

## DUAL PRE-POWER AMP WITH VOLUME CONTROLLER

S1A0136A01

### INTRODUCTION

The S1A0136A01 is a monolithic integrated circuit designed for use in low voltage and low power applications. It has functions including dual audio pre-power amplifier, electronic volume controller and DC motor speed controller in a single chip. It is suitable for portable tape recorders, headphones, cassette tape recorders or radios that are battery-operated.

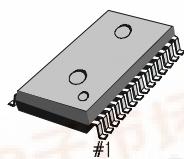
### FEATURES

- Low current consumption in an operating voltage range
- Operating supply voltage range:  $V_{cc} = 2.1V - 5V$
- Only a few components in composing a headphone cassette tape recorder
- Dual audio pre-power amplifier, electronic volume controller and DC motor speed controller in a single chip
- Reduced input and output coupling capacitors because of 1/2  $V_{cc}$  AMP adoption on chip as AC GND

28-SDIP



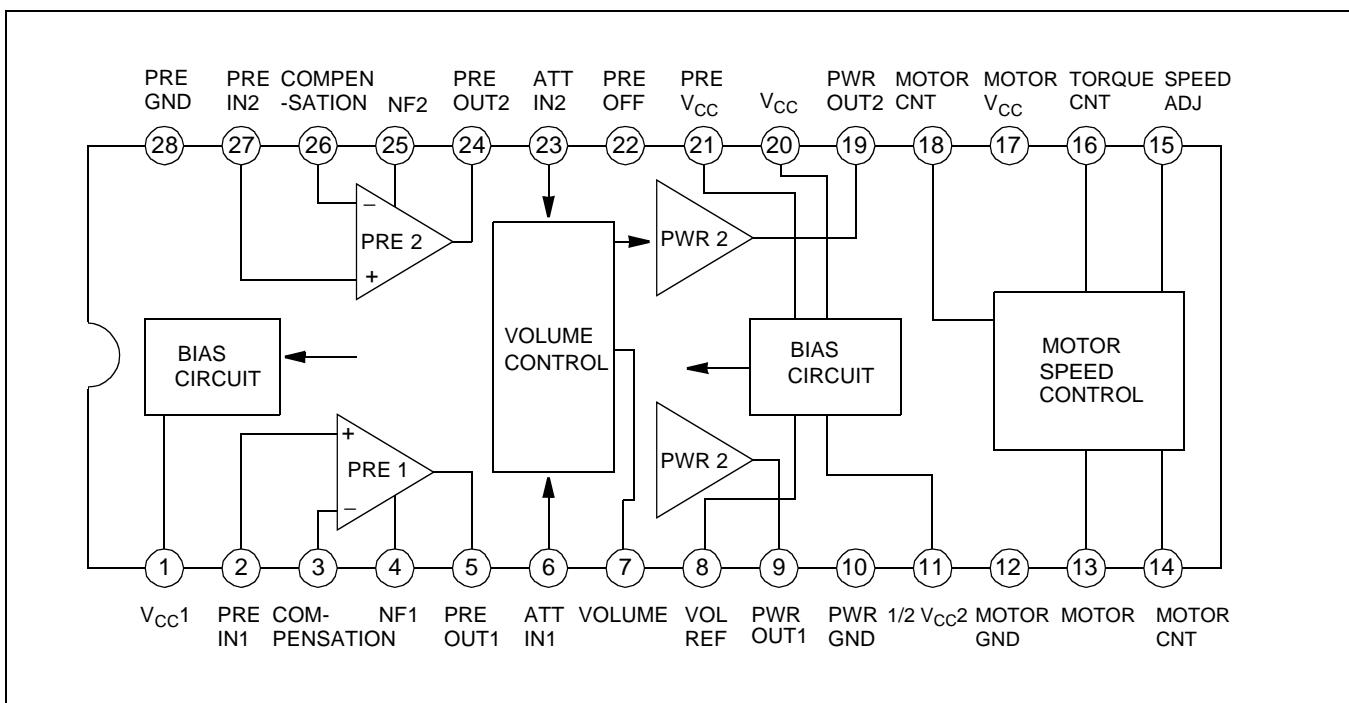
28-SOP



### ORDERING INFORMATION

Device	Package	Operating Temperature
S1A0136A01-A0B0	28-SDIP	-20°C — +65°C
S1A0136A01-S0B0	28-SOP	

## BLOCK DIAGRAM



## ABSOLUTE MAXIMUM RATINGS (Ta = 25°C)

Characteristic	Symbol	Value	Unit
Supply Voltage	V <sub>CC</sub>	7.5	V
Power Dissipation	P <sub>O</sub>	450	mW
Operating Temperature	T <sub>OPR</sub>	-20 — +70	°C
Storage Temperature	T <sub>STG</sub>	-40 — +125	°C

**ELECTRICAL CHARACTERISTICS**(Ta = 25°C, V<sub>CC</sub> = 3V, unless otherwise specified)

<b>Characteristic</b>	<b>Symbol</b>	<b>Test Conditions</b>	<b>Min.</b>	<b>Typ.</b>	<b>Max.</b>	<b>Unit</b>
Quiescent Circuit Current	I <sub>CCQ</sub>	V <sub>CC</sub> = 3V, V <sub>I</sub> = 0, I <sub>M</sub> = 0	–	18	25	mA

**PRE AMPLIFIER SECTION**(V<sub>CC</sub> = 3V, f = 1kHz, R<sub>L</sub> = 10kΩ, unless otherwise specified)

<b>Characteristic</b>	<b>Symbol</b>	<b>Test Conditions</b>	<b>Min.</b>	<b>Typ.</b>	<b>Max.</b>	<b>Unit</b>
Open Loop Voltage Gain	G <sub>VO</sub>	V <sub>O</sub> = -10dBm, R <sub>L</sub> = ∞	–	70	–	dB
Closed Loop Voltage Gain	G <sub>VC1</sub>	V <sub>O</sub> = -10dBm	40	42	44	dB
Output Voltage	V <sub>O</sub>	THD = 1%	0.45	0.6	–	V
Total Harmonic Distortion	THD	V <sub>O</sub> = 0.2V	–	0.05	0.5	%
Output Noise Voltage	V <sub>NO1</sub>	V <sub>i</sub> = 0, R <sub>g</sub> = 2.2kΩ, BPF(30 – 20kHz)	–	150	300	μV
Input Resistance	R <sub>I</sub>	V <sub>O</sub> = 10dBm	18	22	–	kΩ
Cross Talk	CT <sub>1</sub>	R <sub>G</sub> = 2.2kΩ, V <sub>O</sub> = -10dBm	30	–	–	dB
Output Voltage In Pre OFF	V <sub>O</sub> (OFF)	V <sub>I</sub> = 100mV Pre OFF (pin 22) = V <sub>CC</sub>	–	–	-50	dB

**POWER AMPLIFIER SECTION**(Ta = 25°C, V<sub>CC</sub> = 3V, unless otherwise specified)

<b>Characteristic</b>	<b>Symbol</b>	<b>Test Conditions</b>	<b>Min.</b>	<b>Typ.</b>	<b>Max.</b>	<b>Unit</b>
Closed Loop Voltage Gain	G <sub>VC2</sub>	P <sub>O</sub> = 5mW	26	28	30	dB
Voltage Gain Difference	ΔG <sub>V</sub>	V <sub>CONT</sub> = Max	–	0	3	dB
Output Power 1	P <sub>O1</sub>	THD = 10%, R <sub>L</sub> = 32Ω	20	28	–	mW
Output Power 2	P <sub>O2</sub>	THD = 10%, R <sub>L</sub> = 16Ω	30	–	–	mW
Total Harmonic Distortion	THD <sub>2</sub>	P <sub>O</sub> = 5mW	–	0.2	2.0	%
Pre+ Power Output Noise Voltage	V <sub>NO2I</sub>	V <sub>I</sub> = 0, R <sub>G</sub> = 2.2kΩ, V <sub>CONT</sub> = Max	–	6	10	mV
Output Noise Voltage	V <sub>NO3I</sub>	R <sub>G</sub> = 2.2 kΩ, V <sub>CONT</sub> = Min	–	0.25	1.0	mV
Cross Talk	CT <sub>2</sub>	R <sub>O</sub> = 5mW	20	30	–	dB
Ripple Rejection Ratio	RR	V <sub>CC</sub> = 3V, 100Hz, 100mVp-p	34	40	–	dB

**ATTENUATOR SECTION**(Ta = 25°C, V<sub>CC</sub> = 3V, f = 1kHz, unless otherwise specified)

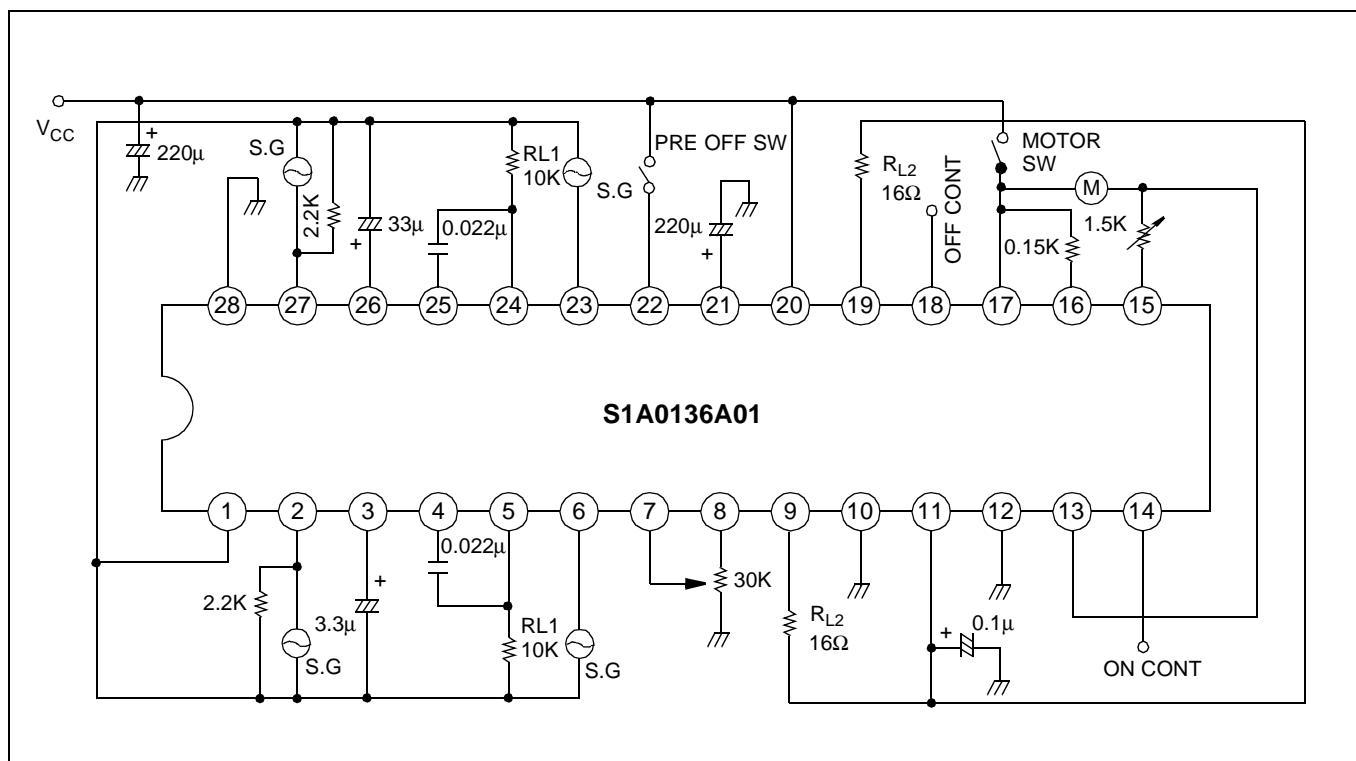
<b>Characteristic</b>	<b>Symbol</b>	<b>Test Conditions</b>	<b>Min.</b>	<b>Typ.</b>	<b>Max.</b>	<b>Unit</b>
Maximum Input Voltage	V <sub>I(MAX)</sub>	–	0.2	–	–	V
Maximum Attenuation	V <sub>ATT(MAX)</sub>	V <sub>CONT</sub> = Min	66	–	–	dB
Attenuation Error	V <sub>ATT(ERR)</sub>	V <sub>CONT</sub> = Max	–	0	–	dB
Input Impedance	Z <sub>I</sub>	–	15	20	–	KΩ

**MOTOR SPEED CONTROLLER**(Ta = 25°C, V<sub>CC</sub> = 3V, I<sub>M</sub> = 100mA, unless otherwise specified)

<b>Characteristic</b>	<b>Symbol</b>	<b>Test Conditions</b>	<b>Min.</b>	<b>Typ.</b>	<b>Max.</b>	<b>Unit</b>
Circuit Current	I <sub>MC</sub>	–	–	3.0	5.0	mA
Starting Current	I <sub>MS</sub>	–	500	–	–	mA
Reference Voltage	V <sub>REF</sub>	V(pin 15, 16)	0.72	0.80	0.87	V
Reference Voltage Regulation 1	ΔV <sub>REF1</sub>	V <sub>CC</sub> = 2.1 – 5.0 V	–	0.05	–	%/V
Reference Voltage Regulation 2	ΔV <sub>REF2</sub>	I <sub>M</sub> = 25 – 250 mA	–	0.01	–	%/mA
Reference Voltage Regulation 3	ΔV <sub>REF3</sub>	Ta = -10 ~ 50 °C	–	0.01	–	%/°C
Current Coefficient	K	–	32	38	43	–
Current Coefficient Regulation 1	ΔK1	V <sub>CC</sub> = 2.1 – 5.0 V	–	0.50	–	%/V
Current Coefficient Regulation 2	ΔK2	I <sub>M</sub> = 25 – 250 mA	–	0.05	–	%/mA
Current Coefficient Regulation 3	ΔK3	Ta = -10 – 50 °C	–	0.02	–	%/°C
Saturation Voltage	V <sub>SAT</sub>	I <sub>M</sub> = 200mA, Pin14 = V <sub>CC</sub>	–	–	0.6	V
Leakage Current	I <sub>LKG</sub>	Pin 18 = V <sub>CC</sub>	–	50	200	μV

\* Voltage across Pin 13, 17

## TEST CIRCUIT



## APPLICATION CIRCUIT

