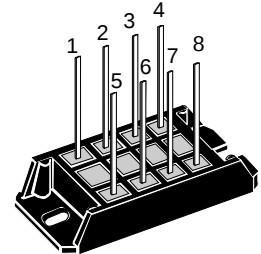
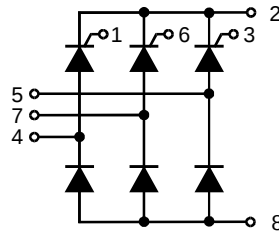


Three Phase Half Controlled Rectifier Bridge

$I_{dAVM} = 20 \text{ A}$
 $V_{RRM} = 1200-1600 \text{ V}$

V_{RSM} V_{DSM} V	V_{RRM} V_{DRM} V	Type
1300	1200	VVZ 12-12io1
1500	1400	VVZ 12-14io1
1700	1600	VVZ 12-16io1



Symbol	Test Conditions	Maximum Ratings
I_{dAV} I_{dAVM} I_{FRMS}, I_{TRMS}	$T_K = 100^\circ\text{C}$; module module per leg	15 A 20 A 12 A
I_{FSM}, I_{TSM}	$T_{VJ} = 45^\circ\text{C}$; $V_R = 0$ $T_{VJ} = T_{VJM}$ $V_R = 0$	$t = 10 \text{ ms}$ (50 Hz), sine $t = 8.3 \text{ ms}$ (60 Hz), sine 110 A 115 A $t = 10 \text{ ms}$ (50 Hz), sine $t = 8.3 \text{ ms}$ (60 Hz), sine 100 A 105 A
I^2t	$T_{VJ} = 45^\circ\text{C}$ $V_R = 0$ $T_{VJ} = T_{VJM}$ $V_R = 0$	$t = 10 \text{ ms}$ (50 Hz), sine $t = 8.3 \text{ ms}$ (60 Hz), sine 60 A ² s 55 A ² s $t = 10 \text{ ms}$ (50 Hz), sine $t = 8.3 \text{ ms}$ (60 Hz), sine 50 A ² s 45 A ² s
$(di/dt)_{cr}$	$T_{VJ} = T_{VJM}$ $f = 400 \text{ Hz}$, $t_p = 200 \mu\text{s}$ $V_D = 2/3 V_{DRM}$ $I_G = 0.3 \text{ A}$, $di_G/dt = 0.3 \text{ A}/\mu\text{s}$	repetitive, $I_T = 50 \text{ A}$ 150 A/ μs non repetitive, $I_T = 1/3 \sim I_{dAV}$ 500 A/ μs
$(dv/dt)_{cr}$	$T_{VJ} = T_{VJM}$; $V_{DR} = 2/3 V_{DRM}$ $R_{GK} = \infty$; method 1 (linear voltage rise)	1000 V/ μs
V_{RGM}		10 V
P_{GM}	$T_{VJ} = T_{VJM}$ $I_T = I_{TAVM}$	$t_p = 30 \mu\text{s}$ $\leq 10 \text{ W}$ $t_p = 500 \mu\text{s}$ $\leq 5 \text{ W}$ $t_p = 10 \text{ ms}$ $\leq 1 \text{ W}$ 0.5 W
P_{GAVM}		0.5 W
T_{VJ}		-40...+125 °C
T_{VJM}		125 °C
T_{stg}		-40...+125 °C
V_{ISOL}	50/60 Hz, RMS $I_{ISOL} \leq 1 \text{ mA}$	$t = 1 \text{ min}$ 3000 V~ $t = 1 \text{ s}$ 3600 V~
M_d	Mounting torque (M5) (10-32 UNF)	2-2.5 Nm 18-22 lb.in.
Weight	typ.	28 g

Features

- Package with DCB ceramic base plate
- Isolation voltage 3600 V~
- Planar passivated chips
- Soldering terminals
- UL registered E 72873

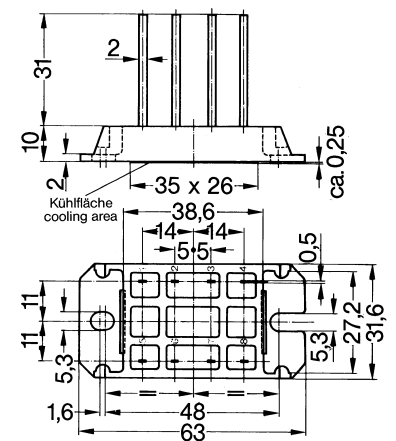
Applications

- Input rectifier for switch mode power supplies (SMPS)
- Softstart capacitor charging
- Electric drives and auxiliaries

Advantages

- Easy to mount with two screws
- Space and weight savings
- Improved temperature and power cycling

Dimensions in mm (1 mm = 0.0394")



Symbol	Test Conditions	Characteristic Values
I_R, I_D	$V_R = V_{RRM}; V_D = V_{DRM}$ $T_{VJ} = T_{VJM}$ $T_{VJ} = 25^\circ\text{C}$	$\leq 5 \text{ mA}$ $\leq 0.3 \text{ mA}$
V_F, V_T	$I_F, I_T = 30 \text{ A}, T_{VJ} = 25^\circ\text{C}$	$\leq 2 \text{ V}$
V_{T0}	For power-loss calculations only	1.1 V
r_T	$(T_{VJ} = 125^\circ\text{C})$	30 mΩ
V_{GT}	$V_D = 6 \text{ V};$ $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = -40^\circ\text{C}$	$\leq 1.0 \text{ V}$ $\leq 1.2 \text{ V}$
I_{GT}	$V_D = 6 \text{ V};$ $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = -40^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$	$\leq 65 \text{ mA}$ $\leq 80 \text{ mA}$ $\leq 50 \text{ mA}$
V_{GD}	$T_{VJ} = T_{VJM};$ $T_{VJ} = T_{VJM};$	$V_D = 2/3 V_{DRM}$ $V_D = 2/3 V_{DRM}$
I_{GD}	$T_{VJ} = T_{VJM};$ $T_{VJ} = T_{VJM};$	$\leq 0.2 \text{ V}$ $\leq 5 \text{ mA}$
I_L	$I_G = 0.3 \text{ A}; t_G = 30 \mu\text{s}$ $di_G/dt = 0.3 \text{ A}/\mu\text{s}$ $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = -40^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$	$\leq 150 \text{ mA}$ $\leq 200 \text{ mA}$ $\leq 100 \text{ mA}$
I_H	$T_{VJ} = 25^\circ\text{C}; V_D = 6 \text{ V}; R_{GK} = \infty$	$\leq 100 \text{ mA}$
t_{gd}	$T_{VJ} = 25^\circ\text{C}; V_D = 1/2 V_{DRM}$ $I_G = 0.3 \text{ A}; di_G/dt = 0.3 \text{ A}/\mu\text{s}$	$\leq 2 \mu\text{s}$
t_q	$T_{VJ} = 125^\circ\text{C}; I_T = 15 \text{ A}, t_p = 300 \mu\text{s}, -di/dt = 10 \text{ A}/\mu\text{s}$	typ. 150 μs
Q_r	$V_R = 100 \text{ V}, dv/dt = 20 \text{ V}/\mu\text{s}, V_D = 2/3 V_{DRM}$	75 μC
R_{thJC}	per thyristor (diode); DC current per module	2.5 K/W 0.42 K/W
R_{thJH}	per thyristor (diode); DC current per module	3.1 K/W 0.52 K/W
d_s	Creeping distance on surface	7 mm
d_a	Creepage distance in air	7 mm
a	Max. allowable acceleration	50 m/s ²

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