--|--|---|---|---|---|---|------|--|
| | | CONDITIONS | TYP | TYP | TYP | TYP | TYP | | |
| C wt | A-port input, B-port output | C _L = 0 pF, f = 10 MHz, | 3 | 3 | 3 | 3 | 4 | ۰۲ | |
| CpdA | B-port input, A-port output | $t_r = t_f = 1 \text{ ns}$ | 14 | 14 | 14 | 15 | 16 | pF | |
| C int | A-port input, B-port output | C _L = 0 pF, | 14 | 14 | 14 | 15 | 16 | ~F | |
| ○pdB1 | CpdB [†] B-port input, A-port output | f = 10 MHz, $t_r = t_f = 1 \text{ ns}$ | 3 | 3 | 3 | 3 | 4 | · pF | |

[†] Power-dissipation capacitance per transceiver

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power-up considerations

A proper power-up sequence always should be followed to avoid excessive supply current, bus contention, oscillations, or other anomalies. To guard against such power-up problems, take the following precautions:

- 1. Connect ground before any supply voltage is applied.
- 2. Power up V_{CCA}.
- 3. V_{CCB} can be ramped up along with or after V_{CCA} .

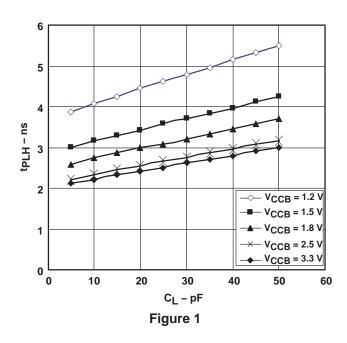
typical total static power consumption ($I_{CCA} + I_{CCB}$)

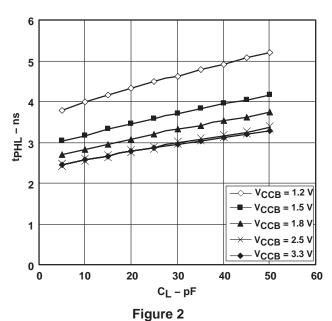
Table 1

| V _{CCB} | VCCA | | | | | | |
|------------------|------|-------|-------|-------|-------|-------|------|
| | 0 V | 1.2 V | 1.5 V | 1.8 V | 2.5 V | 3.3 V | UNIT |
| 0 V | 0 | <0.5 | <0.5 | <0.5 | <0.5 | <0.5 | |
| 1.2 V | <0.5 | <1 | <1 | <1 | <1 | 1 | |
| 1.5 V | <0.5 | <1 | <1 | <1 | <1 | 1 | |
| 1.8 V | <0.5 | <1 | <1 | <1 | <1 | <1 | μΑ |
| 2.5 V | <0.5 | 1 | <1 | <1 | <1 | <1 | |
| 3.3 V | <0.5 | 1 | <1 | <1 | <1 | <1 | |

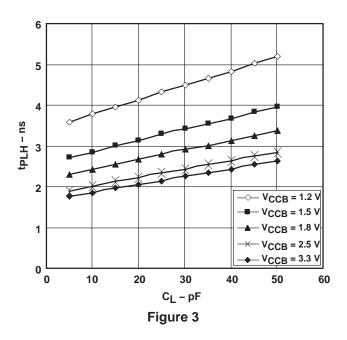
TYPICAL CHARACTERISTICS

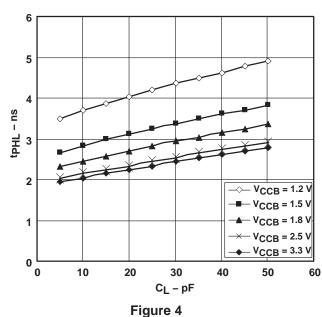
TYPICAL PROPAGATION DELAY (A to B) vs LOAD CAPACITANCE, $T_A = 25^{\circ}C, V_{CCA} = 1.2 V$





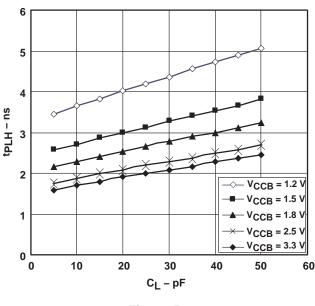
TYPICAL PROPAGATION DELAY (A to B) vs LOAD CAPACITANCE, $T_A = 25^{\circ}C, V_{CCA} = 1.5 V$





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TYPICAL PROPAGATION DELAY (A to B) vs LOAD CAPACITANCE, $T_{A}=25^{\circ}\text{C},\,V_{CCA}=1.8\;\text{V}$



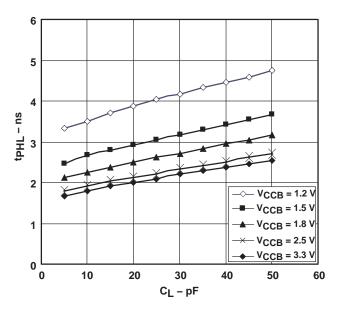
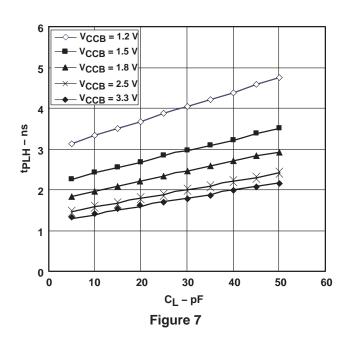
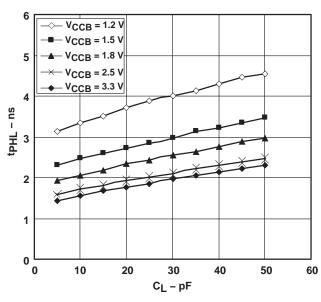


Figure 5

Figure 6

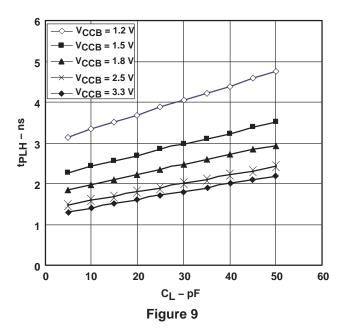
TYPICAL PROPAGATION DELAY (A to B) vs LOAD CAPACITANCE, $T_A = 25^{\circ}C$, $V_{CCA} = 2.5$ V

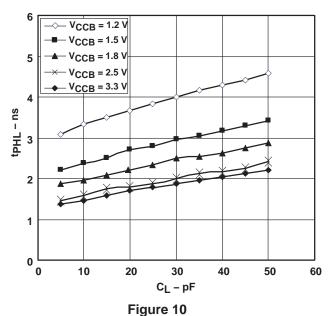




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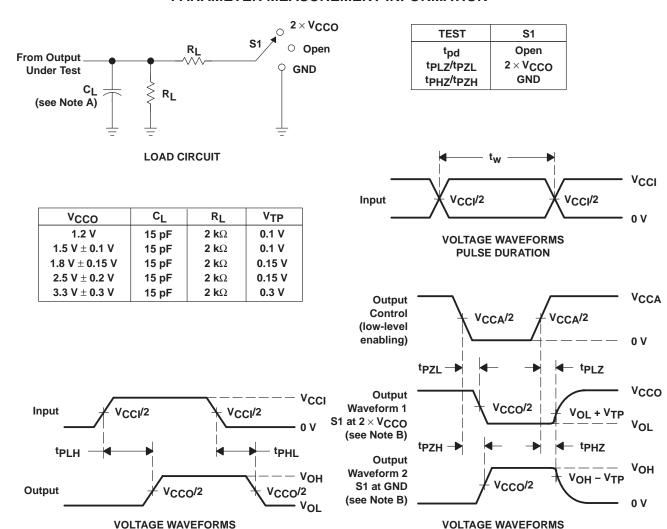
TYPICAL PROPAGATION DELAY (A to B) vs LOAD CAPACITANCE, $T_{A}=25^{\circ}\text{C},\,V_{CCA}=3.3\;\text{V}$





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PARAMETER MEASUREMENT INFORMATION



NOTES: A. C_L includes probe and jig capacitance.

B. Waveform 1 is for an output with internal conditions such that the output is low, except when disabled by the output control. Waveform 2 is for an output with internal conditions such that the output is high, except when disabled by the output control.

ENABLE AND DISABLE TIMES

- C. All input pulses are supplied by generators having the following characteristics: PRR \leq 10 MHz, Z_O = 50 Ω , dv/dt \geq 1 V/ns, dv/dt \geq 1 V/ns.
- D. The outputs are measured one at a time, with one transition per measurement.
- E. tpLz and tpHz are the same as tdis.
- F. tpzL and tpzH are the same as ten.
- G. t_{PLH} and t_{PHL} are the same as t_{pd} .
- H. V_{CCI} is the V_{CC} associated with the input port.
- I. V_{CCO} is the V_{CC} associated with the output port.

PROPAGATION DELAY TIMES

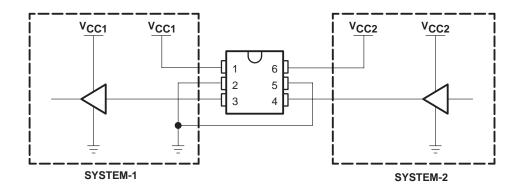
Figure 11. Load Circuit and Voltage Waveforms



SN74AVCH1T45 SINGLE-BIT DUAL-SUPPLY BUS TRANSCEIVER WITH CONFIGURABLE VOLTAGE TRANSLATION AND 3-STATE OUTPUTS SCESS98C - JULY 2004 - REVISED OCTOBER 2004

APPLICATION INFORMATION

Figure 12 shows an example of the SN74AVCH1T45 being used in a unidirectional logic level-shifting application.



| PIN | NAME | FUNCTION | DESCRIPTION | |
|-----|------|------------------|--|--|
| 1 | VCCA | V _{CC1} | SYSTEM-1 supply voltage (1.2 V to 3.6 V) | |
| 2 | GND | GND | Device GND | |
| 3 | А | OUT | Output level depends on V _{CC1} voltage. | |
| 4 | В | IN | Input threshold value depends on V _{CC2} voltage. | |
| 5 | DIR | DIR | GND (low level) determines B-port to A-port direction. | |
| 6 | VCCB | V _{CC2} | SYSTEM-2 supply voltage (1.2 V to 3.6 V) | |

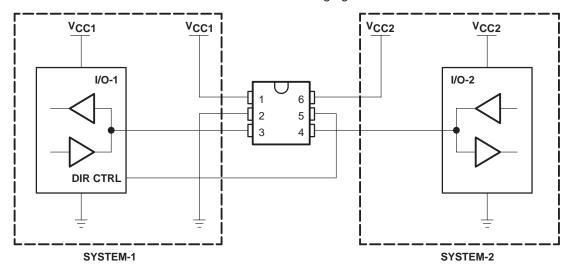
Figure 12. Unidirectional Logic Level-Shifting Application



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APPLICATION INFORMATION

Figure 13 shows the SN74AVCH1T45 being used in a bidirectional logic level-shifting application. Since the SN74AVCH1T45 does not have an output-enable (OE) pin, the system designer should take precautions to avoid bus contention between SYSTEM-1 and SYSTEM-2 when changing directions.



Following is a sequence that illustrates data transmission from SYSTEM-1 to SYSTEM-2 and then from SYSTEM-2 to SYSTEM-1.

| STATE | DIR CTRL | I/O-1 | I/O-2 | DESCRIPTION |
|-------|----------|-------|-------|---|
| 1 | Н | Out | In | SYSTEM-1 data to SYSTEM-2 |
| 2 | н | Hi-Z | Hi-Z | SYSTEM-2 is getting ready to send data to SYSTEM-1. I/O-1 and I/O-2 are disabled. The bus-line state depends on bus hold. |
| 3 | L | Hi-Z | Hi-Z | DIR bit is flipped. I/O-1 and I/O-2 are still disabled. The bus-line state depends on bus hold. |
| 4 | L | Out | In | SYSTEM-2 data to SYSTEM-1 |

Figure 13. Bidirectional Logic Level-Shifting Application

enable times

Calculate the enable times for the SN74AVCH1T45 using the following formulas:

$$t_{PZH}$$
 (DIR to A) = t_{PIZ} (DIR to B) + t_{PIH} (B to A)

$$t_{PZL}$$
 (DIR to A) = t_{PHZ} (DIR to B) + t_{PHL} (B to A)

$$t_{PZH}$$
 (DIR to B) = t_{PLZ} (DIR to A) + t_{PLH} (A to B)

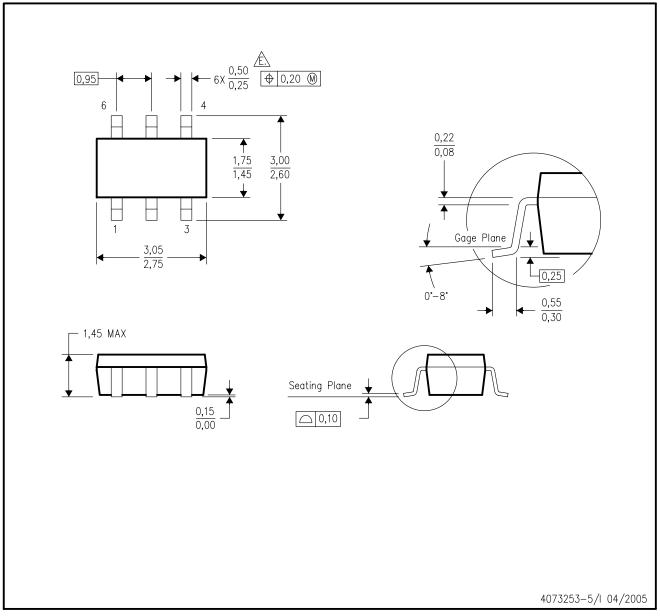
$$t_{PZL}$$
 (DIR to B) = t_{PHZ} (DIR to A) + t_{PHL} (A to B)

In a bidirectional application, these enable times provide the maximum delay from the time the DIR bit is switched until an output is expected. For example, if the SN74AVCH1T45 initially is transmitting from A to B, then the DIR bit is switched; the B port of the device must be disabled before presenting it with an input. After the B port has been disabled, an input signal applied to it appears on the corresponding A port after the specified propagation delay.



DBV (R-PDSO-G6)

PLASTIC SMALL-OUTLINE PACKAGE



NOTES:

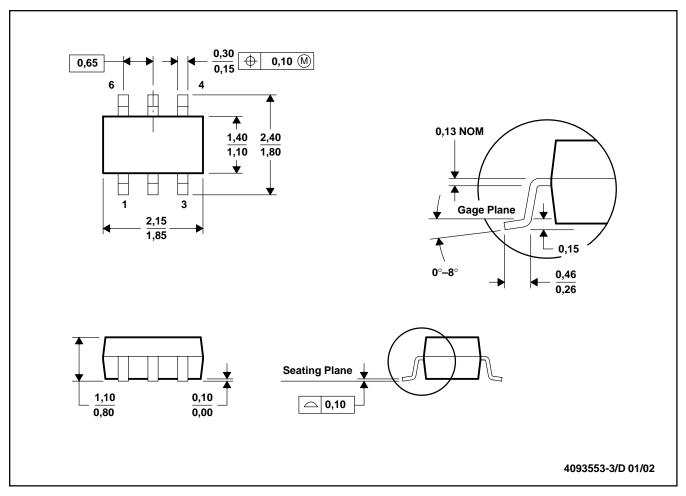
- A. All linear dimensions are in millimeters.
- B. This drawing is subject to change without notice.
- C. Body dimensions do not include mold flash or protrusion.

 D. Leads 1,2,3 may be wider than leads 4,5,6 for package orientation.
- Falls within JEDEC MO-178 Variation AB, except minimum lead width.



DCK (R-PDSO-G6)

PLASTIC SMALL-OUTLINE PACKAGE

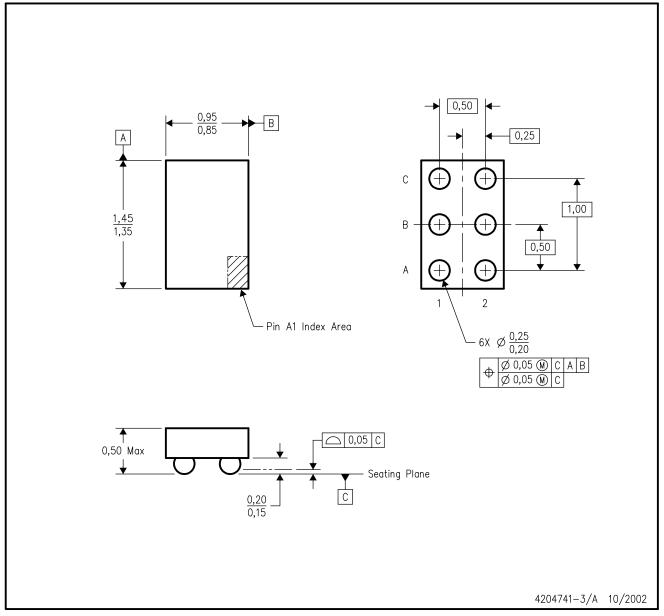


NOTES: A. All linear dimensions are in millimeters.

- B. This drawing is subject to change without notice.
- C. Body dimensions do not include mold flash or protrusion.
- D. Falls within JEDEC MO-203

YZP (R-XBGA-N6)

DIE-SIZE BALL GRID ARRAY



NOTES:

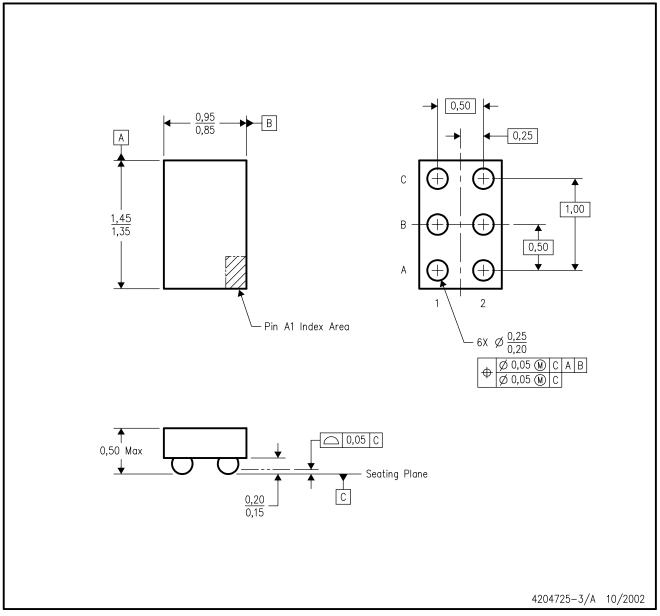
- A. All linear dimensions are in millimeters.
- B. This drawing is subject to change without notice.
- C. NanoFree™ package configuration.
- D. This package is lead-free. Refer to the 6 YEP package (drawing 4204725) for tin-lead (SnPb).

NanoFree is a trademark of Texas Instruments.



YEP (R-XBGA-N6)

DIE-SIZE BALL GRID ARRAY



NOTES:

- A. All linear dimensions are in millimeters.
- B. This drawing is subject to change without notice.
- C. NanoStar™ package configuration.
- D. This package is tin-lead (SnPb). Refer to the 6 YZP package (drawing 4204741) for lead-free.

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