

Thyristor/Diode Modules

ECO-PAC

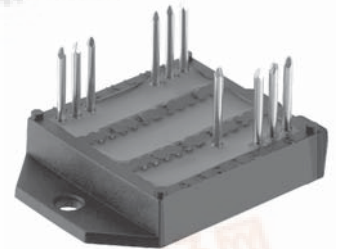
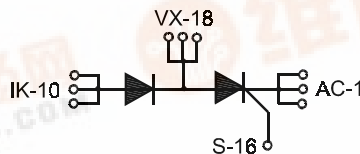
$$I_{TRMS} = 2 \times 180A$$

$$I_{TAVM} = 2 \times 105A$$

$$V_{RRM} = 800 - 1800 V$$

Preliminary Data

V_{RSM} V_{DSM} V	V_{RRM} V_{DRM} V	Typ
900	800	VCD 105 - 08io7
1300	1200	VCD 105 - 12io7
1500	1400	VCD 105 - 14io7
1700	1600	VCD 105 - 16io7
1900	1800	VCD 105 - 18io7



Symbol	Conditions	Maximum Ratings
I_{TRMS}		180 A
I_{TAVM}	$T_C = 85^\circ C$; 180° sine	105 A
I_{TSM}	$T_{VJ} = 45^\circ C$; $V_R = 0 V$; $t = 10 ms$ (50 Hz), sine	2250 A
	$t = 8.3 ms$ (60 Hz), sine	2400 A
	$T_{VJ} = 125^\circ C$; $V_R = 0 V$; $t = 10 ms$ (50 Hz), sine	2000 A
	$t = 8.3 ms$ (60 Hz), sine	2150 A
I^2dt	$T_{VJ} = 45^\circ C$; $V_R = 0 V$; $t = 10 ms$ (50 Hz), sine	25300 A ² s
	$t = 8.3 ms$ (60 Hz), sine	23900 A ² s
	$T_{VJ} = 125^\circ C$; $V_R = 0 V$; $t = 10 ms$ (50 Hz), sine	20000 A ² s
	$t = 8.3 ms$ (60 Hz), sine	19100 A ² s
$(di/dt)_{cr}$	$T_{VJ} = 125^\circ C$; $f = 50 Hz$; $t_p = 200 \mu s$; $V_D = 2/3 V_{DRM}$; $I_G = 0.45 A$; $di_G/dt = 0.45 A/\mu s$; repetitive, $I_T = 250 A$	150 A/ μs
	non repetitive, $I_T = I_{TAVM}$	500 A/ μs
$(dv/dt)_{cr}$	$T_{VJ} = 125^\circ C$; $V_{DR} = 2/3 V_{DRM}$; $R_{GK} = \infty$, method 1 (linear voltage rise)	1000 V/ μs
P_{GM}	$T_{VJ} = 125^\circ C$; $t_p = 30 ms$	$\leq 10 W$
	$I_T = I_{TAVM}$; $t_p = 300 ms$	$\leq 5 W$
P_{GAVM}		0.5 W
V_{RGM}		10 V
T_{VJ}		-40 ... +125 °C
T_{VJM}		125 °C
T_{stg}		-40 ... +125 °C
V_{ISOL}	50/60 Hz, RMS; $t = 1 min$	3000 V ~
	$I_{ISOL} \leq 1 mA$; $t = 1 s$	3600 V ~
M_d	Mounting torque (M4)	1.5 - 2.0 Nm
		14 - 18 lb.in.
Weight	typ.	26 g

Features

- Isolation voltage 3600 V~
- Planar glass passivated chips
- Low forward voltage drop
- Leads suitable for PC board soldering

Applications

- DC motor control
- Light and temperature control
- Softstart AC motor controller
- Solid state switches

Advantages

- Easy to mount with two screws
- Space and weight savings
- Improved temperature and power cycling
- High power density
- Small and light weight

Data according to IEC 60747 refer to a single thyristor unless otherwise stated

IXYS reserves the right to change limits, test conditions and dimensions.

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Symbol	Conditions	Characteristic Values		
		min.	typ.	max.
I_D, I_R	$T_{VJ} = 125^{\circ}\text{C}; V_R = V_{RRM}; V_D = V_{DRM}$			5 mA
V_T	$I_T = 300 \text{ A}; T_{VJ} = 25^{\circ}\text{C}$			1.5 V
V_{TO} r_T	For power-loss calculations only			0.8 V 2.4 mΩ
V_{GT}	$V_D = 6 \text{ V};$ $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = -40^{\circ}\text{C}$			1.5 V 1.6 V
I_{GT}	$V_D = 6 \text{ V};$ $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = -40^{\circ}\text{C}$			150 mA 200 mA
V_{GD} I_{GD}	$T_{VJ} = 125^{\circ}\text{C}; V_D = \frac{2}{3}V_{DRM}$ $T_{VJ} = 125^{\circ}\text{C}; V_D = \frac{2}{3}V_{DRM}$			0.2 V 10 mA
I_L	$T_{VJ} = 25^{\circ}\text{C}; t_p = 10 \text{ ms}$ $I_G = 0.45 \text{ A}; di_G/dt = 0.45 \text{ A}/\mu\text{s}$			450 mA
I_H	$T_{VJ} = 25^{\circ}\text{C}; V_D = 6 \text{ V}; R_{GK} = \infty$			200 mA
t_{gd}	$T_{VJ} = 25^{\circ}\text{C}; V_D = \frac{1}{2} V_{DRM}$ $I_G = 0.45 \text{ A}; di_G/dt = 0.45 \text{ A}/\mu\text{s}$			2 μs
R_{thJC} R_{thCH}	per Thyristor; DC per module per Thyristor; DC per module		0,2 0,1	0.26 K/W 0.13 K/W K/W K/W
d_s d_A a	Creeping distance on surface Creeping distance in air Max. allowable acceleration			11.2 mm 5.0 mm 50 m/s ²

